

RoDynRF

Robust Dynamic Radiance Fields

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TUE-AM-002



Robust Dynamic Radiance Fields

- **Input:** a causally captured monocular video



Robust Dynamic Radiance Fields

- **Output:** space-time view synthesis



Fix time
Change view



Fix view
Change time



Fix time
Change view

Robust Dynamic Radiance Fields

- **Challenge:** COLMAP fails to recover camera poses

Input dynamic
monocular videos



Robust Dynamic Radiance Fields

- Our work tackles this **robustness** problem and showcases high-fidelity dynamic view synthesis results on a wide variety of videos

Reconstructed poses/geometry



Space-time synthesis results



Neural Radiance Field (NeRF)

Input

A set of calibrated images



Output

A static 3D scene representation
that renders novel views



What are the remaining challenges?

Input

A set of **calibrated** images

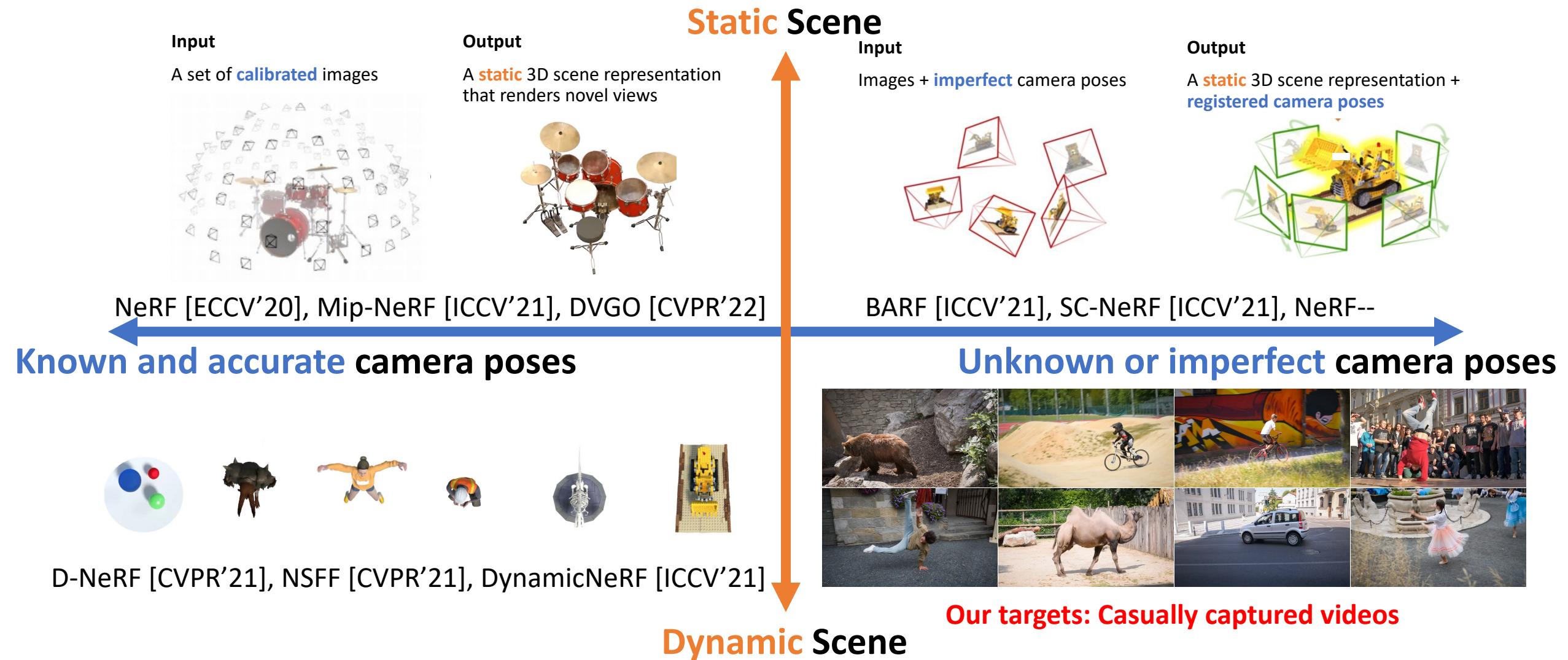


Output

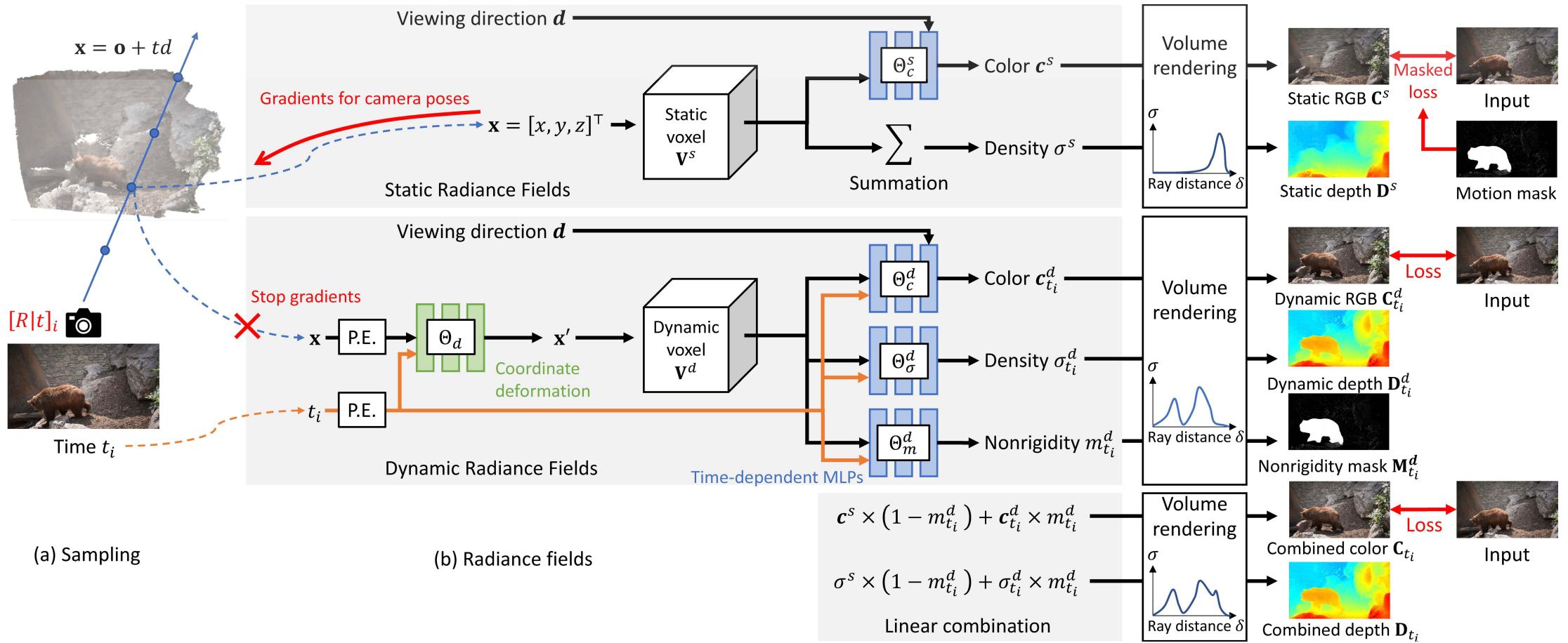
A **static** 3D scene representation
that renders novel views



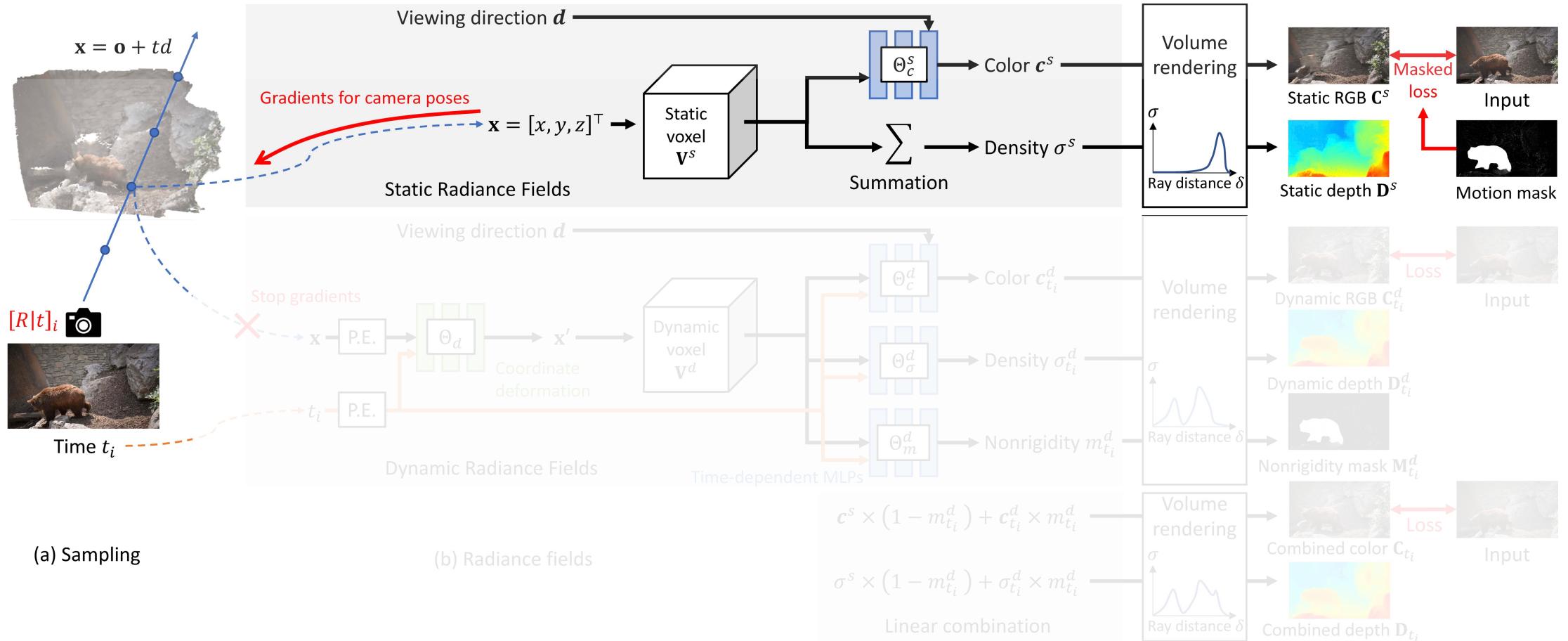
Extensions of NeRF



RoDynRF

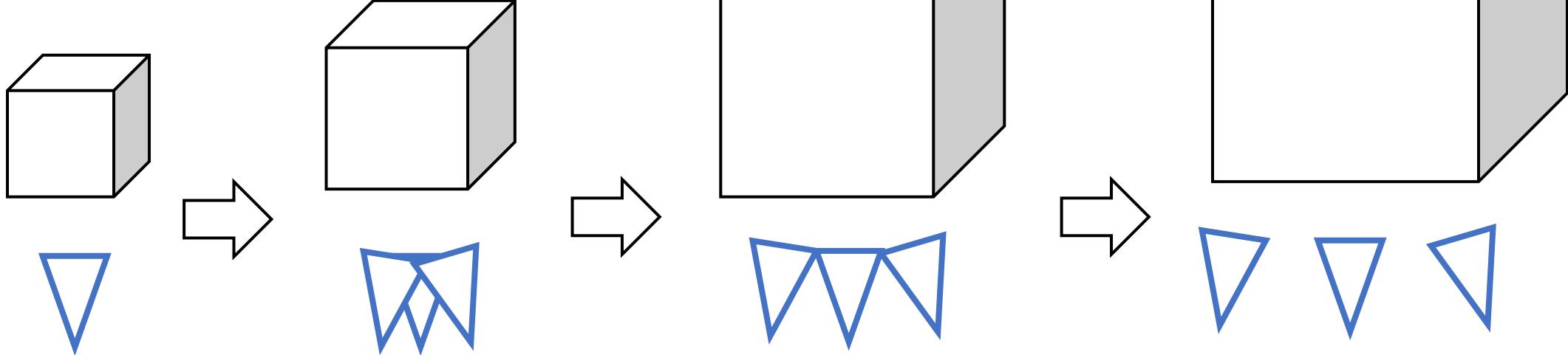


RoDynRF – Static Radiance Field + Camera Optimization



Camera Optimization

- Coarse-to-fine strategy

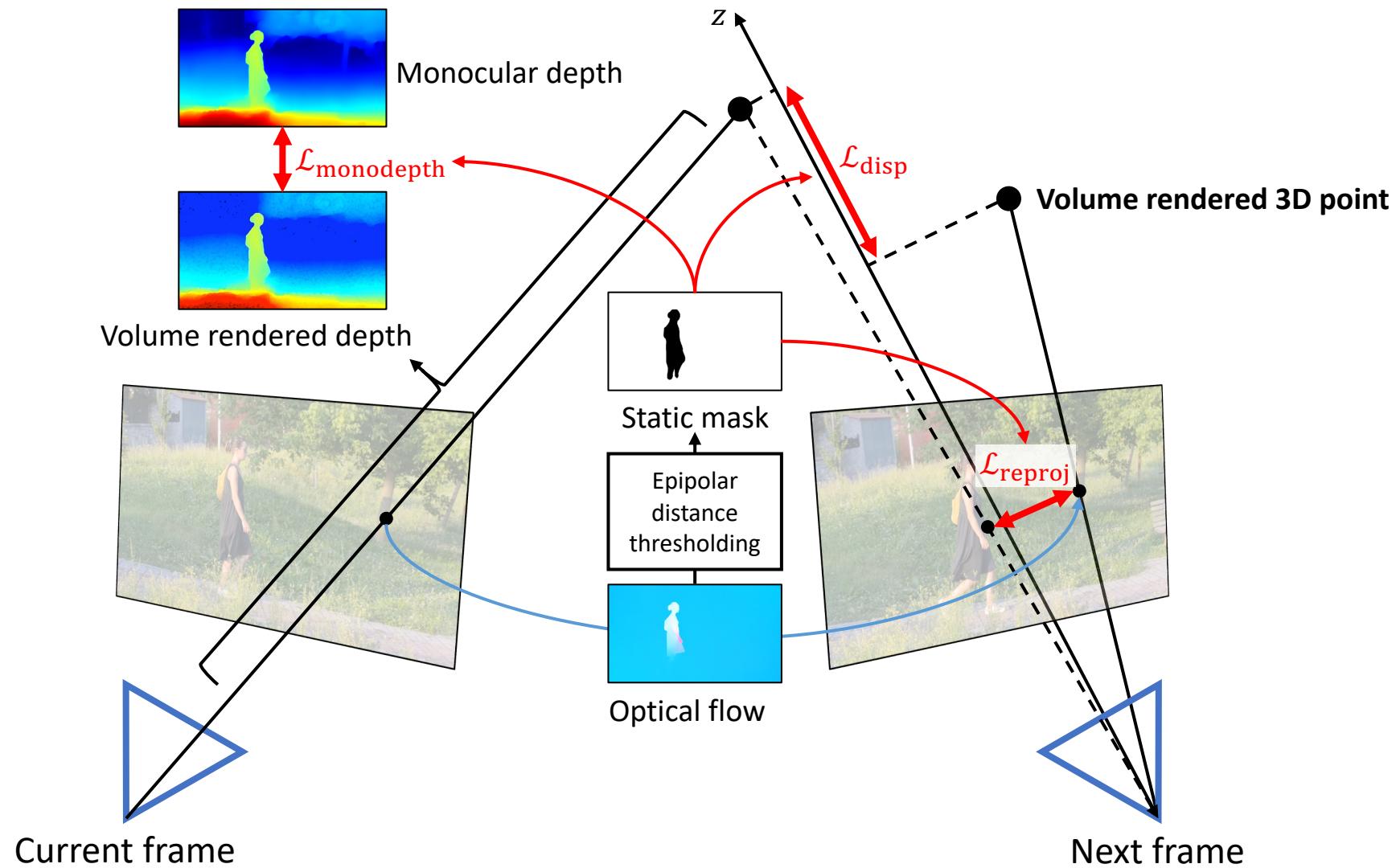


Start from
identity poses



Reconstructed images

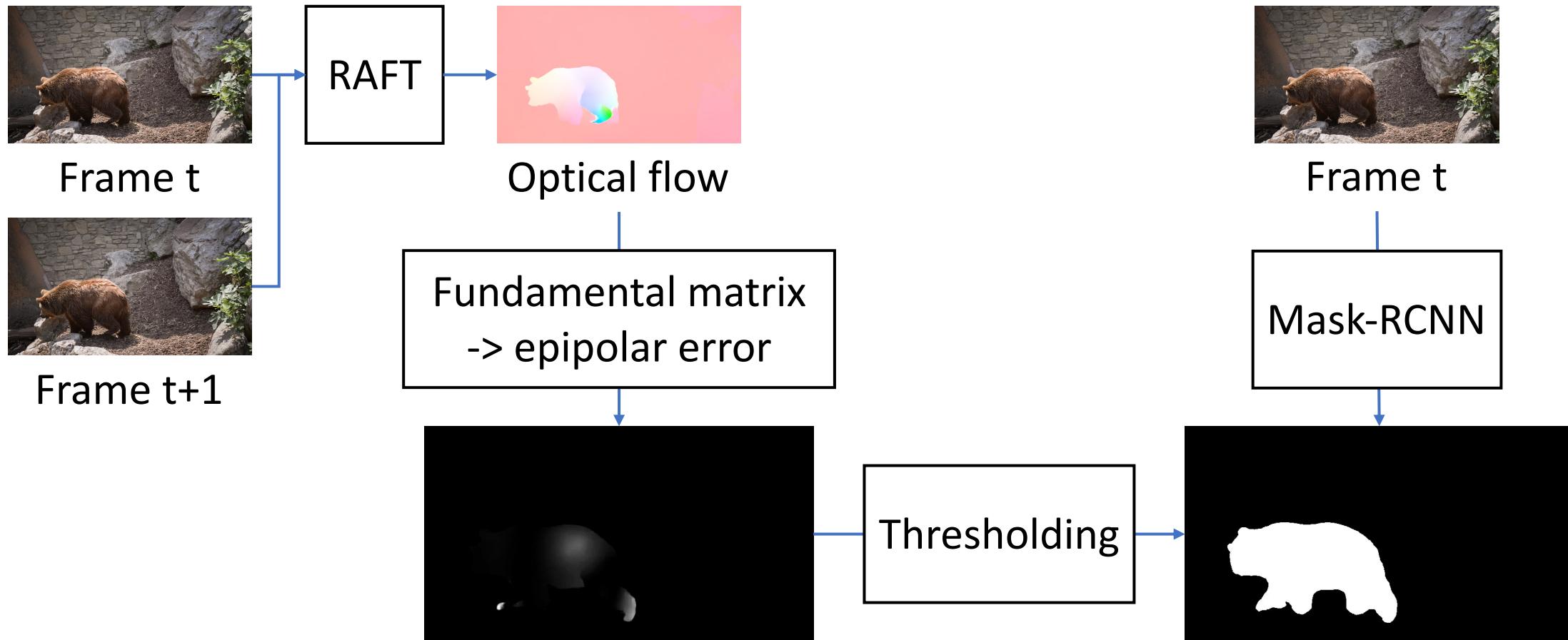
Static Radiance Field + Camera Optimization



Pose Estimation

But we do not have the masks for casual videos

- Mask out moving objects with epipolar constraints



Static Radiance Field Reconstruction Results



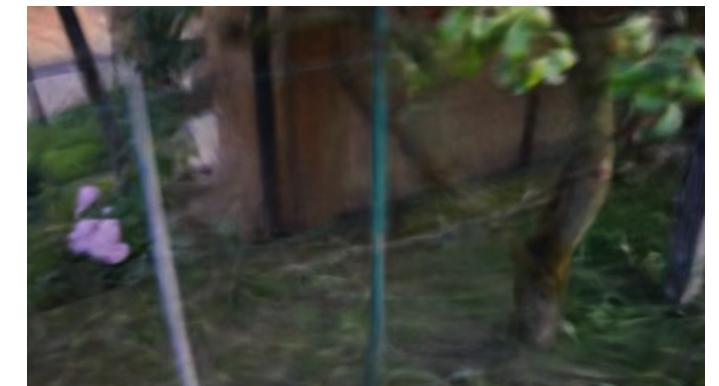
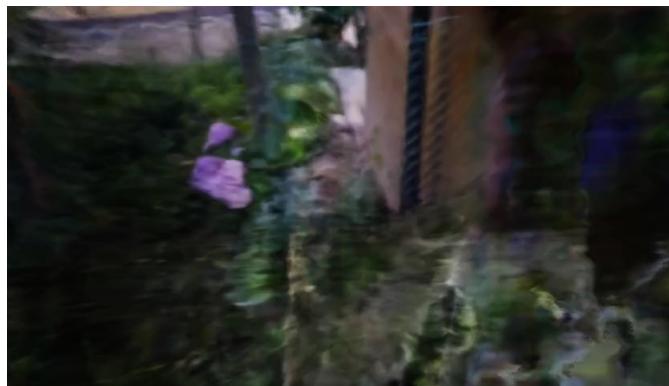
Input video



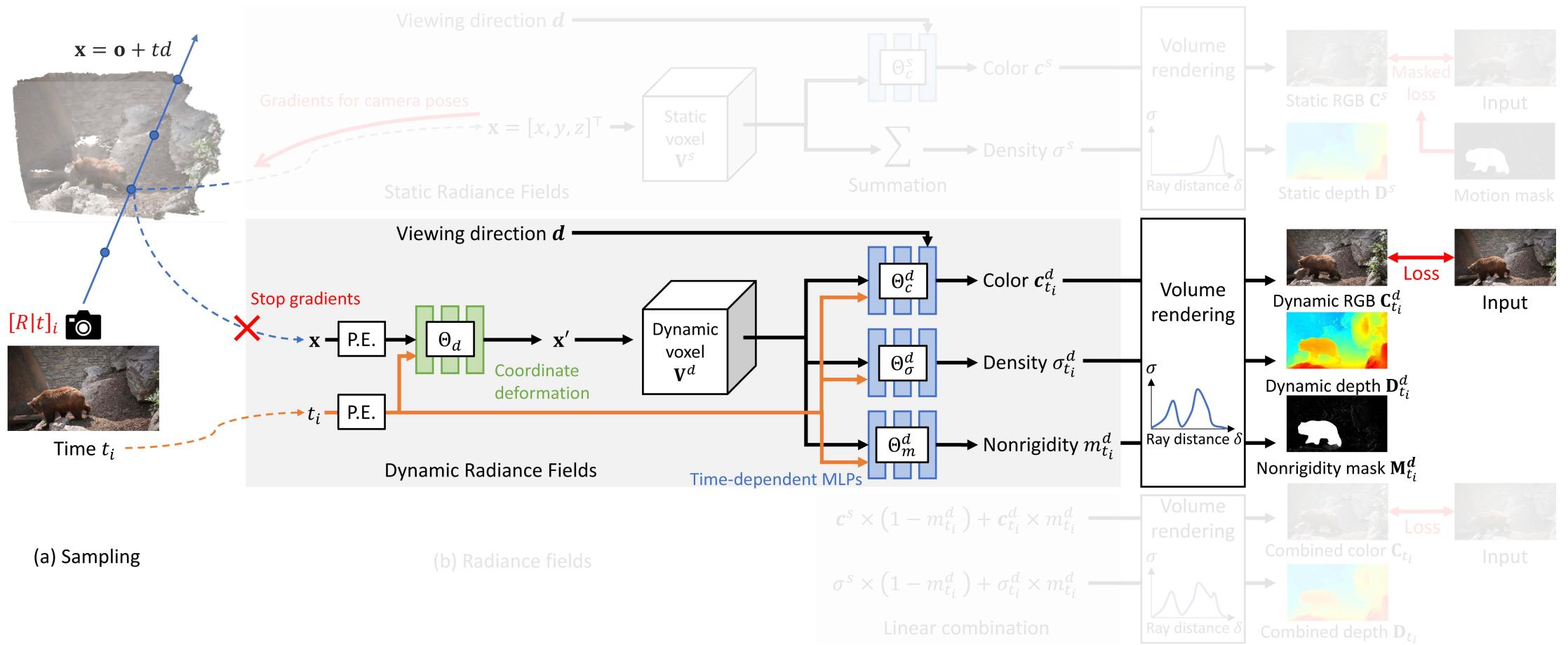
BARF [ICCV'21]



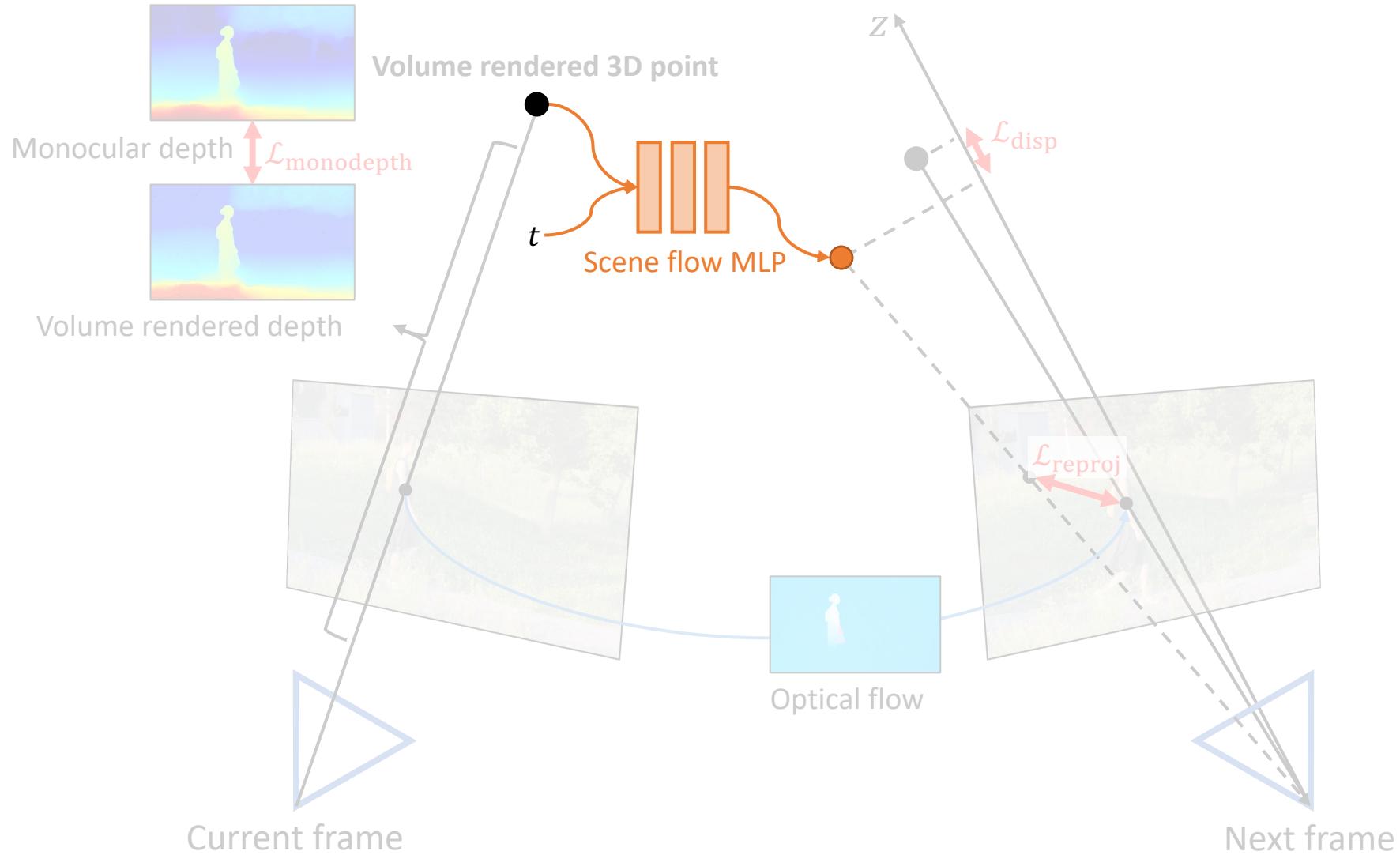
Ours



RoDynRF – Dynamic Radiance Field

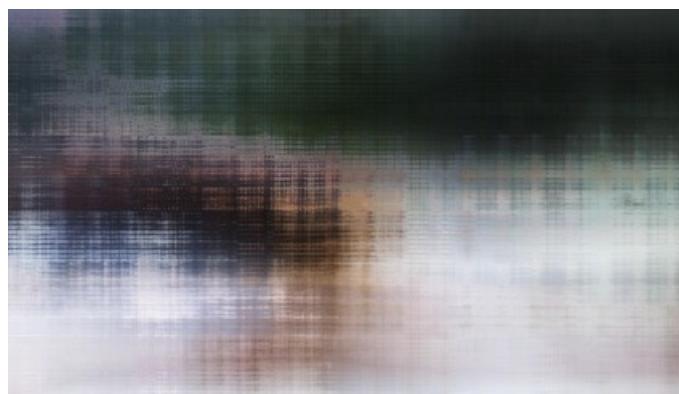


Dynamic Radiance Field



Space-Time Synthesis Comparisons

- With COLMAP poses



Input video

DynamicNeRF [ICCV'21]

Ours

Visual Comparisons + Our Estimated Poses



Input video

COLMAP



Ours



DynamicNeRF [ICCV'21]

Fails to recover
camera poses



TiNeuVox [SIGGRAPH Asia'22]

Visual Comparisons + Our Estimated Poses



Input video

Estimated poses



Ours



DynamicNeRF [ICCV'21]



TiNeuVox [SIGGRAPH Asia'22]

Visual Comparisons + Our Estimated Poses



Input video

Estimated poses



Ours



DynamicNeRF [ICCV'21]



TiNeuVox [SIGGRAPH Asia'22]

Visual Comparisons + Our Estimated Poses



Input video

Estimated poses



DynamicNeRF [ICCV'21]



Ours



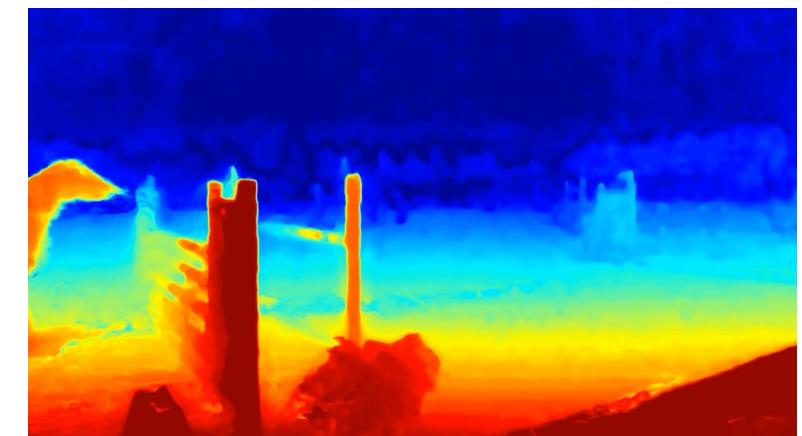
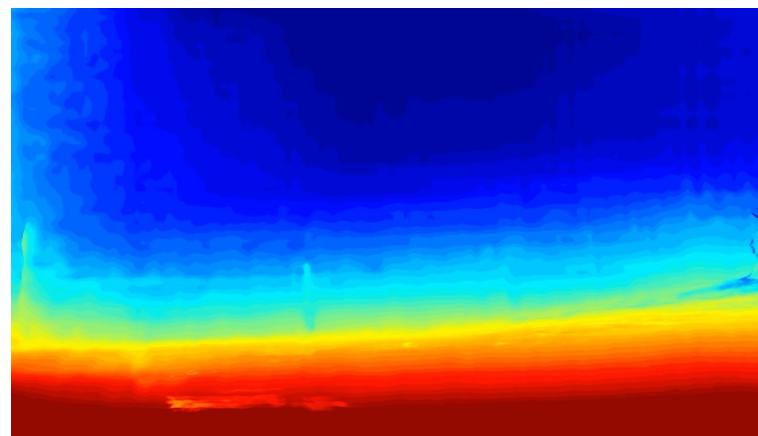
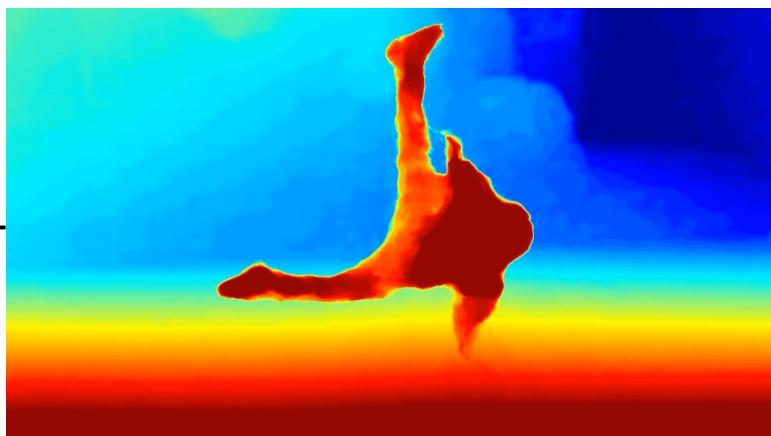
TiNeuVox [SIGGRAPH Asia'22]

Consistent Geometry Prediction

RGB



Depth



Failure Cases -- Fast Moving camera



Input



Our space-time synthesis result

Failure Cases -- Changing Focal Length



Input



Our space-time synthesis result



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