

# Principles of Forgetting in Domain-Incremental Semantic Segmentation in Adverse Weather Conditions

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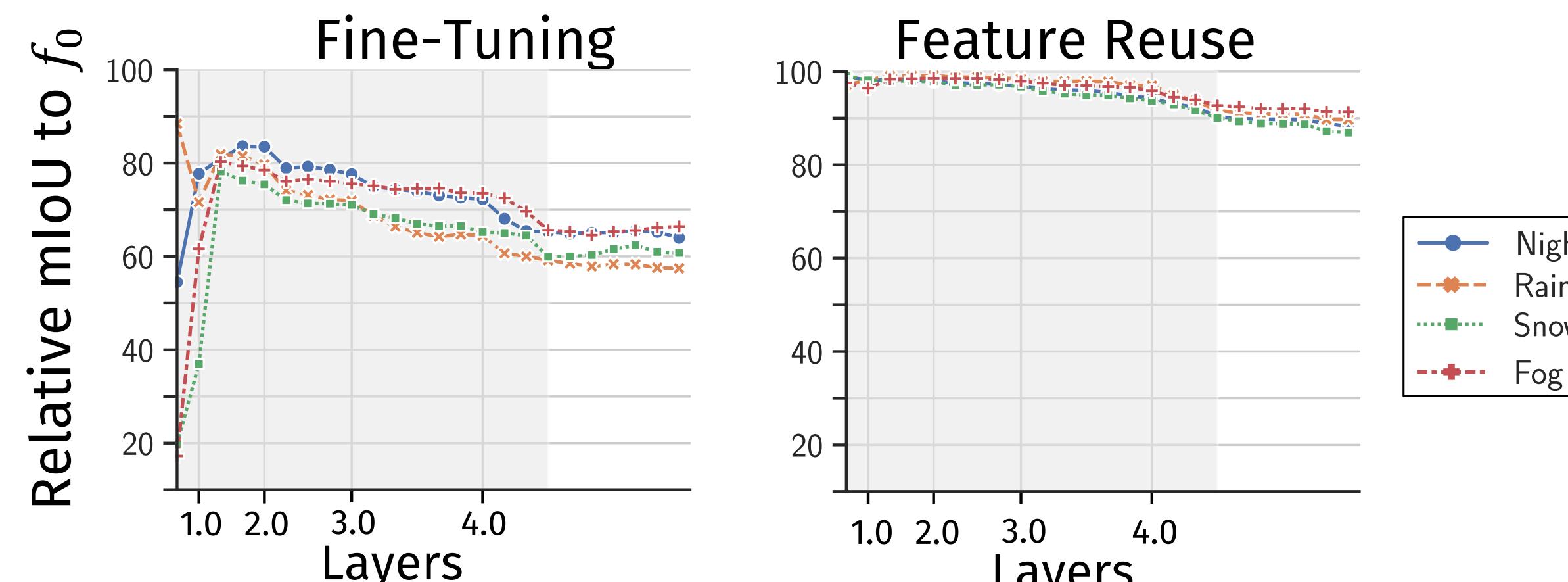
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## Overview

**Severe activation drift in early layers** in domain-incremental learning due to:

1. Biased population statistics in BatchNorm Layers
2. Specialized domain-specific features in early layers

Increasing **feature reuse** by learning generalized features drastically decreases activation shift and thereby catastrophic forgetting.



## Activation Drift after Incremental Learning

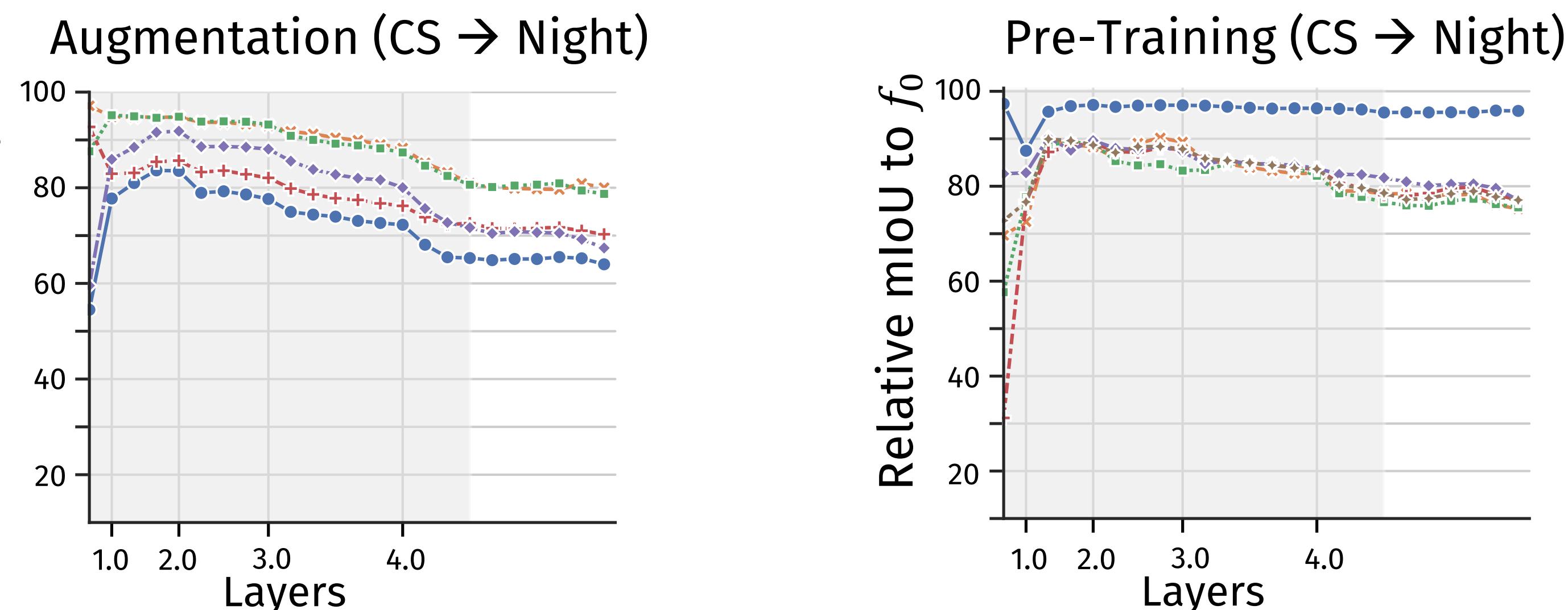
Severe activation drift and forgetting specifically for seemingly similar tasks, especially Cityscapes → Rain, why?

Task 2	Cityscapes		Task 2	
	Cityscapes	Task 2	Cityscapes	Task 2
Rain	30.4	38.8	57.7	33.2
Night	10.5	45.9	43.6	26.1
Snow	23.1	42.2	62.3	29.8
Fog	33.4	44.0	69.0	28.0

Results in mIoU (%)



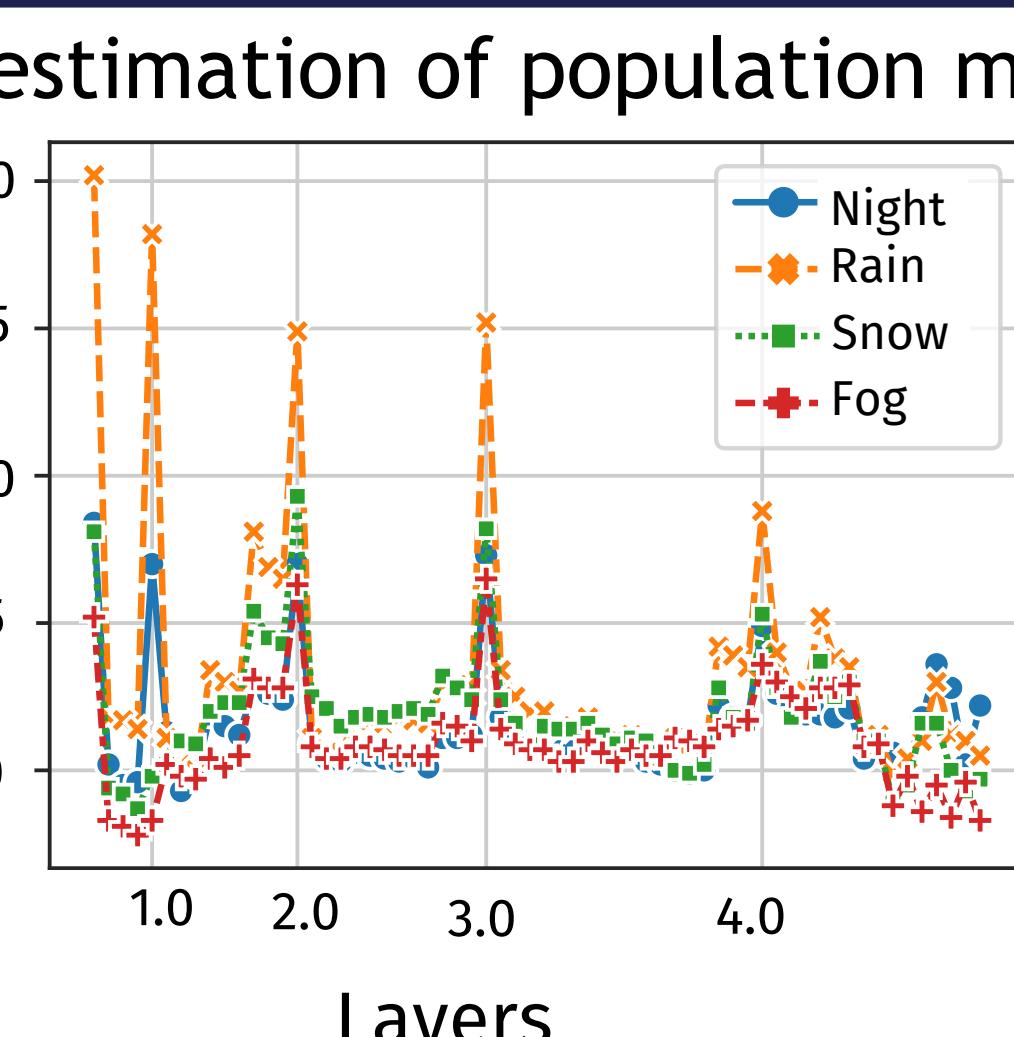
## Low-Level Feature Reuse



Method	Cityscapes		Task 2	
	Test mIoU	avg. zero-shot	avg. Test	avg. Forgetting
FT	72.0	24.4	58.2	30.1
AutoAlb.	72.2	38.6	59.7	12.8
Distort	71.7	34.5	59.5	17.4
ImageNet	73.9	20.3	60.9	23.6
DINO	75.0	25.6	63.4	22.2
BarlowT.	73.9	30.6	62.5	19.0
SwAV	-	28.9	62.2	25.7
Offline	-	58.8	59.1	2.6

Results in mIoU (%)

## Impact of Batch Normalization

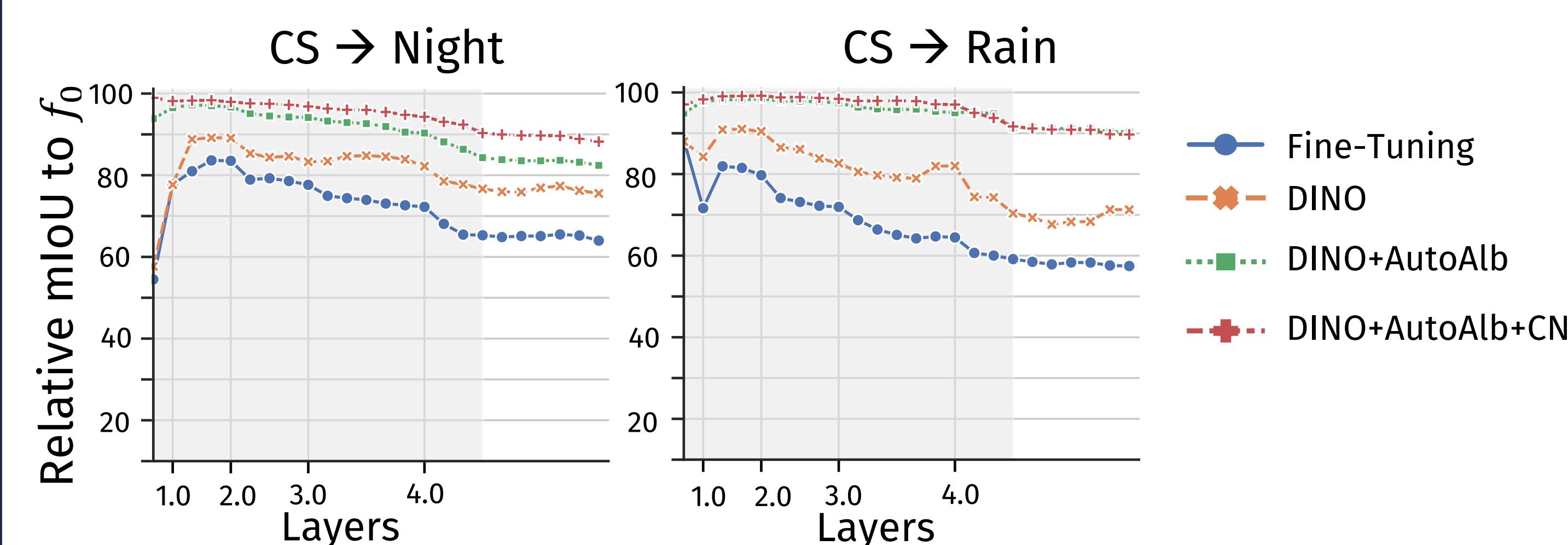


- BN population statistics are biased → leads to severe forgetting
- Pre-Trained are more affected

## Comparison to Continual Learning

Method	Night		Rain	
	lrn. acc.	avg. forg.	lrn. acc.	avg. forg.
EWC	52.8	18.0	61.4	21.2
+ DINO	58.1	10.0	66.0	11.3
+ AutoAlb + CN	58.5	4.8	69.1	4.9
Replay	58.2	5.6	64.2	2.9
+ DINO	62.4	4.2	70.8	2.1
+ AutoAlb + CN	61.8	4.1	69.9	3.8
Ours	62.1	7.9	71.0	8.0

## Combining the Findings



- DINO alone increases feature reuse only after layer 1.0
- Initially discrepancy

## Take-Aways

- Feature-Reuse drastically reduces catastrophic forgetting
- Pre-Training stabilizes intermediate representations
- Low-Level Representations can be stabilized with augmentation

Initialization of your model greatly affects catastrophic forgetting!