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清华大学  
Tsinghua University



# TINC: Tree-structured Implicit Neural Compression

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CVPR



VANCOUVER, CANADA

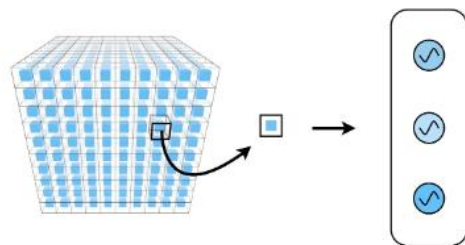
# 1 Introduction



## Implicit Neural Representation, INR, is a promising compressor

- Treat the data as the result of sampling a continuous function.
- Use a neural network to parameterize the function to represent the data.

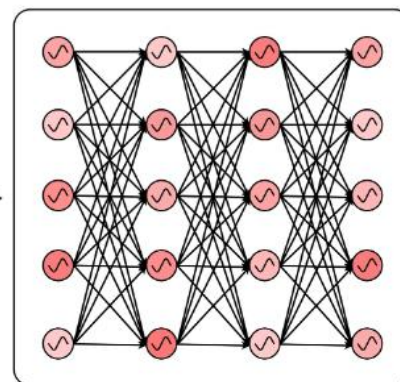
**Input:** Any coordinate in the imaging data coordinate system, i.e. the coordinate of a voxel.



$v$

Coordinate Vector

## Parameterized Neural Networks



$$z^{(0)} = \gamma(W^{(0)}v + b^{(0)})$$

Input Layer

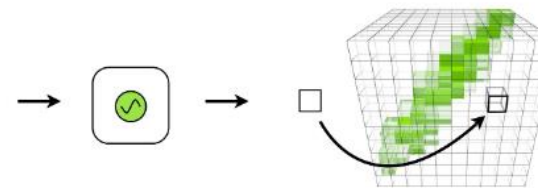
$$z^{(l)} = \rho^{(l)}(W^{(l)}z^{(l-1)} + b^{(l)})$$

Hidden Layers

$$z^{(L+1)} = W^{(L+1)}z^{(L)} + b^{(L+1)}$$

Output Layer

**Output:** The value of the imaging data corresponding to this coordinate, i.e. the intensity value of a voxel.



$f_{\theta}(v)$

Intensity

## characteristics

Traditional discrete grid representation



## Continuous parameterization

- ✓ Not limited by grid resolution
- ✓ Simulation of details in the signal
- ✓ Modeling the higher order derivative information contained in the natural signal

# 1 Introduction

## □ INR is limited confronted with large sized data

- INR is intrinsically of limited spectrum coverage and cannot envelop the spectrum of the target data.
- Two pioneering works using INR for data compression, including **NeRV** and **SCI** have attempted to handle this issue in their respective ways.

### NeRV

- Introduces the convolution operation into INR.
- ✓ Reduces the required number of parameters using the weight sharing mechanism.
- X Convolution is spatially invariant and thus limits NeRV's representation accuracy on complex data with spatial varying feature distribution.

### SCI

- Adopts divide-and-conquer strategy and partitions the data into blocks within INR's concentrated spectrum envelop.
- ✓ Improves the local fidelity.
- X Cannot remove non-local redundancies for higher compression ratio and tend to cause blocking artifacts.

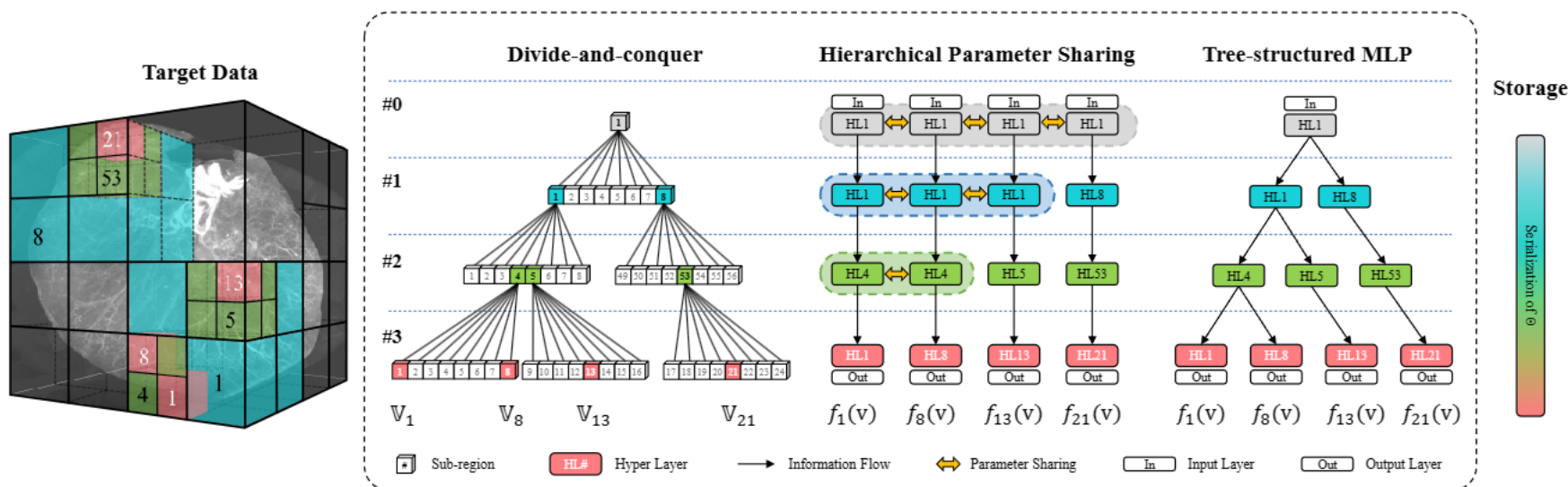


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- We propose to build a tree-structured Multi-Layer Perceptrons (MLPs), which consists of a set of INRs to represent local regions in a compact manner and organizes them under a hierarchical architecture for parameter sharing and higher compression ratio.



# 1 Introduction



## □ TINC outperforms the SOTAs under high compression ratios

- Using the massive and diverse biomedical data, we conduct extensive experiments to validate that TINC greatly improves the capability of INR and even outperforms the commercial compression tools (H.264 and HEVC) under high compression ratios.

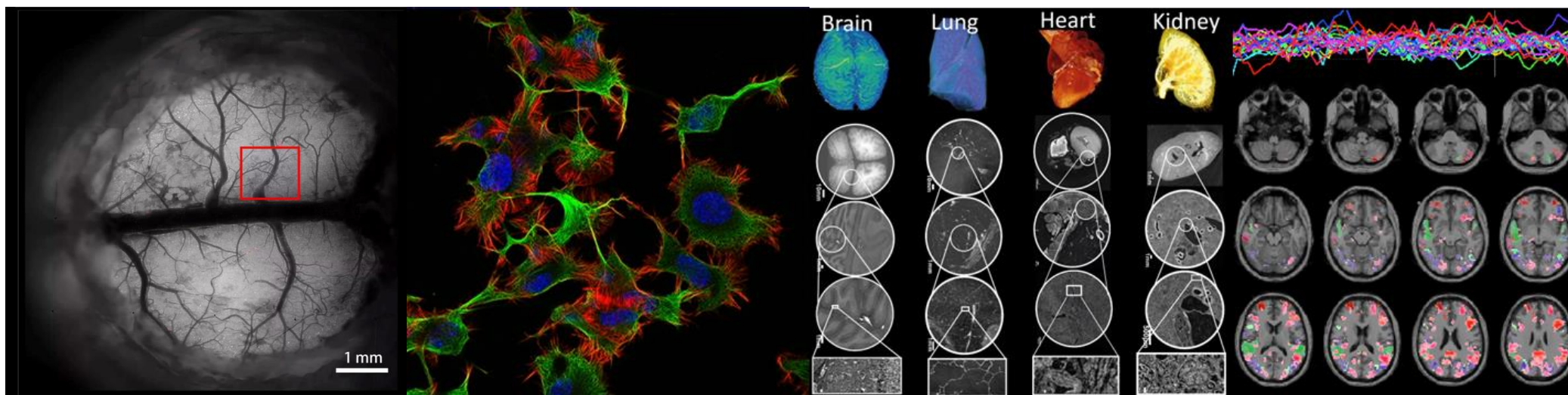
Method	Medical data				Biological data			
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# 1 Introduction



## □ Biomedical Imaging

- Visualization of organisms at different scales of cells, tissues and organs using various imaging techniques.



# 1 Introduction



## □ Biomedical imaging data characteristics, needs and challenges of compression

### characteristics

- **High sampling rate:** for capturing minute structural details, providing higher spatial resolution.
- **High imaging speed:** for capturing rapid dynamic changes, providing higher temporal resolution.
- **High dimensionality:** for representing information including spatial location, time series, etc.
- **Large volume:** terabytes or even petabytes of data.

### needs

- **Storage:** reduce storage costs, and avoid experimental data loss
- **Transmission:** reduce transmission costs, promote experimental data sharing.
- **Analysis:** reduce I/O pressure, reduce storage space during analysis, improve analysis efficiency, and accelerate scientific discovery.

### challenges of compressors

How to design high compression rate biomedical imaging data compressor, for efficient storage, transmission and analysis of biomedical data?



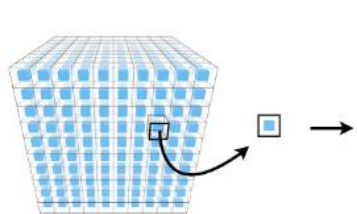
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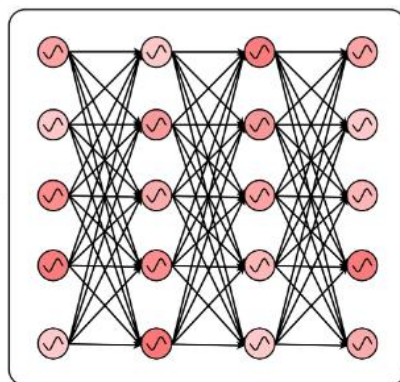
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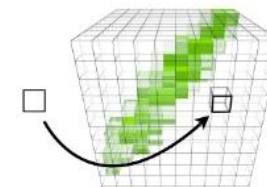
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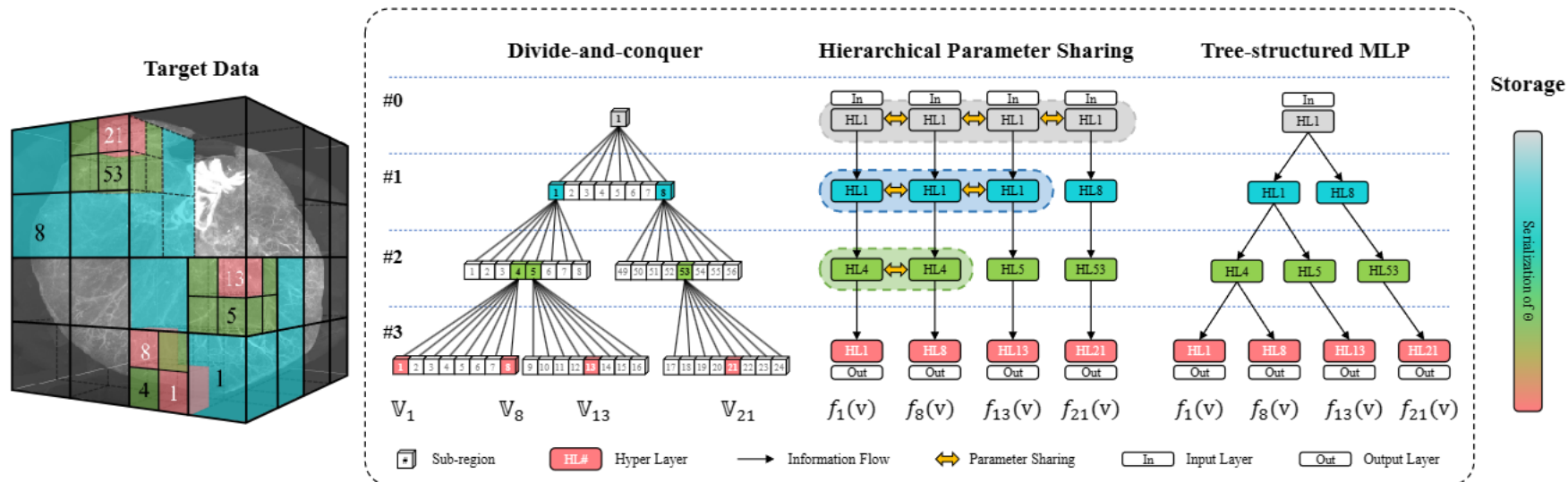
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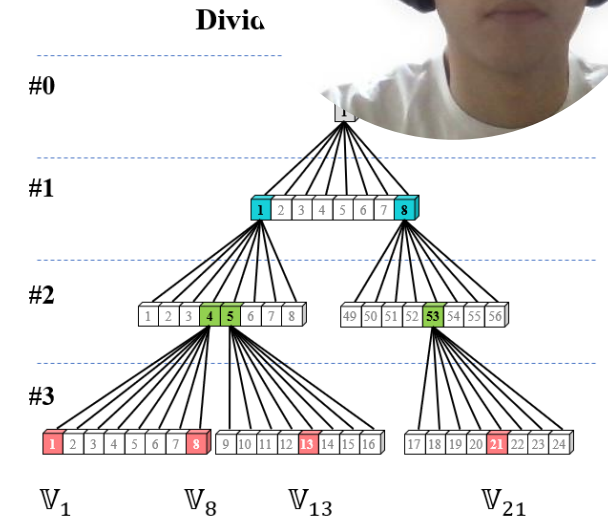
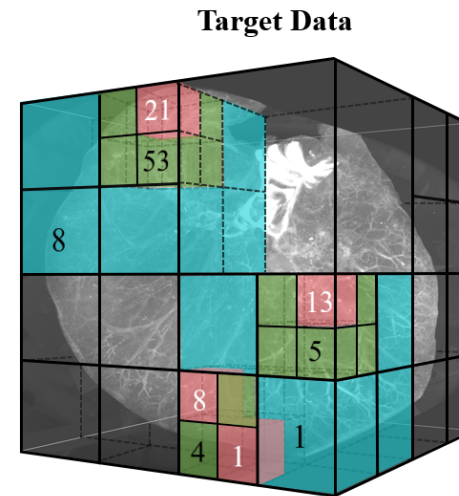


# 2 Method



## Ensemble of Implicit Neural Compressors

- We borrow the idea of ensemble learning to partition the target volume into blocks and use multiple less expressive  $f_k(\cdot, \Theta_k)$  to achieve a powerful representation.
- We adopt the divide-and-conquer strategy to ensemble all implicit functions that represents data at its corresponding coordinate region.



$$\begin{array}{l}
 f(\mathbf{v}; \Theta) \\
 \downarrow \\
 f_k(\cdot, \Theta_k) \\
 \{f_k, k = 1, \dots, K\}
 \end{array}
 \xrightarrow{\text{optimization problem}}
 \min_{\Theta} \int_{\mathbf{v} \in \mathbb{V}} \mathcal{L}(f(\mathbf{v}; \Theta), \mathbf{d}(\mathbf{v}))$$

$$\left\{ \begin{array}{l}
 f(\mathbf{v}; \Theta) := \sum_{k=1}^K \mathbf{1}_{\mathbb{V}_k}(\mathbf{v}, f_k(\mathbf{v}, \Theta_k)) \\
 \mathbf{1}_{\mathbb{V}_k}(\mathbf{v}, x) = \begin{cases} x, & \mathbf{v} \in \mathbb{V}_k \\ 0, & \text{else} \end{cases} \\
 |\Theta| = \sum_{k=1}^K |\Theta_k|
 \end{array} \right.$$



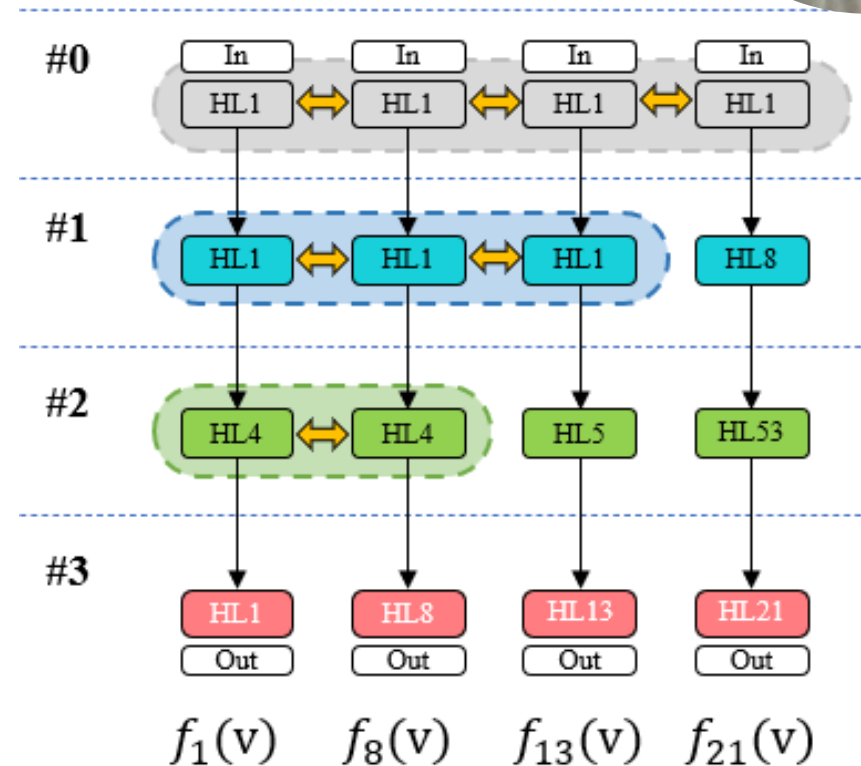
# 2 Method



## □ Hierarchical Parameter Sharing Mechanism

- We let these  $\{f_k\}$  share their neural network parameters hierarchically with each other according to the spatial distance between corresponding regions.
- for a leaf node at level  $l$ , its corresponding MLP-implemented hidden layers can be divided into  $l$  segments, i.e.  $f_k = f_k^{out} \circ f_k^l \circ f_k^{l-1} \circ \dots \circ f_k^1 \circ f_k^{in}$
- The sharing mechanism is defined on the octree structure. For example, if  $f_i$  and  $f_j$  share the same ancestor nodes at  $1 \sim 3$  levels, three pairs of hidden layer segments  $(f_i^1, f_j^1), (f_i^2, f_j^2), (f_i^3, f_j^3)$  will share the same parameters.

## Hierarchical Parameter Sharing



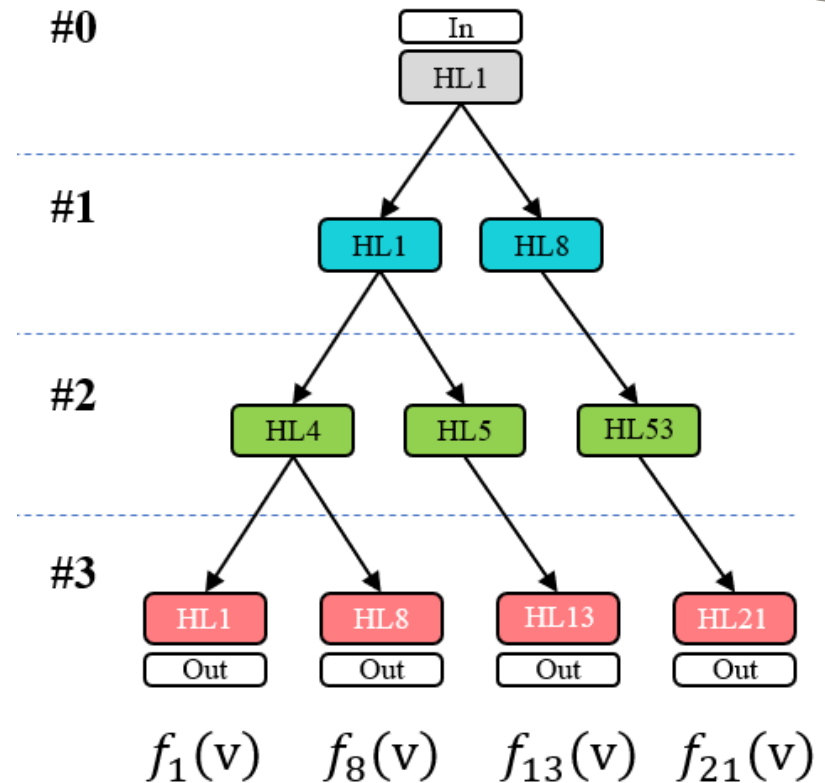
# 2 Method



## Tree-structured Network Architecture

- We propose a tree-structured MLP based on the L level octree partitioning.
- Each node contains a hyper layer consisting of some fully connected layers and takes the output of its parent node's hyper layer as input.
- Root node and leaf nodes additionally contain the input and output layers respectively.
- ✓ The output information of the leaf node is processed by the hyper layers in its ancestor nodes.
- ✓ At the same level, all sibling nodes share the same parent node and thus take the same information as input.

## Tree-structured MLP



# 3 Experiments

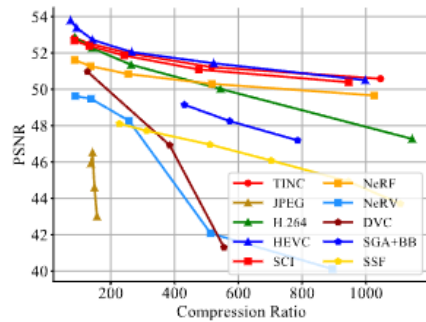


## Performance Comparison with SOTAs

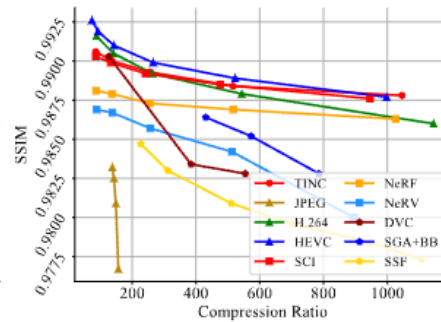
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# Best

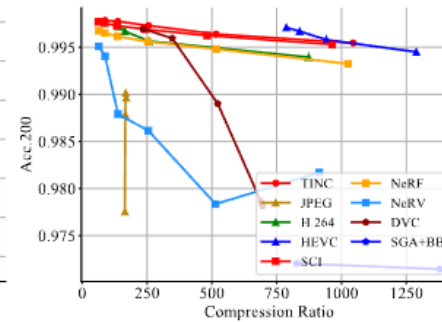
● Second best



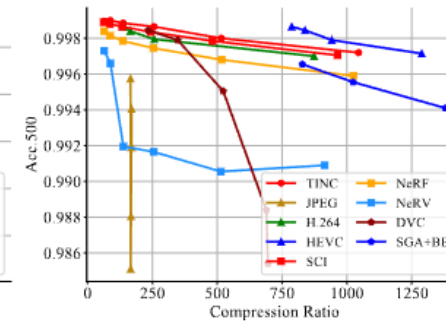
(a)



(b)



(c)



(d)

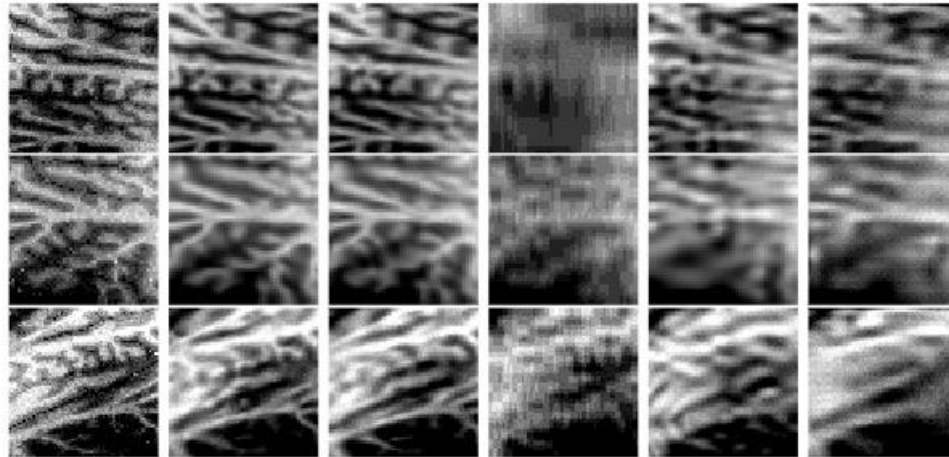
**TINC outperforms the SOTAs under high compression ratios**



# 3 Experiments

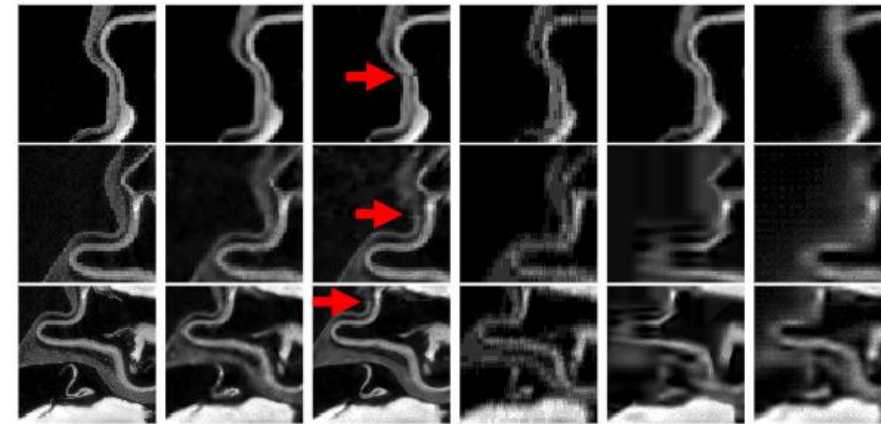


## □ Performance Comparison with SOTAs



(a) Three ROIs from *Brain* data; compression ratio:  $\sim 87\times$

✓ Outperforms the SOTAs

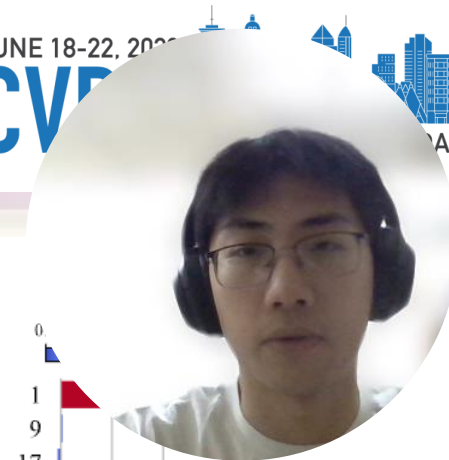


(b) Three ROIs from *Heart* data; compression ratio:  $\sim 87\times$

Ground Truth TINC (ours) SCI NeRV HEVC SGA+BB

✓ Avoids blocking artifacts at the boundary

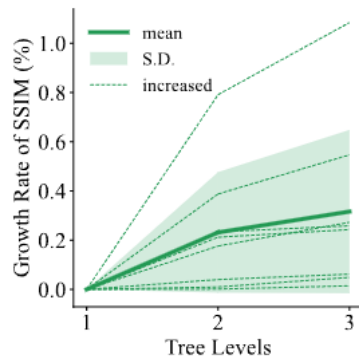
# 3 Experiments



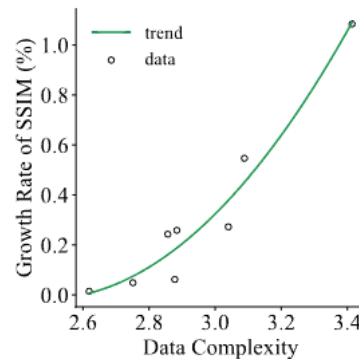
## Flexibility Settings for Different Data

➤ We also analyze TINC's flexibility to different cases via experimentally studying the effect of three key settings:

1. number of tree levels
2. intra-level parameter allocation
3. inter-level parameter allocation

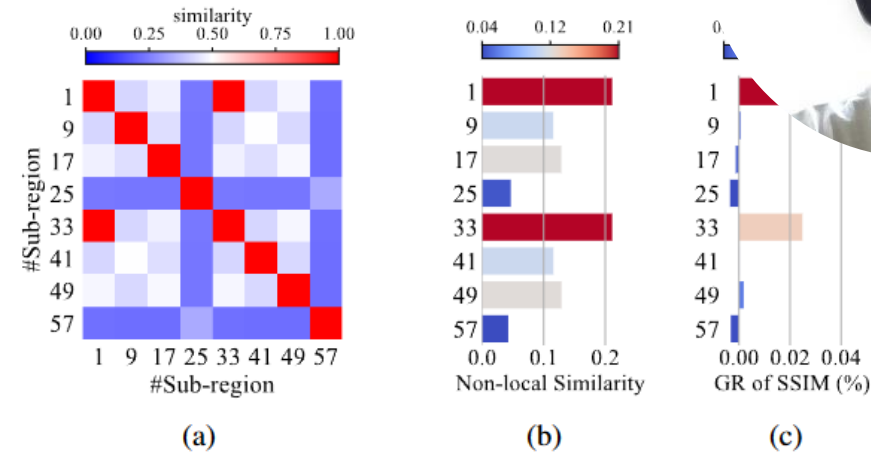


(a)

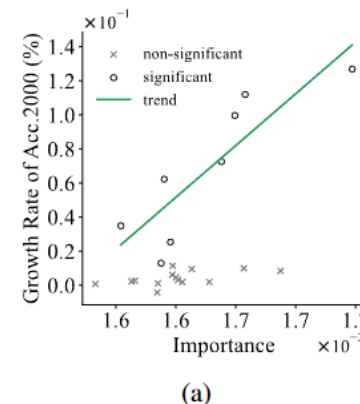


(b)

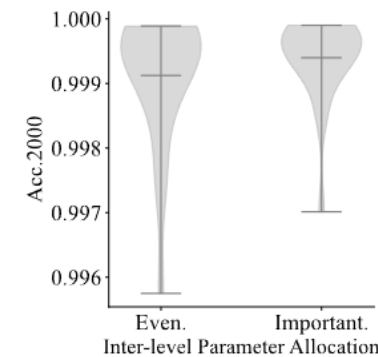
✓ Setting of Tree Levels L



## ✓ Inter-level Parameter Allocation



(a)



(b)

✓ Intra-level Parameter Allocation

# 4 Conclusion



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## □ Limitations and Future Extensions

- Similar to all current INR based compression methods, TINC is of high decompression speed but slow in compression, since it takes time to pursue the MLPs matching the target data.
- We plan to combine meta-learning to find the best initialization parameters for each organ to speed up TINC.