

Hyperbolic Contrastive Learning for Visual Representations beyond Objects

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Songwei Ge^{1*}, Shlok Mishra^{1*}, Simon Kornblith², Chun-Liang Li², David Jacobs¹

¹University of Maryland, College Park ²Google Research



Motivation

- We are using hyperbolic loss to learn this structure from real-world images!
- Representation learned by our model.



	Pre-train	Bbox	VOC	IN-100	IN-1k
MoCo-v2	COCO	-	64.79	64.84	51.17
HCL w/o \mathcal{L}_{hyp}	COCO	SS	73.13	73.84	54.21
HCL w/o \mathcal{L}_{hyp}	COCO	GT	75.55	76.22	54.52
HCL	COCO	SS	74.19	75.16	55.03
HCL	COCO	GT	76.51	76.74	55.63
MoCo-v2	OpenImages	-	69.95	72.80	54.12
HCL w/o \mathcal{L}_{hyp}	OpenImages	SS	71.82	75.33	56.58
HCL w/o \mathcal{L}_{hyp}	OpenImages	GT	73.79	77.36	57.57
HCL	OpenImages	SS	74.31	78.14	58.12
HCL	OpenImages	GT	75.40	79.08	58.51

- Linear evaluation results.

- Object images of the same class tend to gather near the center around similar directions, while the scene images are far away in these directions with larger norms.

Motivation



Motivation



Motivation



Motivation

- Objects from visually similar classes lie close to each other in the representation space.



* Wu, Zhirong, et al. "Unsupervised feature learning via non-parametric instance discrimination." CVPR 2018.

- Real world images have much more diversity and structure in them as compared to ImageNet images.

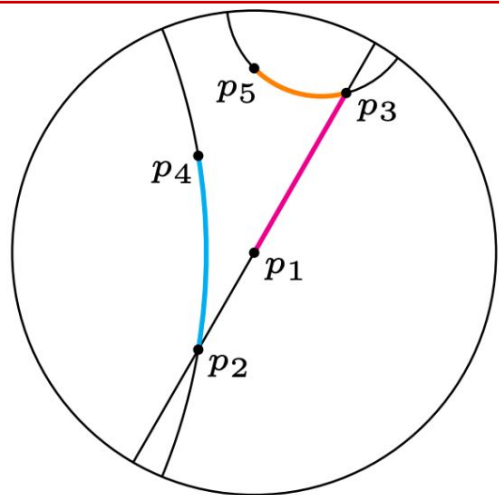
OpenImages Samples



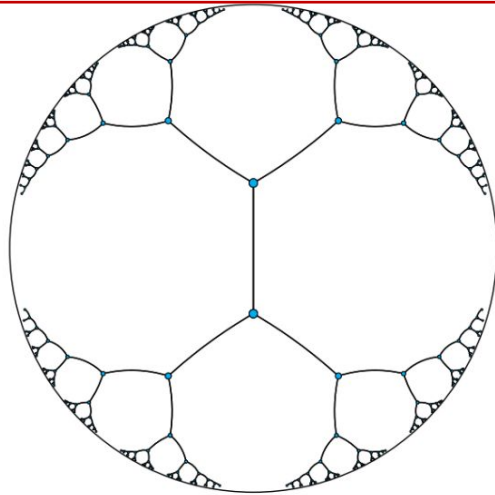
Background

- Hyperbolic distance:

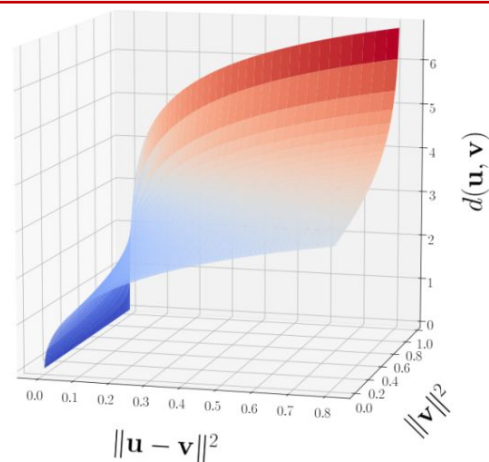
$$d(\mathbf{u}, \mathbf{v}) = \operatorname{arcosh} \left(1 + 2 \frac{\|\mathbf{u} - \mathbf{v}\|^2}{(1 - \|\mathbf{u}\|^2)(1 - \|\mathbf{v}\|^2)} \right).$$



(a) Geodesics of the Poincaré disk

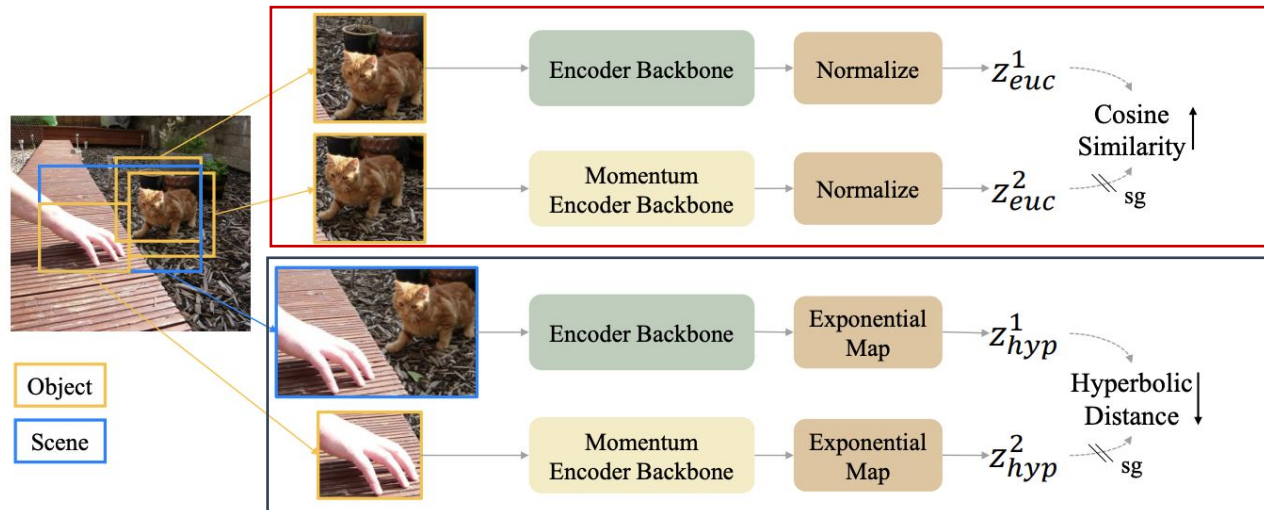


(b) Embedding of a tree in \mathcal{B}^2



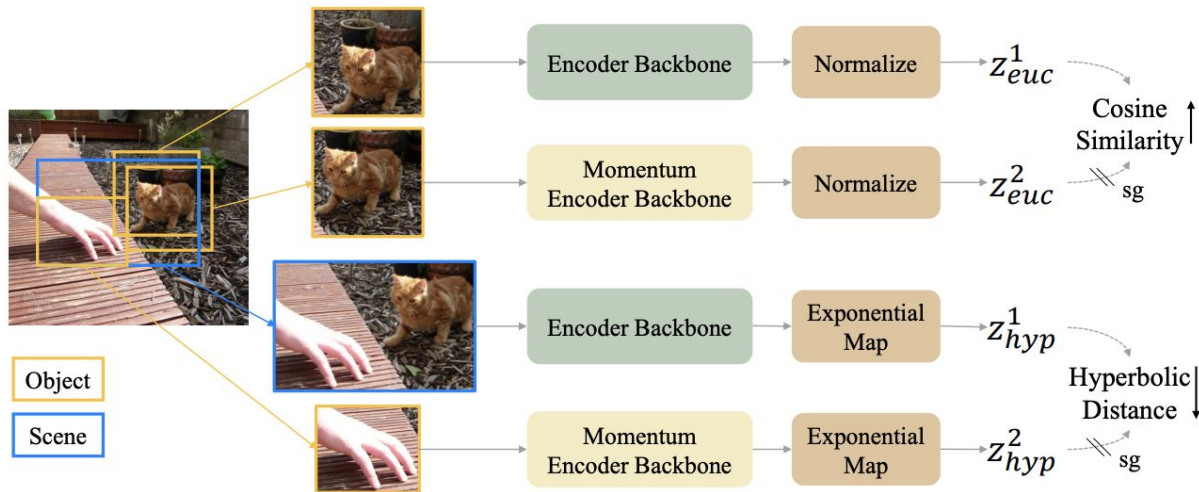
(c) Growth of Poincaré distance

Proposed approach



- Two object regions are cropped to learn object representations with the euclidean loss.
- Scene region with a contained object region is used to learn scene representations using hyperbolic space.

Proposed approach



$$\mathcal{L}_{hyp} = -\log \frac{\exp\left(-\frac{d_{\mathbb{D}}(\mathbf{z}_{hyp}^1, \mathbf{z}_{hyp}^2)}{\tau}\right)}{\exp\left(-\frac{d_{\mathbb{D}}(\mathbf{z}_{hyp}^1, \mathbf{z}_{hyp}^2)}{\tau}\right) + \sum_n \exp\left(-\frac{d_{\mathbb{D}}(\mathbf{z}_{hyp}^1, \mathbf{z}_{hyp}^n)}{\tau}\right)}$$

- Here z_{hyp}^1 and z_{hyp}^2 are the projected features on the Poincaré ball.
- $d_{\mathbb{D}}$ is the riemannian distance on the Poincaré ball.

Results using HCL.

	Pre-train	Bbox	VOC	IN-100	IN-1k
MoCo-v2	COCO	-	64.79	64.84	51.17
HCL w/o \mathcal{L}_{hyp}	COCO	SS	73.13	73.84	54.21
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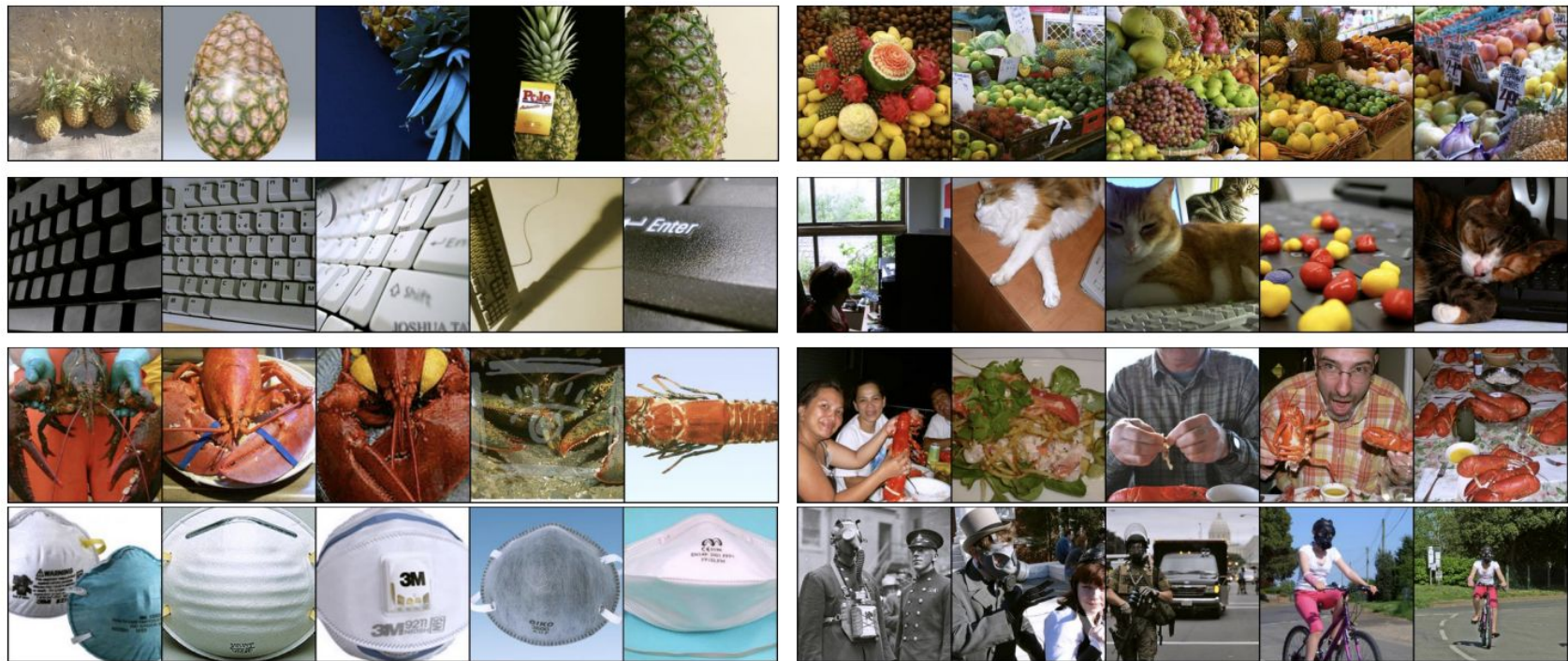
- Linear evaluation results.

	AP ^b	AP ₅₀ ^b	AP ₇₅ ^b	AP ^m	AP ₅₀ ^m	AP ₇₅ ^m
<i>MoCo-v2 pre-trained on COCO:</i>						
Baseline	38.5	58.1	42.1	34.8	55.3	37.3
HCL w/o \mathcal{L}_{hyp}	39.7	60.1	43.4	36.0	57.3	38.8
HCL CC	40.6	61.1	44.5	37.0	58.3	39.7
<i>Dense-CL pre-trained on COCO:</i>						
Baseline	39.6	59.3	43.3	35.7	56.5	38.4
HCL w/o \mathcal{L}_{hyp}	41.3	61.5	44.7	37.5	59.5	40.4
HCL	42.5	62.5	45.8	38.5	60.6	41.4
<i>ORL pre-trained on COCO:</i>						
Baseline	40.3	60.2	44.4	36.3	57.3	38.9
HCL	41.4	61.4	45.5	37.3	58.5	40.0
<i>Dense-CL pre-trained on OpenImages:</i>						
Baseline	38.2	58.9	42.6	34.8	55.3	37.8
HCL w/o \mathcal{L}_{hyp}	41.1	61.5	44.4	37.2	58.3	39.7
HCL	42.1	62.6	45.5	38.3	59.4	40.6

- Object Detection and Semantic Segmentation results on COCO.

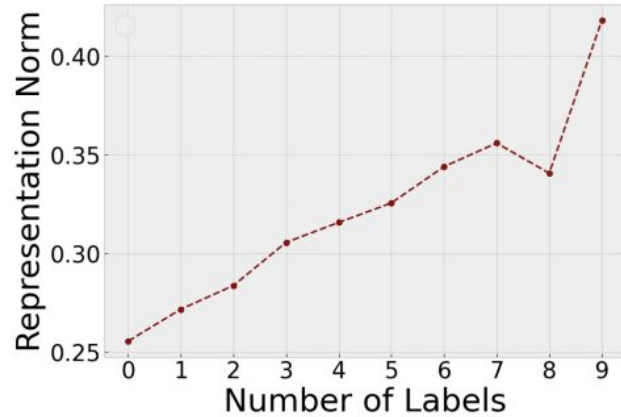
Analysis

Smallest norms (objects) ← ———— ■■■ ———— → Largest norms (scenes)



- The 5 images on the left have the smallest representation norms among all the images from the same class, and the 5 on the right have the largest norms.

Label Uncertainty quantification



- Average representation norms of images with different number of labels in ImageNet-Real