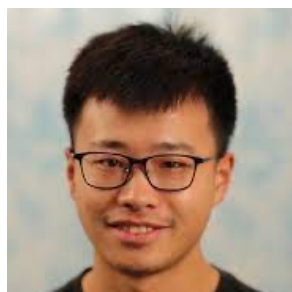


Poster Tag  
THU-PM-309



# Contrastive Mean Teacher for Domain Adaptive Object Detectors



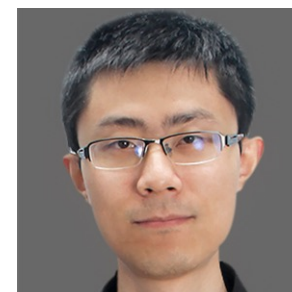
Shengcao Cao<sup>1</sup>



Dhiraj Joshi<sup>2</sup>



Liang-Yan Gui<sup>1</sup>



Yu-Xiong Wang<sup>1</sup>

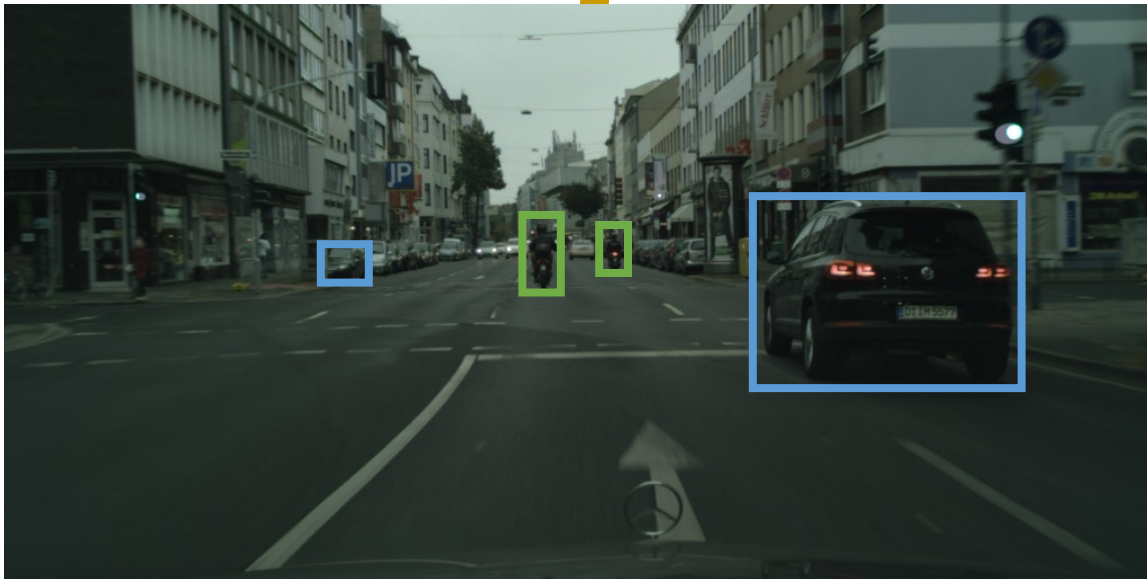
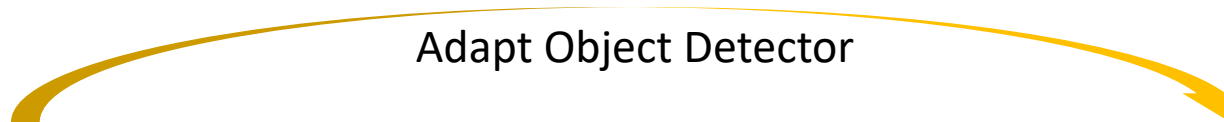
<sup>1</sup>University of Illinois at Urbana-Champaign

<sup>2</sup>IBM Research



# Overview

- Problem: **Unsupervised domain adaptation for object detection**



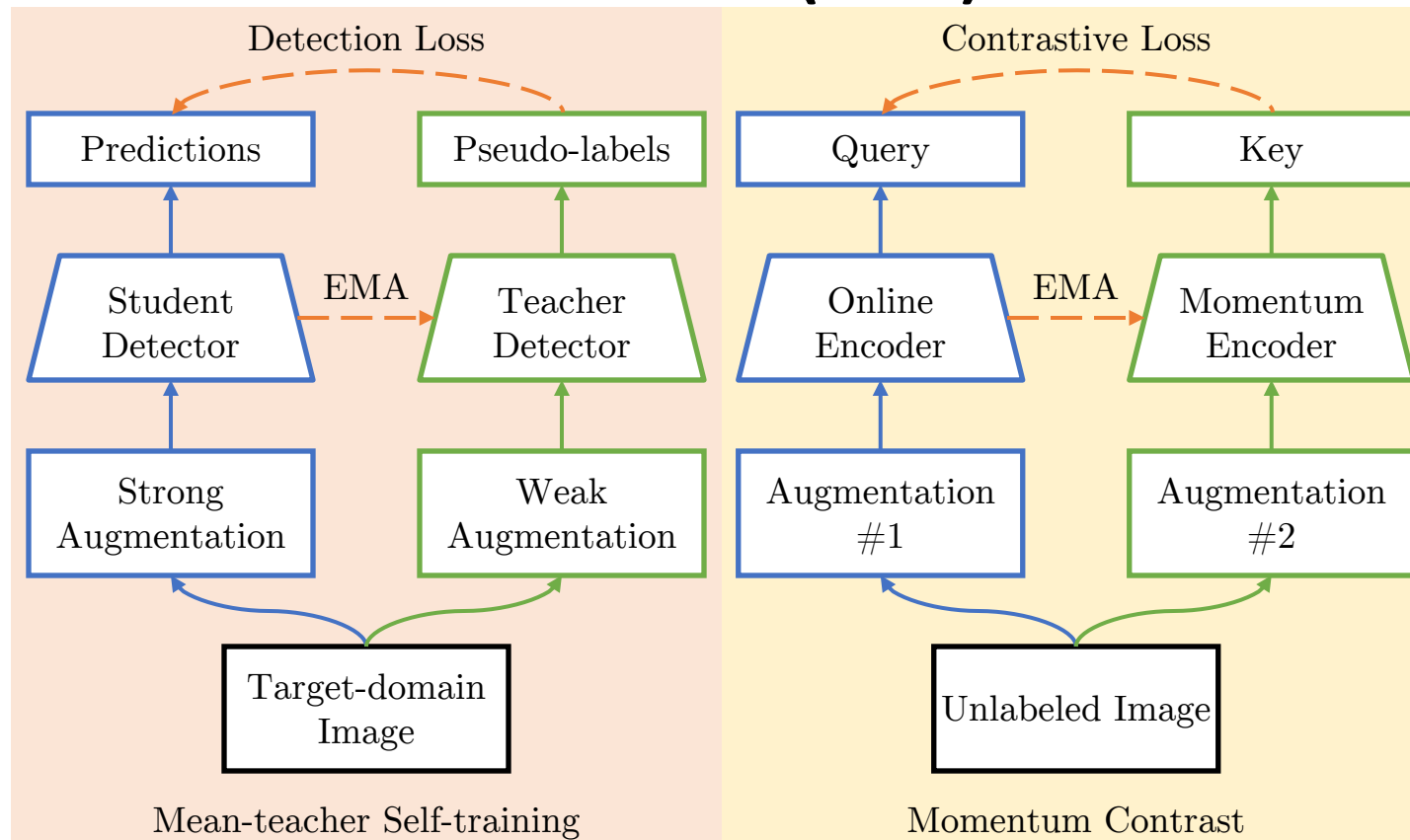
Labeled Source Domain



Unlabeled Target Domain

# Overview

- Problem: Unsupervised domain adaptation for object detection
- Solution: **Contrastive Mean Teacher (CMT)**



Why do we need unsupervised domain adaptation for object detectors?

Why do we need **unsupervised** domain adaptation for object detectors?

**Challenge 1:** Object-level labels are expensive or even unavailable

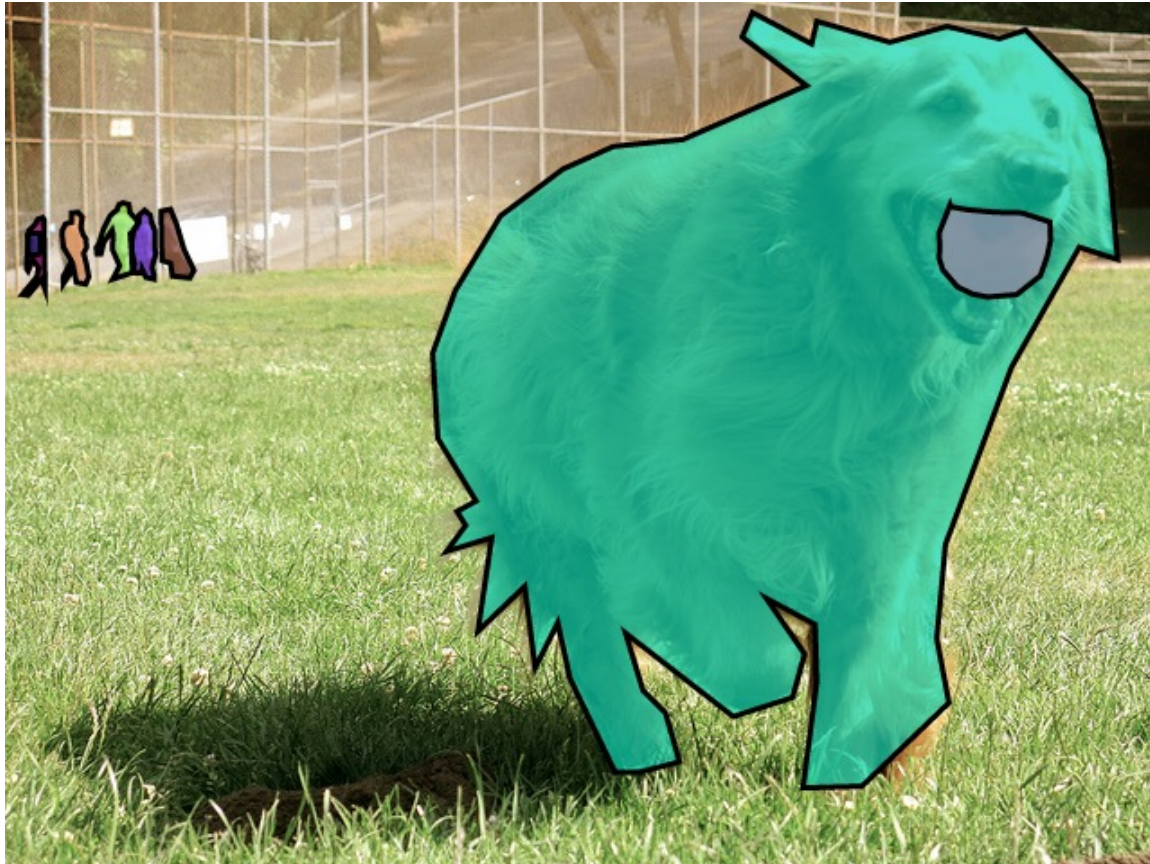


**Image-level** annotation

"Dog"

Why do we need **unsupervised** domain adaptation for object detectors?

**Challenge 1:** Object-level labels are expensive or even unavailable



### Object-level annotation

- Category of each object
  - Bounding box
  - Pixel-level mask

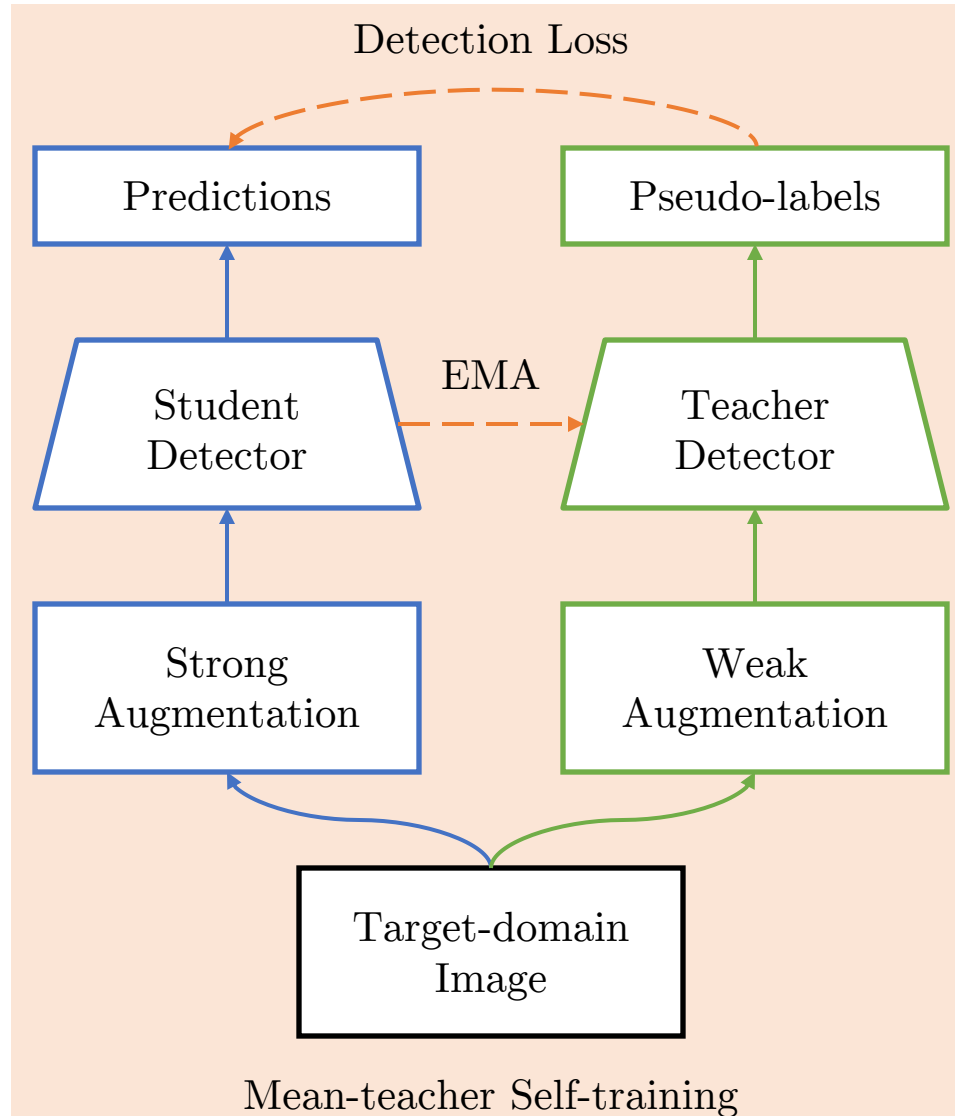
Why do we need unsupervised **domain adaptation** for object detectors?

**Challenge 2:** Real-world applications may face a huge domain gap or different data distribution

Example: Weather change



# Recent Paradigm: Mean-teacher Self-training

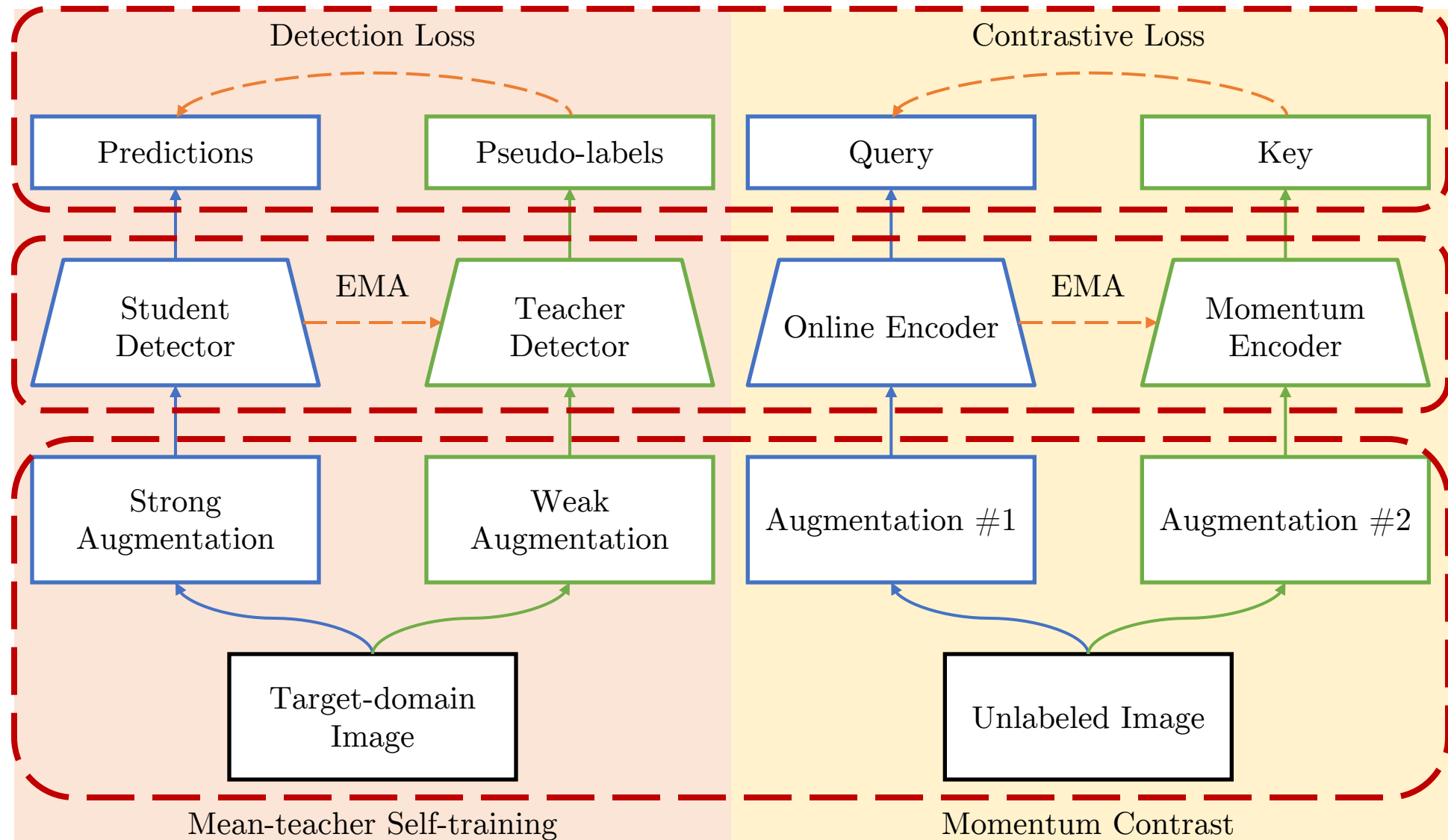


Leads to state-of-the-art domain adaptive object detectors

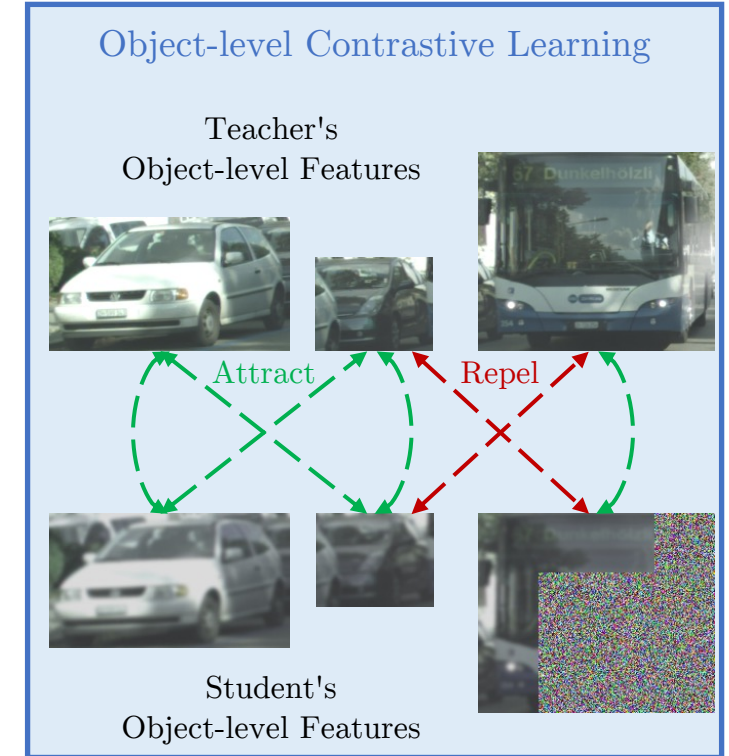
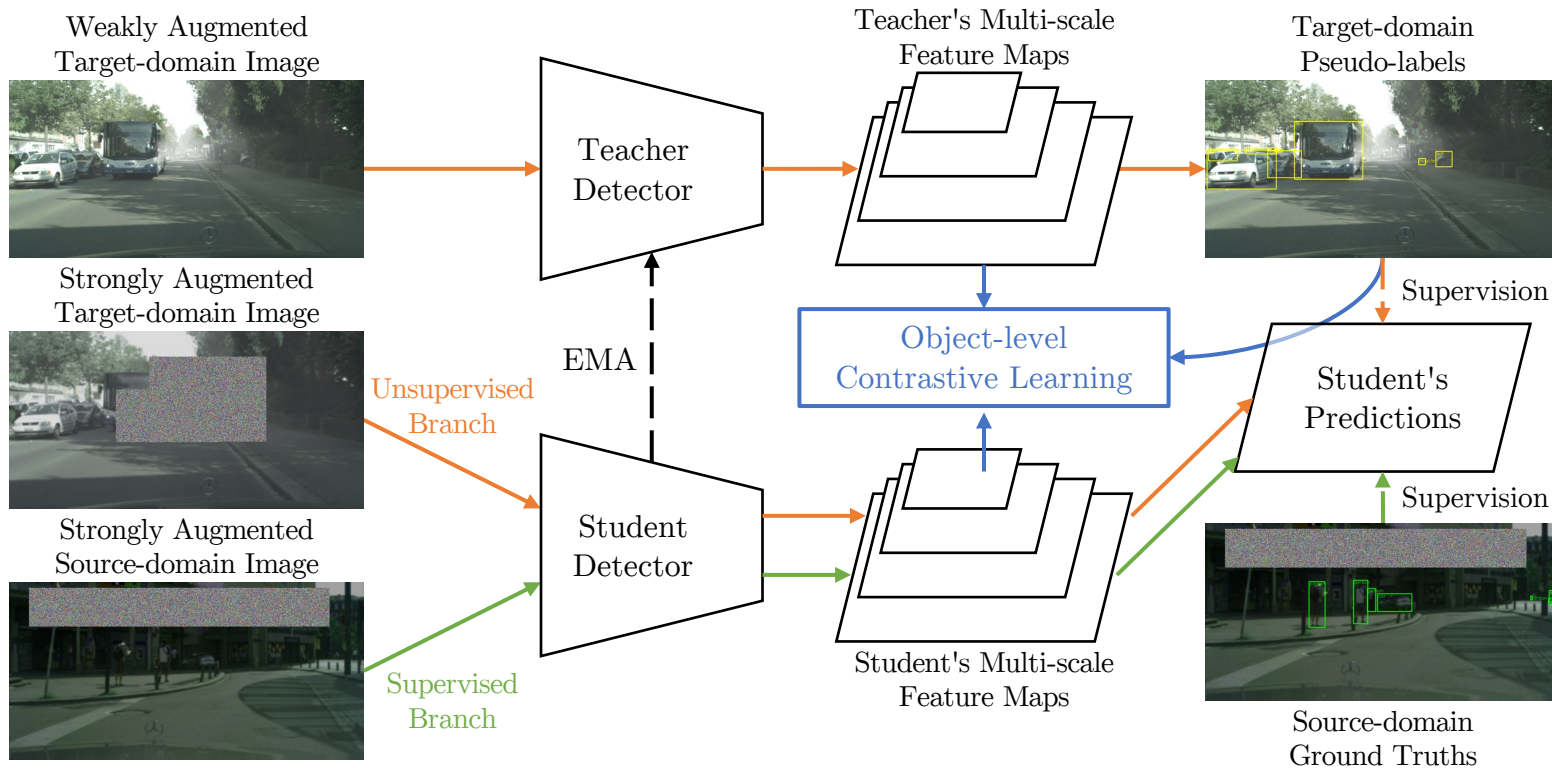
- Adaptive Teacher (*CVPR'22*)
- Probabilistic Teacher (*ICML'22*)



# Aligning Mean Teacher and Momentum Contrast



# Contrastive Mean Teacher (CMT)

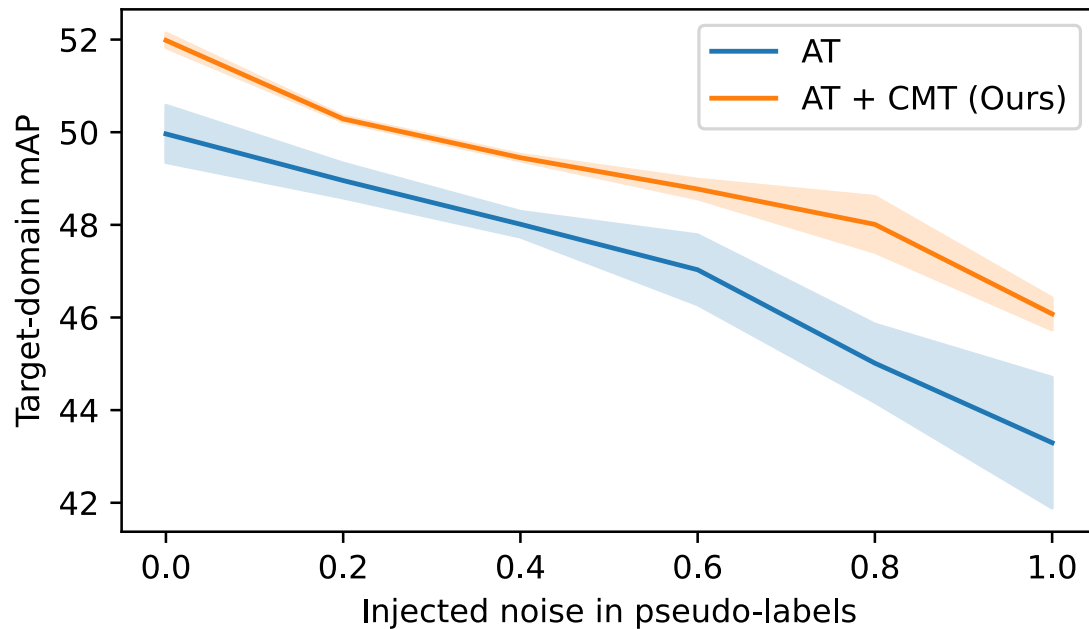


# New State of the Art on Cityscapes → Foggy Cityscapes

Method	person	rider	car	truck	bus	train	motor	bike	mAP
Source	27.9	33.4	40.4	12.1	23.2	10.1	20.7	30.9	24.8
Oracle	41.2	49.1	61.6	32.6	56.6	49.0	37.9	42.4	46.3
PDA ( <i>WACV'20</i> )	36.0	45.5	54.4	24.3	44.1	25.8	29.1	35.9	36.9
ICR-CCR ( <i>CVPR'20</i> )	32.9	43.8	49.2	27.2	36.4	36.4	30.3	34.6	37.4
PT ( <i>ICML'22</i> )	43.2	52.4	63.4	33.4	56.6	37.8	41.3	48.7	47.1
PT ( <i>ICML'22</i> ) + CMT (Ours)	45.6	55.1	66.5	34.0	59.4	42.4	43.9	47.4	49.3 (+2.2)
AT ( <i>CVPR'22</i> )	46.3	55.9	64.3	38.5	61.1	39.3	40.8	52.3	49.8
AT ( <i>CVPR'22</i> ) + CMT (Ours)	47.0	55.7	64.5	39.4	63.2	51.9	40.3	53.1	<b>51.9 (+2.1)</b>

# Analytical Experiment and Ablation Study

Benefit of CMT is more pronounced when pseudo-labels are noisier



Both our techniques improves object-level contrastive learning

- 1) Building contrastive pairs using predicted classes
- 2) Learning from features of multiple scales

Method	Class-based Contrast	Multi-scale Features	mAP	Gain w.r.t. PT
PT	-	-	47.1	-
PT + CMT (Ours)	✗	✗	47.8	+0.7
	✗	✓	48.2	+1.1
	✓	✗	48.7	+1.6
	✓	✓	<b>49.3</b>	<b>+2.2</b>





# Take-away

Code available here:



- Real-world challenges call for **unsupervised domain adaption** for object detection
- We align **Mean Teacher** and **Momentum Contrast** into one unified framework **Contrastive Mean Teacher (CMT)**
- Our **CMT** achieves new state-of-the-art performance on various benchmarks including Cityscapes → Foggy Cityscapes