

Cooperation or Competition: Avoiding Player Domination for Multi-target Robustness by Adaptive Budgets

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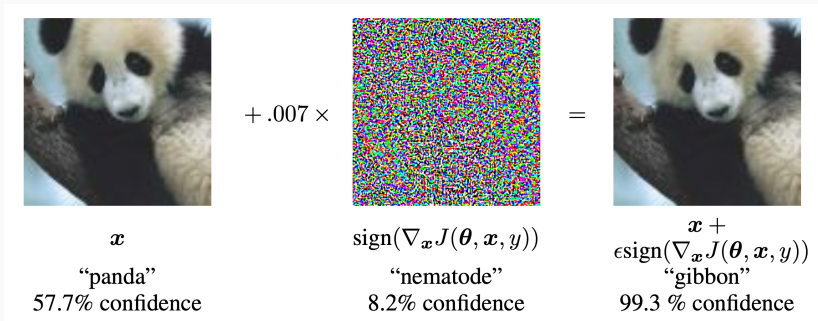
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Background

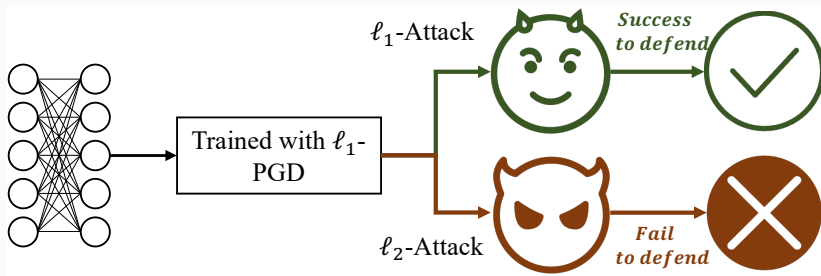
Machine learning models are susceptible to adversarial examples

Figure 1: Example of adversarial examples. Image credit [2].



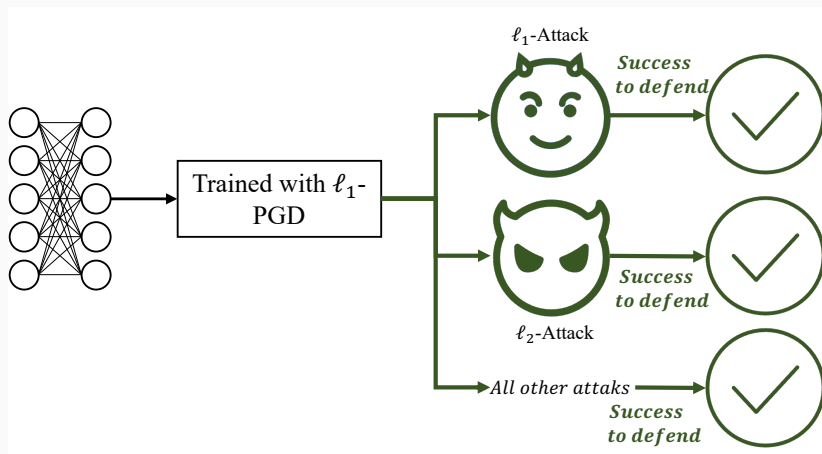
Most of the existing defenses are not universally robust

Figure 2: Most of the existing defenses are not universally robust and fail to defend against other adversaries [3, 4].

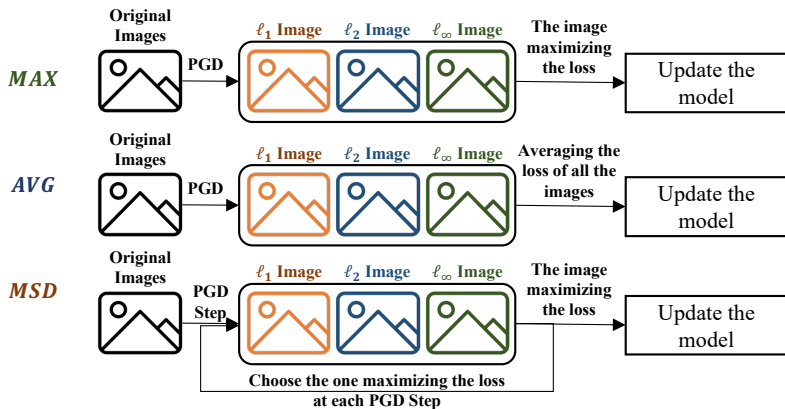


Ultimate goal of robustness

Figure 3: Targeting robustness against multiple adversaries simultaneously [1].



Previous Methods



Our Analysis

Theoretical Analysis on SVM

We first introduce the data distribution and the SVM model.

Data Distribution

Data \mathbf{x} and label y are sampled as

$$y \stackrel{\text{u.a.r.}}{\sim} \{+1, -1\}, \quad x_1 = \begin{cases} +y, & \text{w.p. } p; \\ -y, & \text{w.p. } 1 - p, \end{cases} \quad x_2, \dots, x_{d+1} \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(\mu y, 1).$$

SVM Model

We train a linear SVM model $f_{\mathbf{w}}(\cdot)$ with soft-SVM loss on the data sampled as above:

$$\begin{aligned} \min_{\mathbf{w}} \mathbb{E}_{(\mathbf{x}, y) \sim \mathcal{D}} \sum_{p \in \{1, 2, \infty\}} \gamma_p \max(0, 1 - y f_{\mathbf{w}}(\mathbf{x} + \delta(\mathbf{x})_p)), \\ \text{s.t. } \|\mathbf{w}\|_2 = 1, \end{aligned}$$

where $f_{\mathbf{w}}(\mathbf{x}) = \mathbf{w}^\top \mathbf{x}$, $\delta_p(\mathbf{x})$ is the p -adversarial example for \mathbf{x} , and $\gamma = [\gamma_1, \gamma_2, \gamma_\infty]$ satisfies $\sum_{i \in \{1, 2, \infty\}} \gamma_i = 1$.

Theoretical Analysis on SVM

We first found that under the following case, there will be player domination.

Definition (Player dominates the cooperative game)

If $\exists i \in [k]$ such that $\gamma_i^t = 1$ and $\gamma_j^t = 0, \forall j \in [K]/\{i\}, \forall t$, then we call that player dominates the bargaining game.

ℓ_{infty} domination, Informal

Let $\mu \geq 4/\sqrt{d}$, $\epsilon_\infty \geq 2\mu$, $p \leq 0.977$, $\epsilon_\infty \geq \frac{2}{d}\epsilon_1$ and $\epsilon_\infty \geq \sqrt{\frac{2}{d}}\epsilon_2$. With MAX and MSD, ∞ -player (∞ -adversary) dominates the training procedure as shown below.



Theoretical Analysis on SVM

After analyzing the training dynamics of SVM, we notice that when the ∞ -player dominates the bargaining game, and given $\epsilon_\infty > \mu$, the SVM model may not converge.

Theorem [Player domination makes the training procedure not converge, Informal]

With MAX and MSD, if ∞ -player dominates and $\epsilon_\infty > \mu$, the **weights for the non-robust features flips over time**, i.e.,
$$\text{sign}(\mathbf{w}_i^t) = -\text{sign}(\mathbf{w}_i^{t-1}), \forall i \geq 2.$$

Theoretical Analysis on Linear Model

Assuming the loss function of each player is denoted as $\ell_k, k \in [K]$, which is L -smooth and μ -strongly convex, we have the following theorems.

Theorem [MAX and MSD might not converge, Informal]

If the training is dominated by one player during the whole game, then the loss of all players and the overall loss would **increase** as time t grows.

Theorem [AVG's loss decreases, Informal]

Using AVG to train the linear model, the overall loss **decreases** as time t grows.

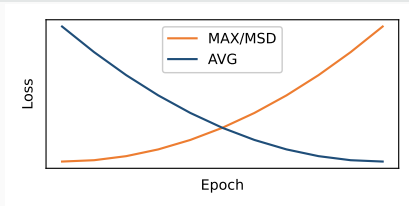


Figure 4: An example under the linear case.

Our Method

AdaptiveBudget

AdaptiveBudget is designed to **avoid the phenomenon of the same player dominating the whole training procedure** as this phenomenon leads to non-convergence under SVM and Linear cases.

Algorithm 1 Framework of Multi-target Adversarial Training with Adaptive Budget

Require: Training Epochs E , Training samples $(\mathcal{X}, \mathcal{Y})$, adversarial budgets $(\epsilon_\infty, \epsilon_1, \epsilon_2)$, model $f(\cdot)$, loss function ℓ .

```
1: for  $e \in [E]$  do
2:   for  $\mathbf{x}, y \in (\mathcal{X}, \mathcal{Y})$  do
3:      $\mathbf{g}_p \leftarrow \ell'(\mathbf{x} + \delta_p(\mathbf{x}))$ ,  $\delta_p(\mathbf{x}) \leftarrow \text{PGD}(\mathbf{x}, k, \eta, \ell, \epsilon_p, \ell), \forall p \in \{1, 2, \infty\}$ 
4:     Get adaptive budgets  $\hat{\epsilon}_1, \hat{\epsilon}_2, \hat{\epsilon}_\infty \leftarrow \text{AdaptiveBudget}([\mathbf{g}_1, \mathbf{g}_2, \mathbf{g}_\infty], [\epsilon_1, \epsilon_2, \epsilon_\infty]);$ 
5:     Adversarial training using MAX, MSD or AVG with budgets  $(\hat{\epsilon}_1, \hat{\epsilon}_2, \hat{\epsilon}_\infty)$ ;
6:   end for
7: end for
8: Return the classifier  $f$ .
9:
10: AdaptiveBudget(Gradients $[\mathbf{g}_1, \mathbf{g}_2, \mathbf{g}_\infty]$ , Epsilon $[\epsilon_1, \epsilon_2, \epsilon_\infty]$ ):
11:    $\rho_{\max} \leftarrow \text{argmax}_{p \in \{\infty, 1, 2\}} \|\mathbf{g}_p\|$ ,  $\rho_{\min} \leftarrow \text{argmin}_{p \in \{\infty, 1, 2\}} \|\mathbf{g}_p\|$ ;
12:    $\rho_{\text{mid}} \leftarrow \{1, 2, \infty\} / \{\rho_{\max}, \rho_{\min}\}$ ;
13:    $\epsilon_{\rho_{\max}} \leftarrow \epsilon_{\rho_{\max}} \cdot \frac{\|\mathbf{g}_{\rho_{\max}}\|}{\|\mathbf{g}_{\rho_{\text{mid}}}\|}$ ,  $\epsilon_{\rho_{\min}} \leftarrow \epsilon_{\rho_{\min}} \cdot \frac{\|\mathbf{g}_{\rho_{\min}}\|}{\|\mathbf{g}_{\rho_{\text{mid}}}\|}$ ;
14:   Return  $\epsilon_1, \epsilon_2, \epsilon_\infty$ .
```

Experimental Results

Experimental Results on MNIST

Models w. adaptive budget	ℓ_1	ℓ_2	ℓ_∞	MAX		MSD		AVG				
				ℓ_1 (ours)	ℓ_2 (ours)	ℓ_1 (ours)	ℓ_2 (ours)	ℓ_1 (ours)	ℓ_2 (ours)			
Clean Accuracy (%)	97.2	99.1	99.2	98.6	98.9	98.9	98.2	98.3	98.9	99.1	99.1	99.1
ℓ_1 PGD Robust Acc (%)	47.3*	67.8*	54.6*	67.1*	71.4 ↑	69.7 ↑	67.3*	66.8↓	65.9↓	70.6*	68.2↓	68.9↓
ℓ_2 PGD Robust Acc (%)	24.1*	66.8*	61.8*	67.2*	69.4 ↑	69.5 ↑	68.0*	67.9↓	65.3↓	69.4*	68.3↓	68.3↓
ℓ_∞ PGD Robust Acc (%)	0*	0.1*	88.9*	21.2*	67.2 ↑	67.6 ↑	62.4*	69.7 ↑	69.7 ↑	59.5*	67.7 ↑	65.6 ↑
All PGD Robust Acc (%)	0*	0.1*	52.1*	21.2*	61.3 ↑	61.4 ↑	59.7*	62.1 ↑	61.0 ↑	55.4*	59.2 ↑	58.2 ↑

Experimental Results on CIFAR-10

Models w. adaptive budget	ℓ_1	ℓ_2	ℓ_∞	MAX			MSD			AVG		
				ℓ_1 (ours)	ℓ_2 (ours)		ℓ_1 (ours)	ℓ_2 (ours)		ℓ_1 (ours)	ℓ_2 (ours)	
Clean Accuracy	92.4	87.5	84.2	79.6	76.9	78.7	79.2	77.6	79.0	83.8	81.6	81.5
ℓ_1 PGD Robust Acc (%)	90.8	31.7	17.3	44.0*	50.7 ↑	51.7 ↑	50.8*	51.2 ↑	52.6 ↑	55.7*	57.3 ↑	56.3 ↑
ℓ_2 PGD Robust Acc (%)	0.1	64.0	60.6	55.6*	63.4 ↑	65.1 ↑	64.3*	63.6↓	65.5 ↑	67.0*	66.6↓	67.0
ℓ_∞ PGD Robust Acc (%)	0	27.8	51.2	41.3*	47.5 ↑	47.6 ↑	45.7*	48.4 ↑	47.2 ↑	39.4*	45.5 ↑	44.2 ↑
All PGD Robust Acc (%)	0	23.8	17.3	40.4*	46.0 ↑	46.8 ↑	44.1*	47.2 ↑	46.4 ↑	39.2*	45.2 ↑	43.6 ↑
ℓ_1 AA Robust Acc (%)	0	23.8	6.2	41.4*	45.7 ↑	45.5 ↑	45.5*	46.4 ↑	46.7 ↑	49.7*	52.7 ↑	50.8 ↑
ℓ_2 AA Robust Acc (%)	0	63.0	57.4	53.7*	60.4 ↑	63.2 ↑	61.9*	62.3 ↑	62.1 ↑	65.4*	64.6↓	65.5 ↑
ℓ_∞ AA Robust Acc (%)	0	26.1	48.0	38.4*	44.7 ↑	44.1 ↑	43.1*	45.2 ↑	44.4 ↑	37.0*	43.1 ↑	42.1 ↑
All AA Robust Acc (%)	0	19.5	6.2	37.6*	42.9 ↑	42.3 ↑	41.6*	43.4 ↑	43.0 ↑	36.6*	42.5 ↑	41.2 ↑

Experimental Results on CIFAR-100

Models w. AdaptiveBudget	MAX			MSD			AVG		
	ℓ_1 (ours)	ℓ_2 (ours)		ℓ_1 (ours)	ℓ_2 (ours)		ℓ_1 (ours)	ℓ_2 (ours)	
Clean Accuracy	55.49*	56.48	55.53	56.09*	55.52	54.94	59.94*	57.78	58.16
ℓ_1 PGD Robust Acc (%)	25.45*	29.27 ↑	29.78 ↑	35.50*	30.31↓	28.87↓	30.35*	33.16 ↑	32.62 ↑
ℓ_2 PGD Robust Acc (%)	39.55*	40.00 ↑	39.85 ↑	40.14*	40.28 ↑	39.28↓	40.26*	41.03 ↑	40.27 ↑
ℓ_∞ PGD Robust Acc (%)	25.03*	25.34 ↑	25.87 ↑	24.83*	26.19 ↑	25.59 ↑	18.92*	21.81 ↑	21.57 ↑
All PGD Robust Acc (%)	21.11*	24.14 ↑	24.76 ↑	25.10*	25.03↓	24.43↓	18.61*	21.55 ↑	21.16 ↑
ℓ_1 AA Robust Acc (%)	13.00*	23.00 ↑	20.90 ↑	25.10*	24.00↓	24.20↓	25.20*	28.60 ↑	28.00 ↑
ℓ_2 AA Robust Acc (%)	36.30*	35.60↓	36.40 ↑	37.60*	35.80↓	36.40↓	37.00*	37.90 ↑	37.10 ↑
ℓ_∞ AA Robust Acc (%)	22.00*	21.50↓	22.30 ↑	21.80*	22.80 ↑	22.70 ↑	16.30*	19.00 ↑	19.70 ↑
All AA Robust Acc (%)	12.20*	20.60 ↑	18.60 ↑	21.00*	21.30 ↑	21.50 ↑	16.10*	18.90 ↑	19.50 ↑

Conclusion

- We show the first theoretical results on the convergence of MAX, MSD, and AVG on the multi-target robustness.

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Summary

- We show the first theoretical results on the convergence of MAX, MSD, and AVG on the multi-target robustness.
- We design a novel algorithm namely AdaptiveBudget which is able to alleviate the player domination phenomenon and thus might avoid the non-convergence of MAX and MSD under SVM and Linear cases.
- Experimental results show that AdaptiveBudget improves the performance of MSD, MAX, and AVG.

Thanks for listening!



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