

JacobiNeRF: NeRF Shaping with Mutual Information Gradients

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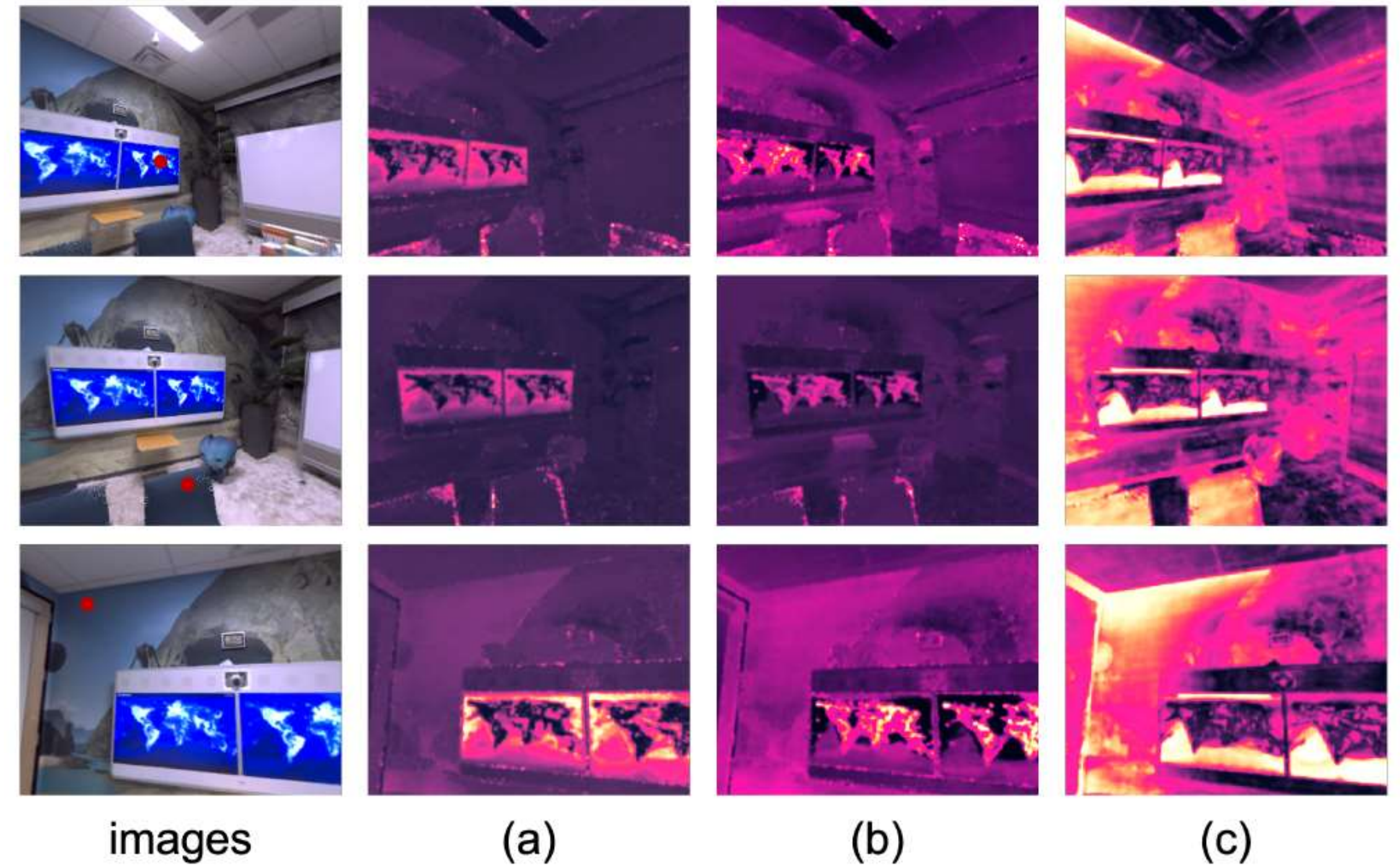
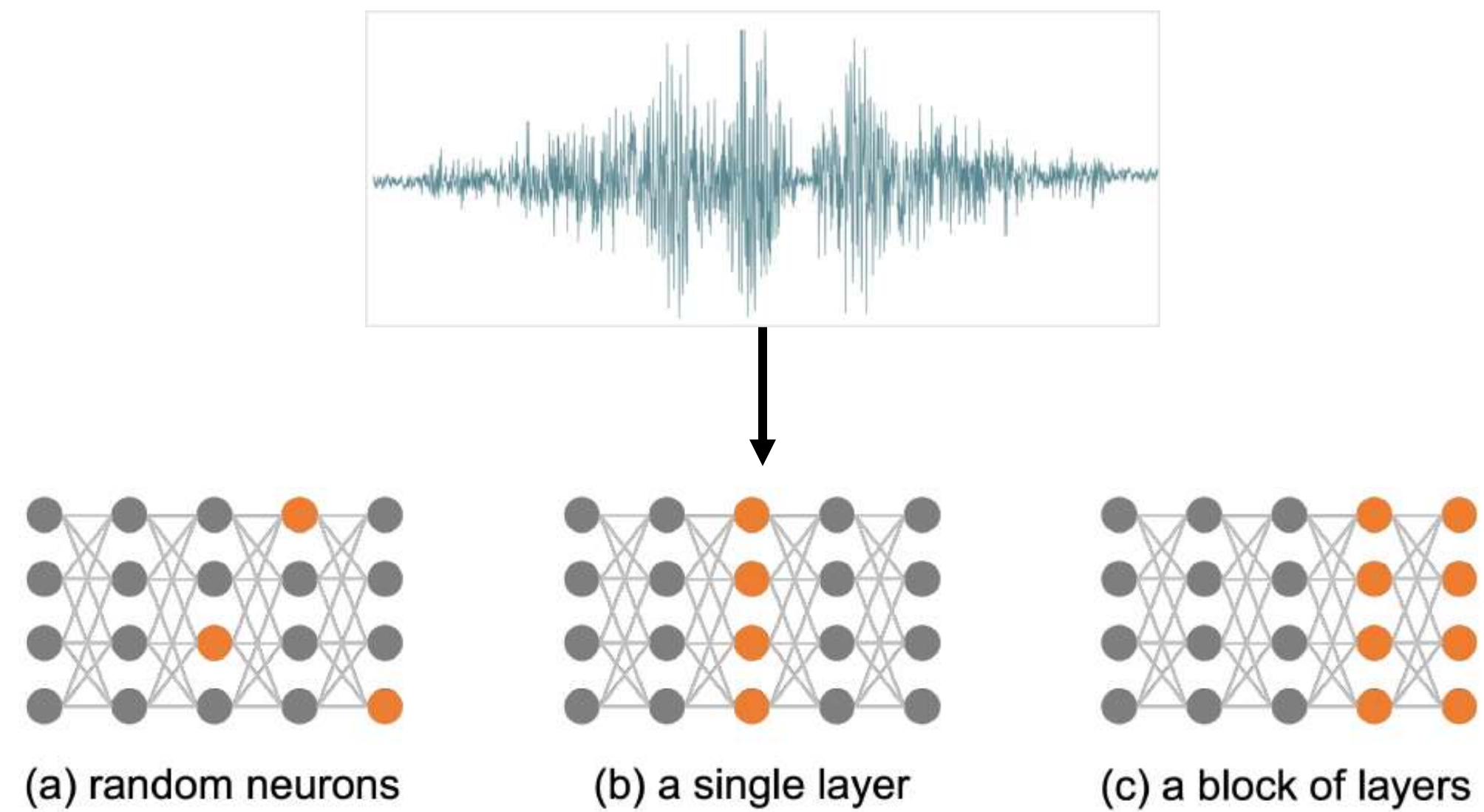
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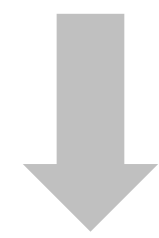
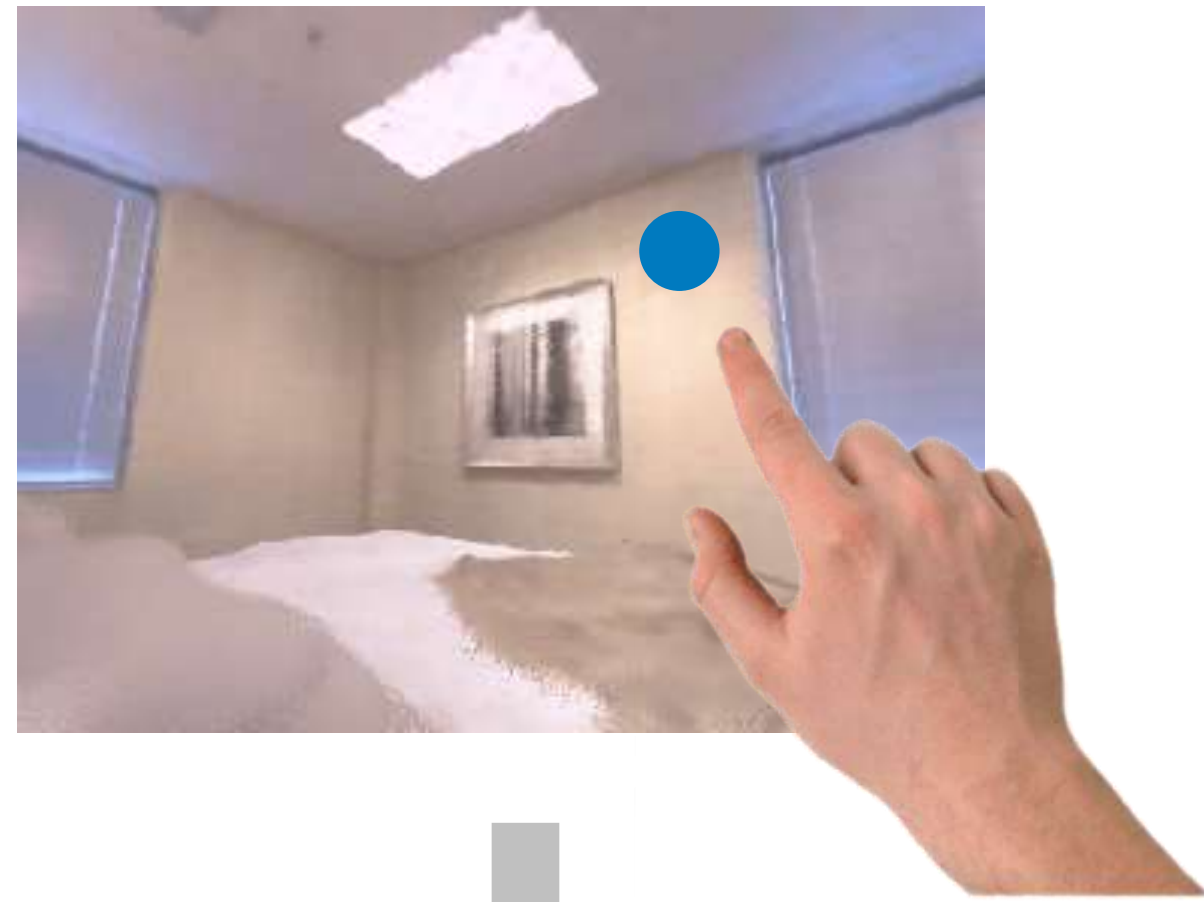


Preview: Plain NeRF Lacks Semantic Awareness



“Jiggling” the neuron weights of the NeRF results in diffuse perturbations that are not semantically aligned

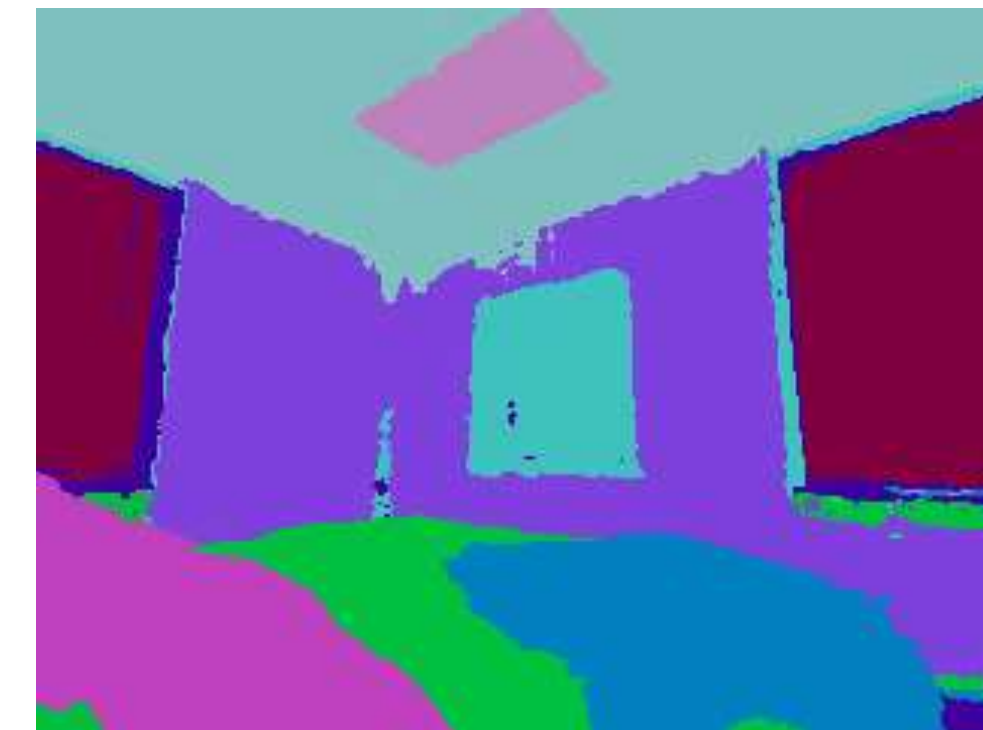
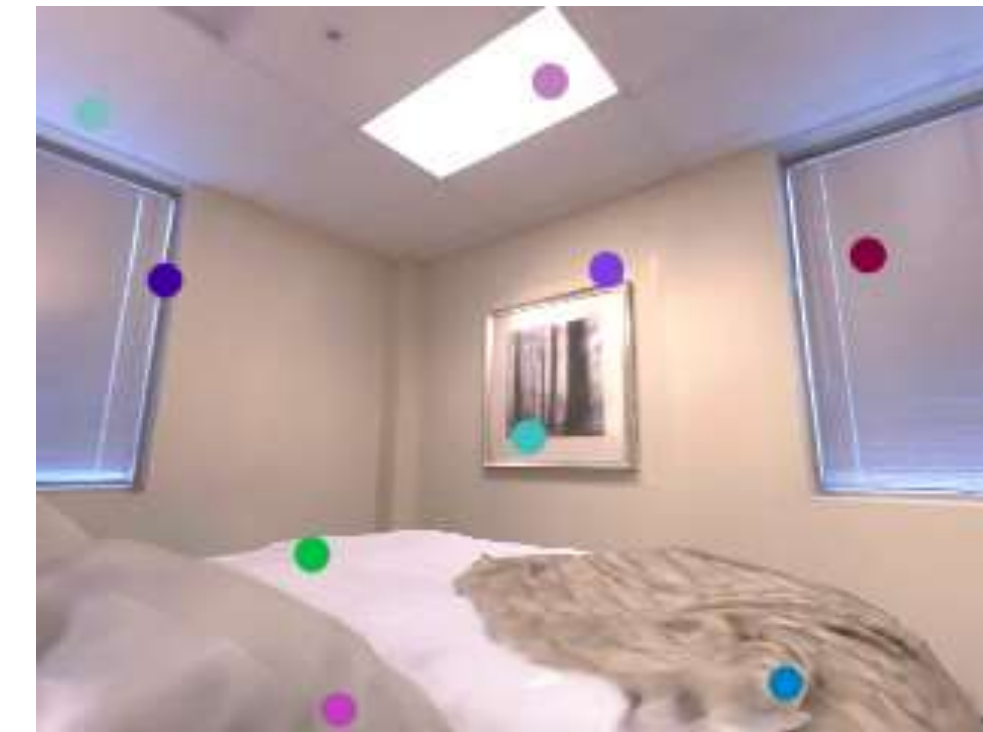
Preview: User Interactions with 3D Scenes through 2D Views



selecting

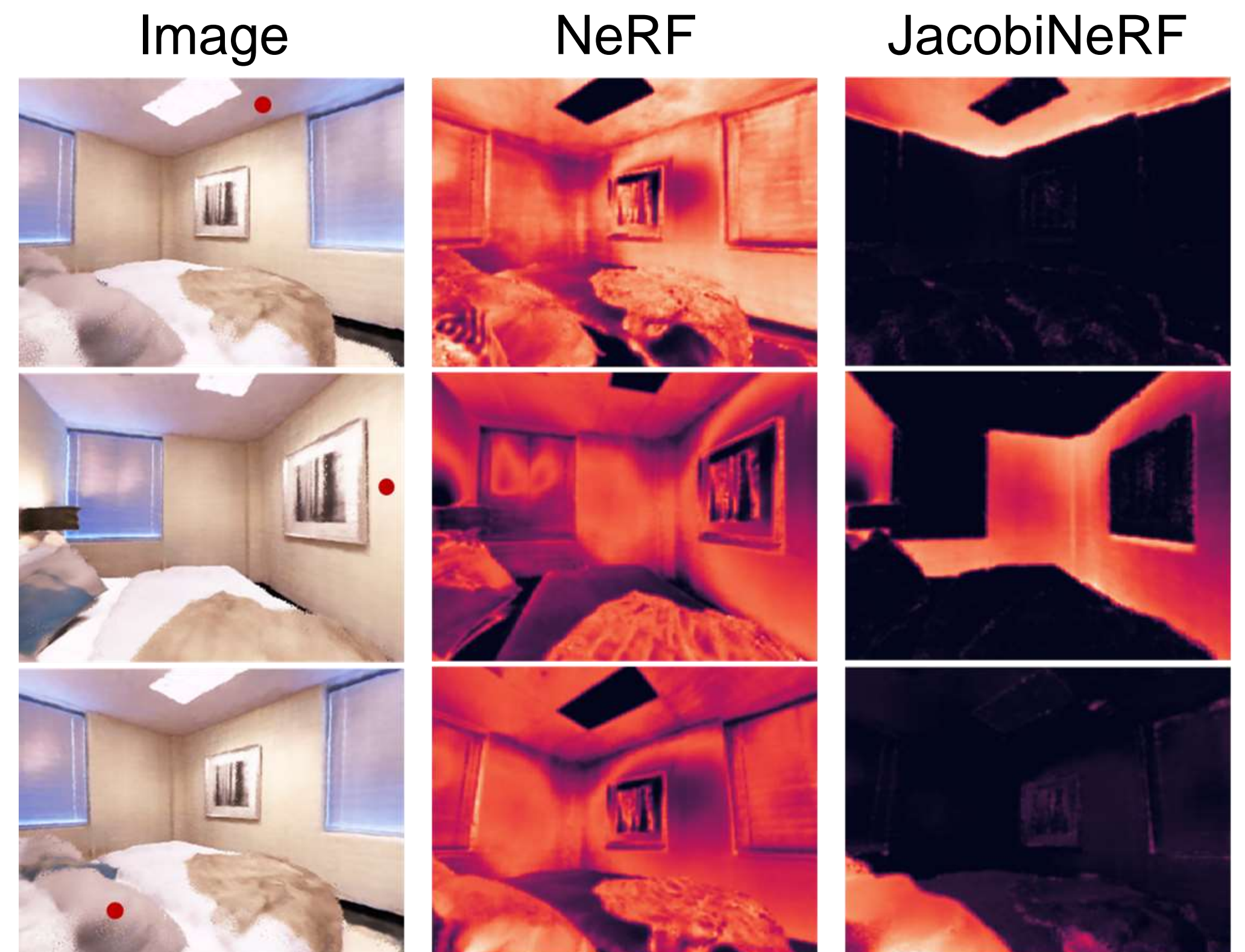
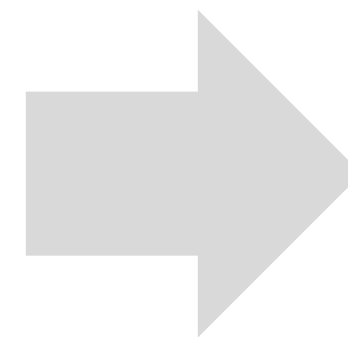
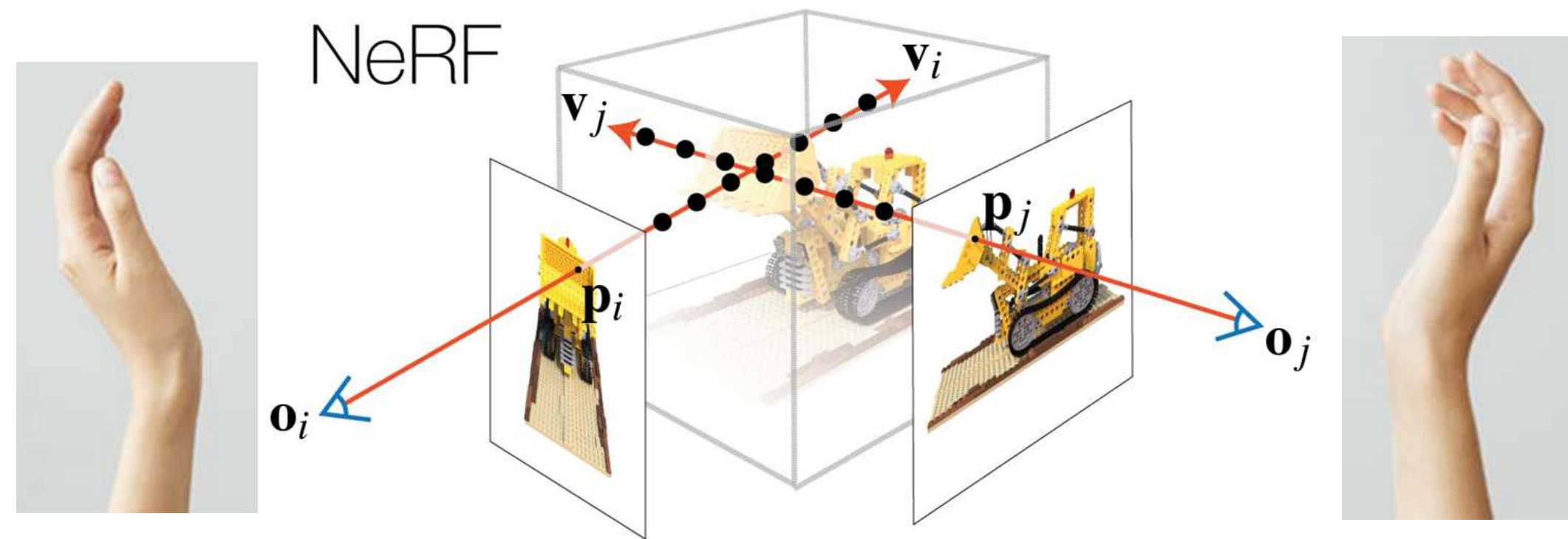


editing

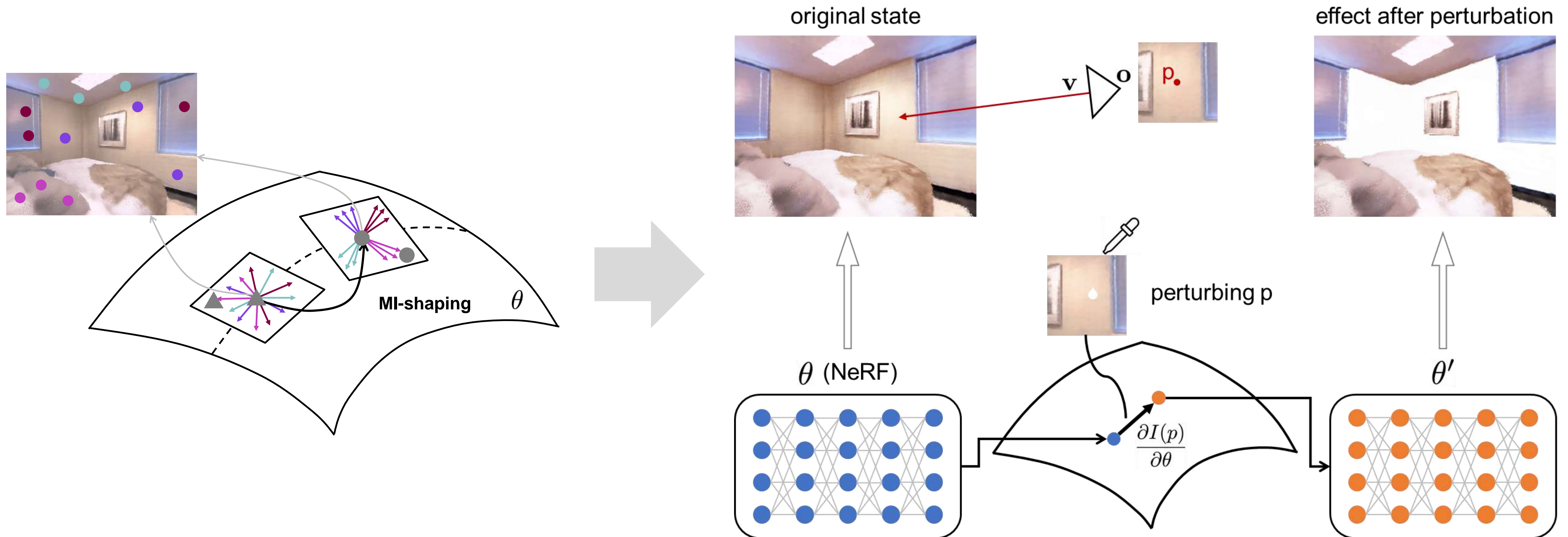


label propagation

Preview: Encode Semantic Correlations into a NeRF



Preview: NeRF Shaping with Mutual Information Gradients



Preview: Label Propagation

Semantic Seg

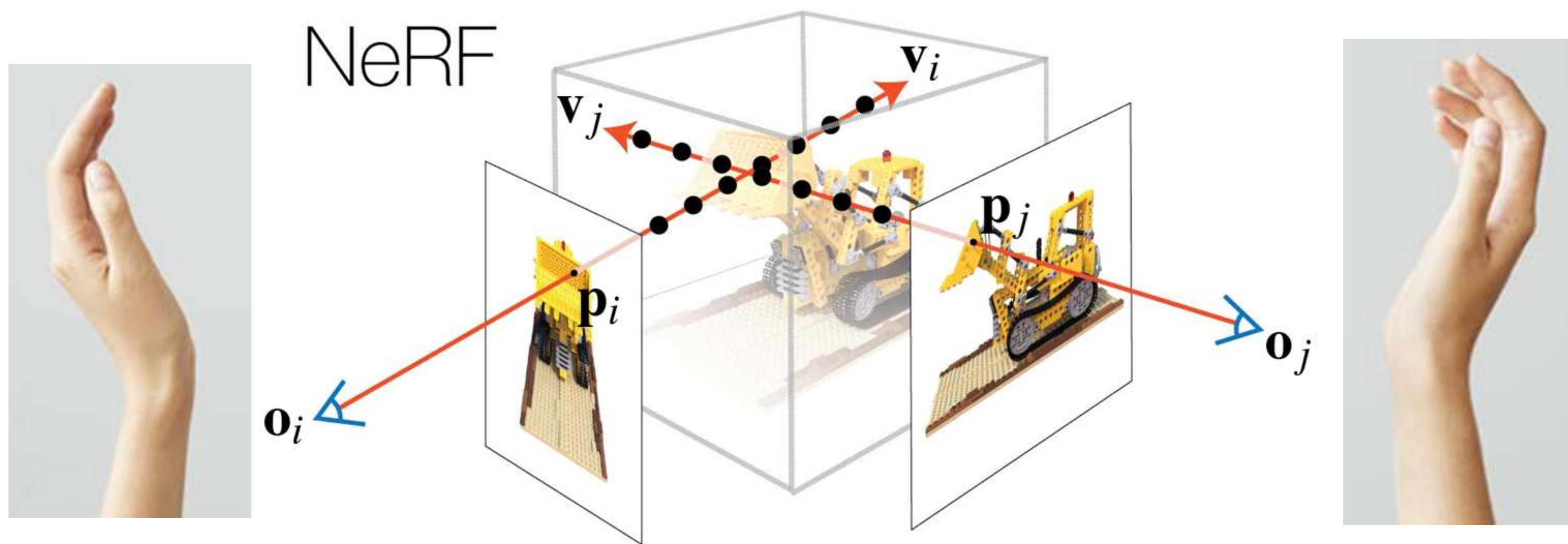


Instance Seg

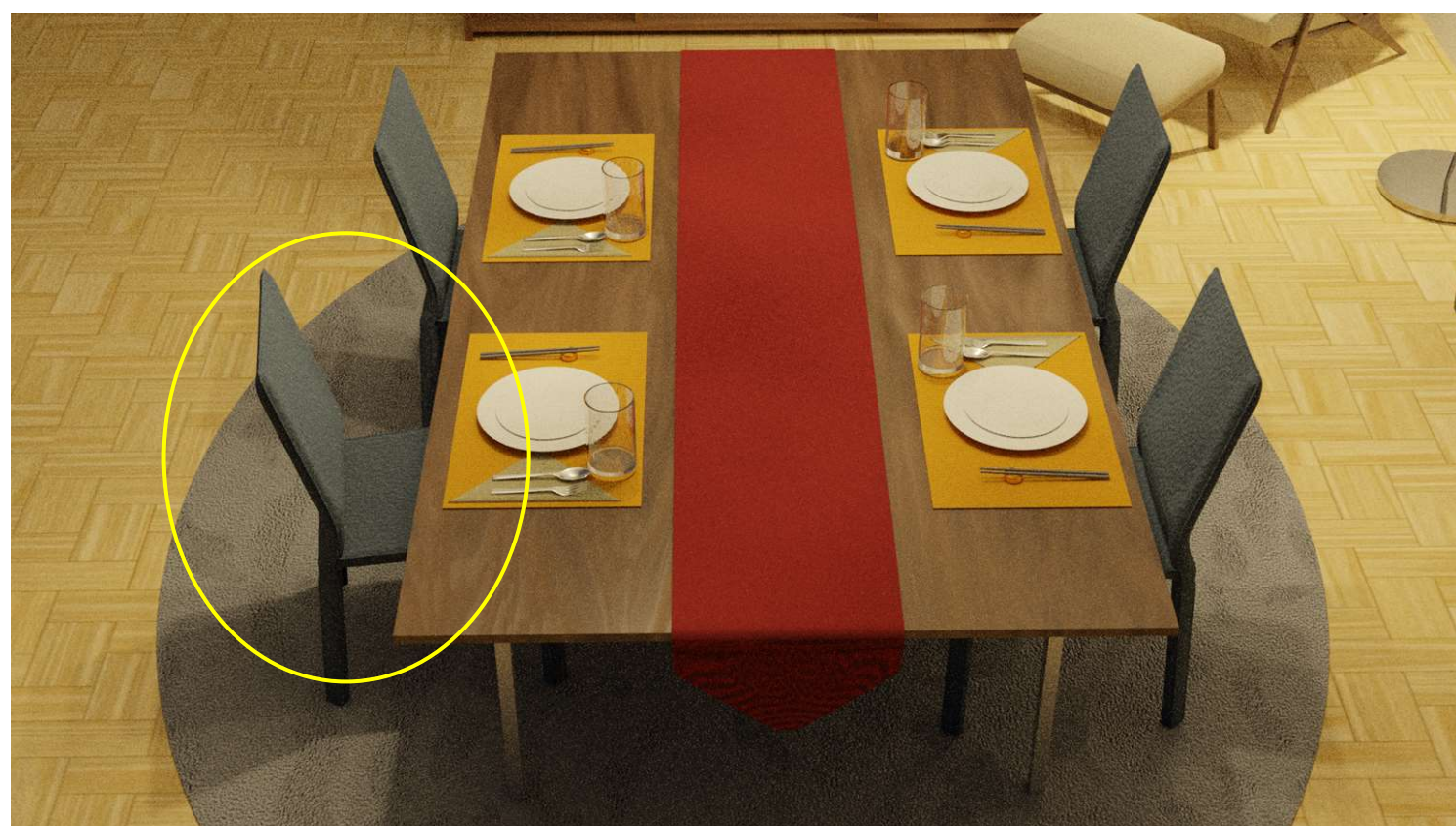


Example sparse annotation interaction

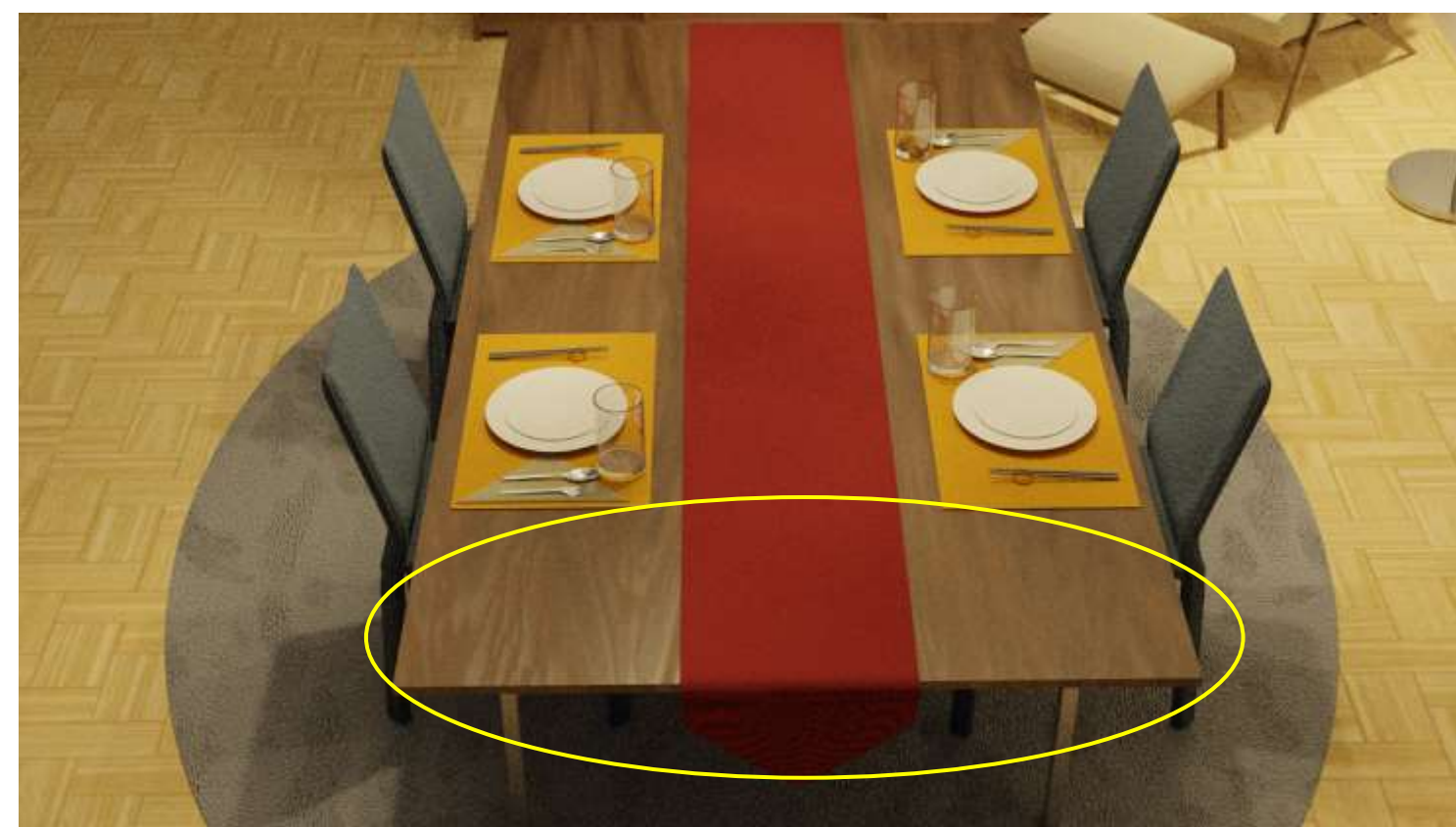
User Interactions with NeRFs



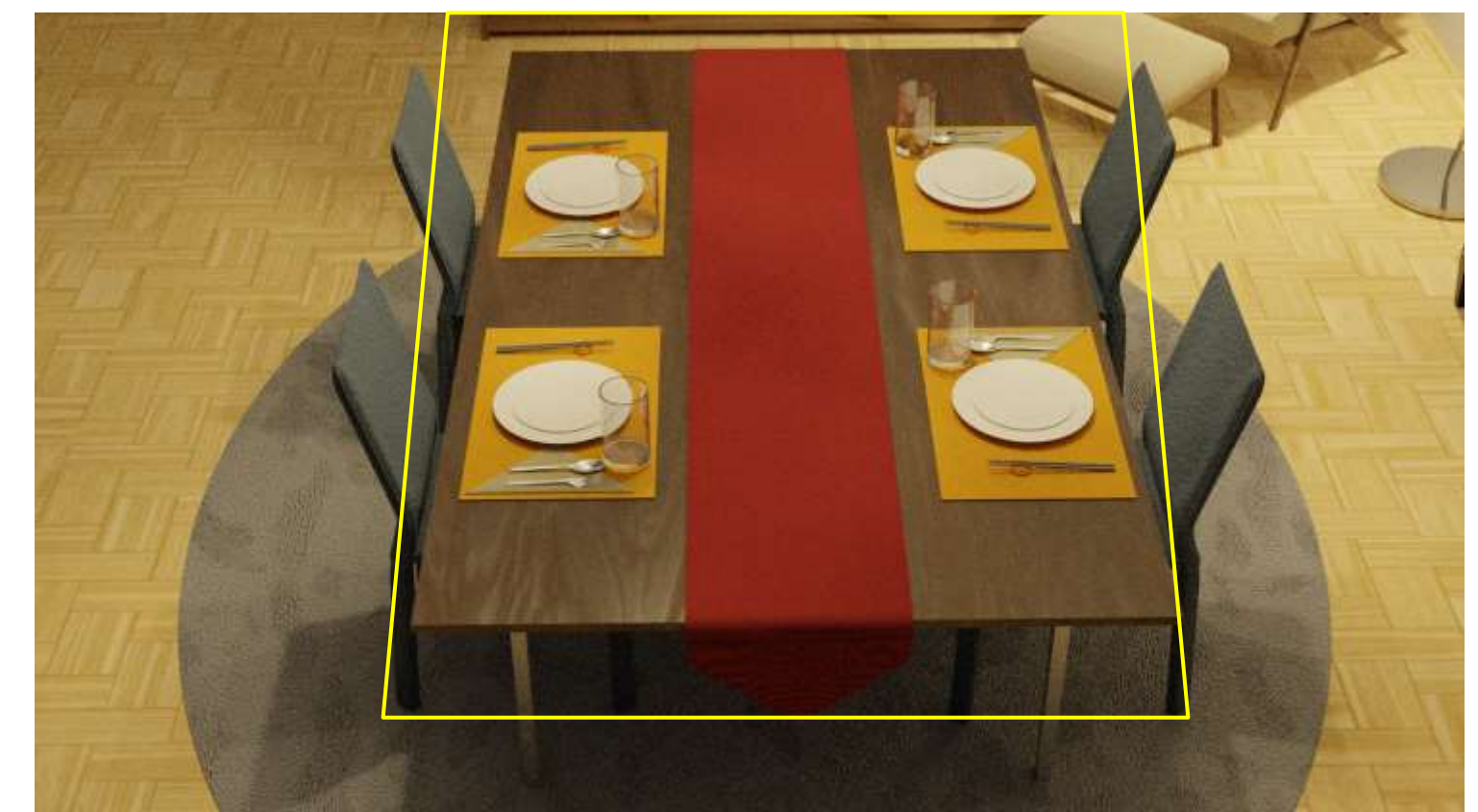
Semantic Structure of a Scene is Reflected in its Co-Variations



this chair has moved

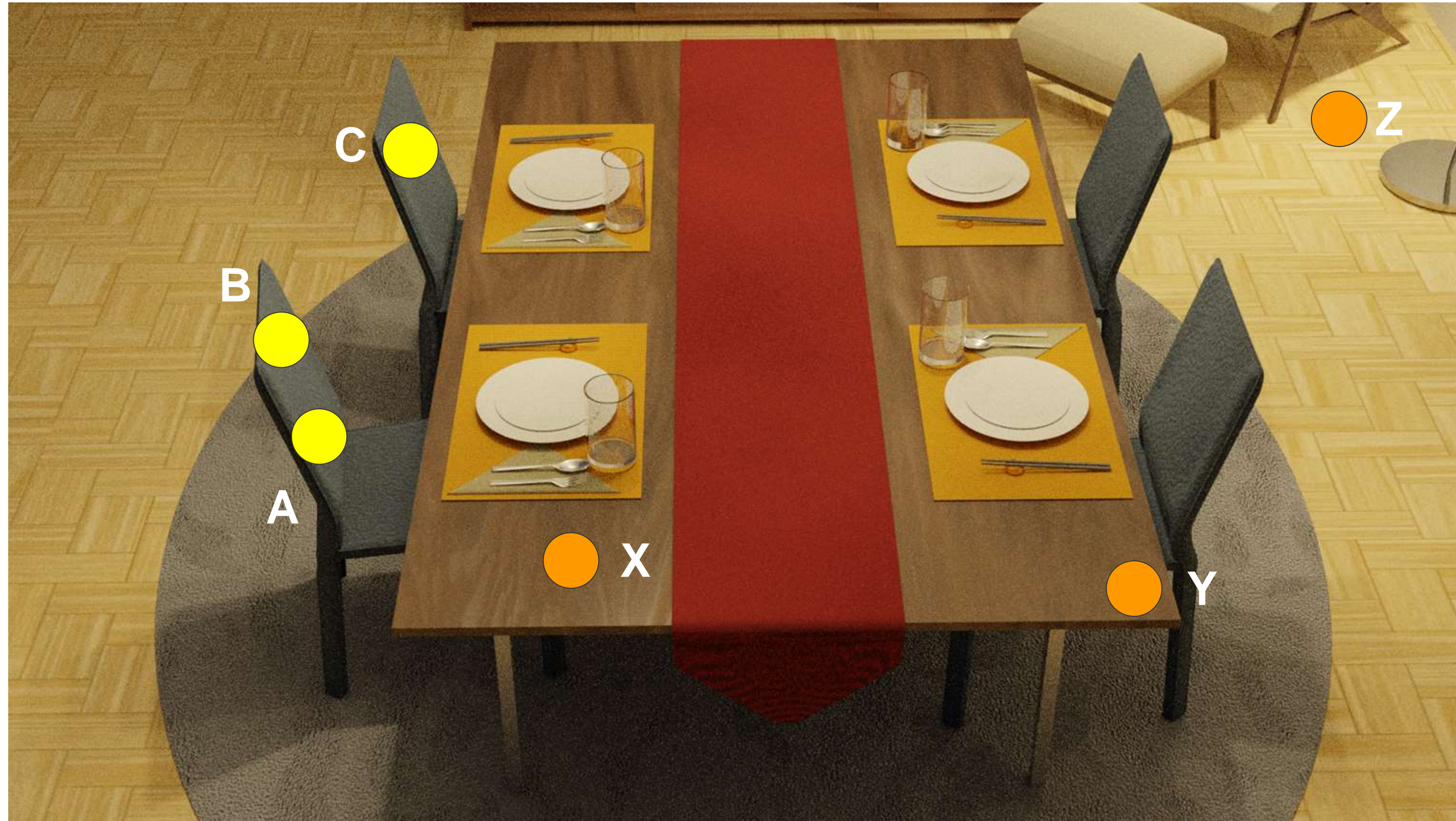


the table became longer



the table became darker

Mutual Information and 2nd Order Relationships



A is more correlated with B than with C

$$I(A, B) > I(A, C)$$

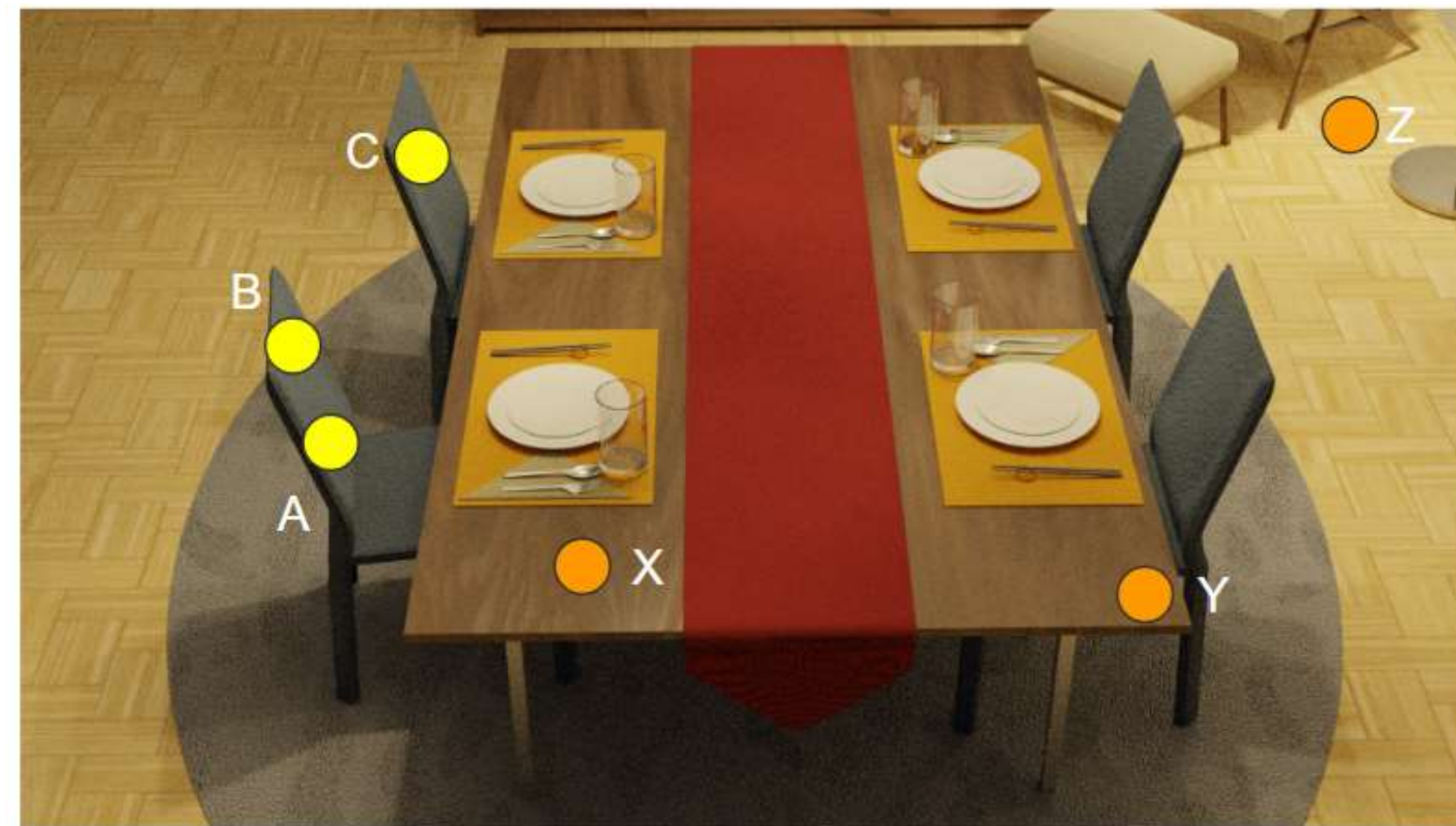
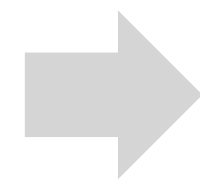
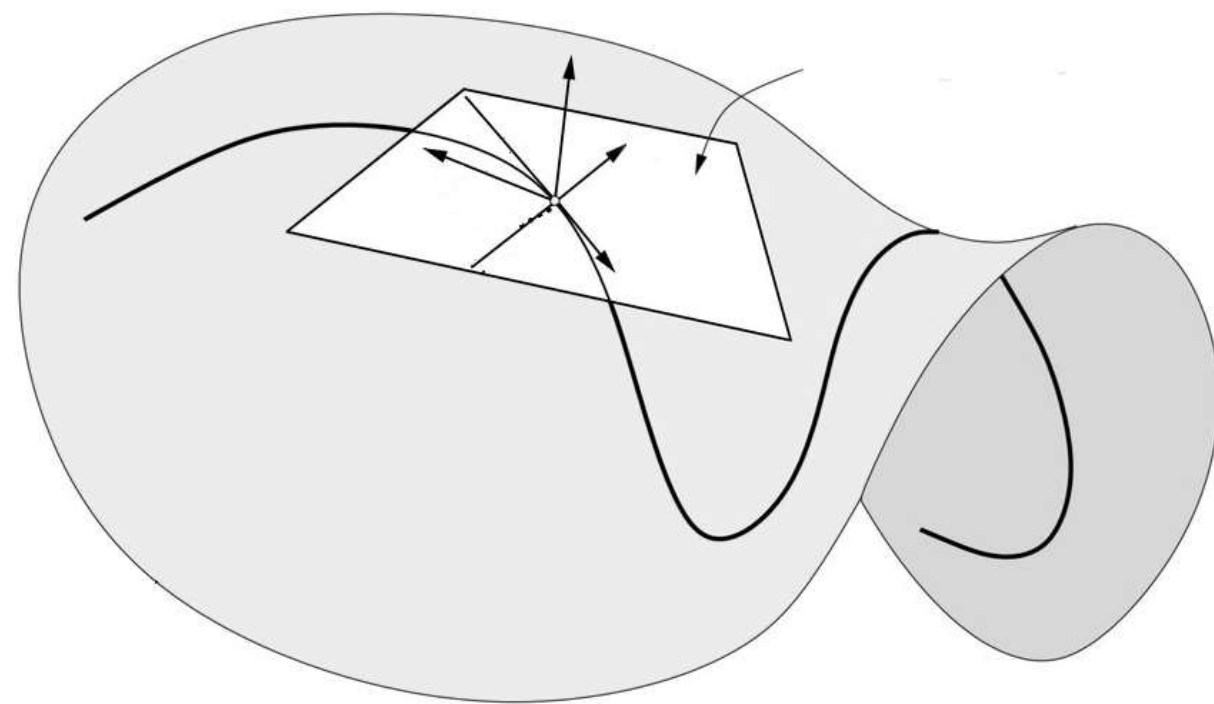
X is more correlated with Y than with Z

$$I(X, Y) > I(X, Z)$$

Shaping Neural Representations

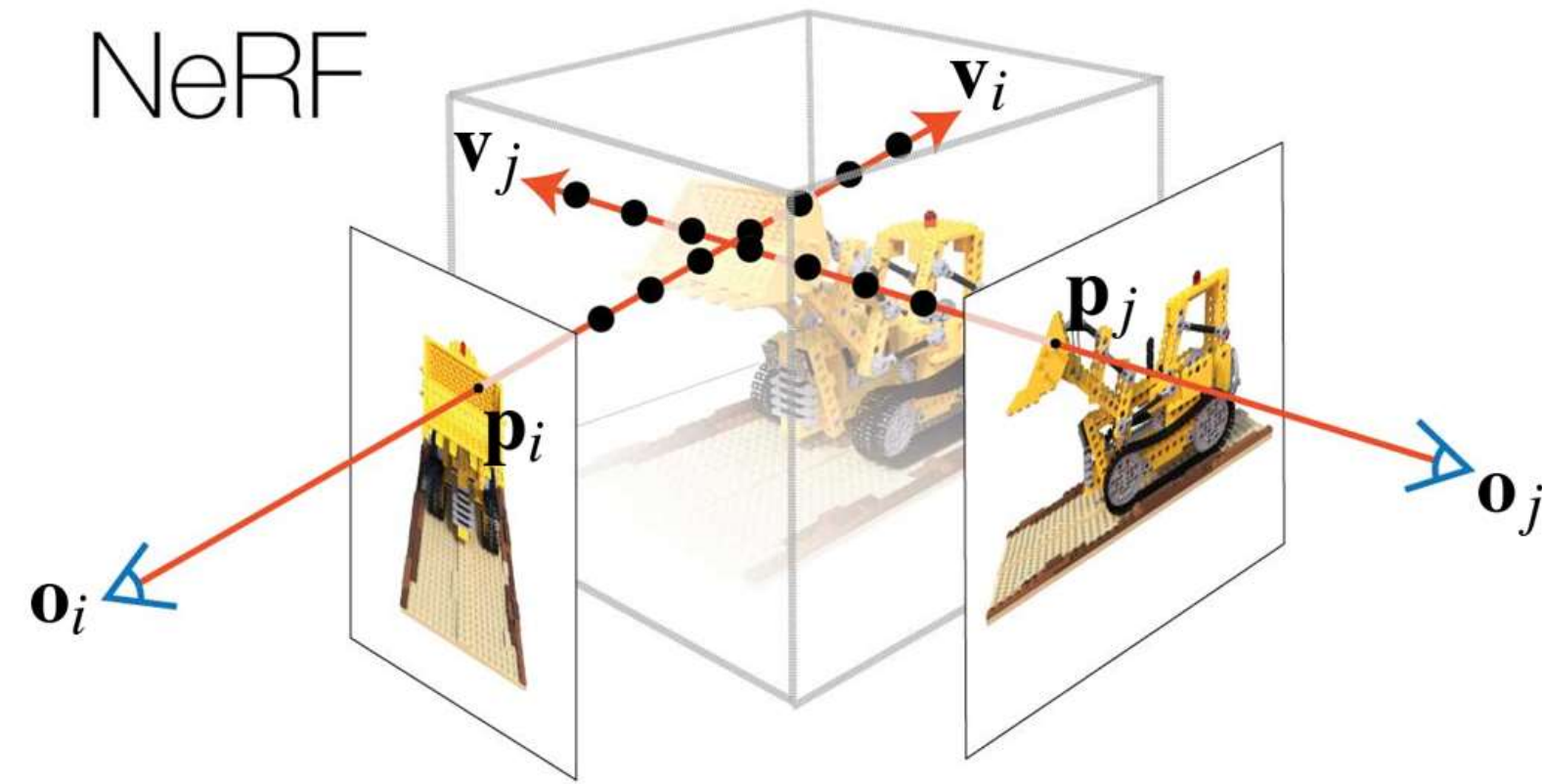
Can we shape NeRFs to better reflect mutual correlations in the scene?

The scene tangent space



$$\begin{aligned} \mathbb{I}(A,B) &> \mathbb{I}(A,C) \\ \mathbb{I}(X,Y) &> \mathbb{I}(X,Z) \end{aligned}$$

Mutual Information via NeRF Gradients



$$I(p_i) = \Phi(\mathbf{o}_i, \mathbf{v}_i; \theta)$$

$$I(p_j) = \Phi(\mathbf{o}_j, \mathbf{v}_j; \theta)$$

$$\hat{I}(p_i) = \Phi(\mathbf{o}_i, \mathbf{v}_i; \theta^D + \mathbf{n})$$

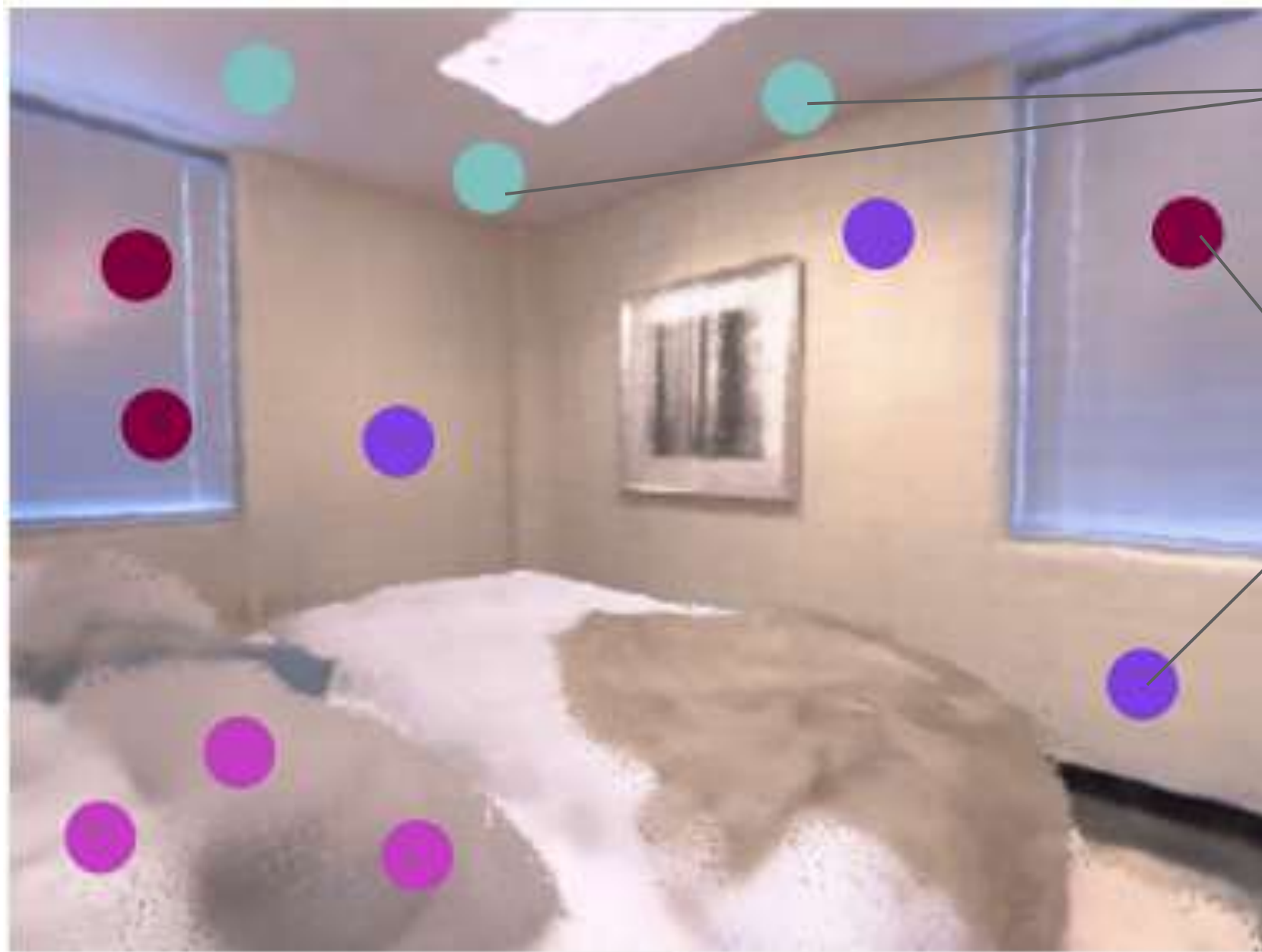
$$\hat{I}(p_j) = \Phi(\mathbf{o}_j, \mathbf{v}_j; \theta^D + \mathbf{n})$$

Mutual information \mathbb{I}

$$\mathbb{I}(\hat{I}(p_i), \hat{I}(p_j)) \approx \left| \cos \left(\frac{\partial \Phi_i}{\partial \theta^D}, \frac{\partial \Phi_j}{\partial \theta^D} \right) \right|$$

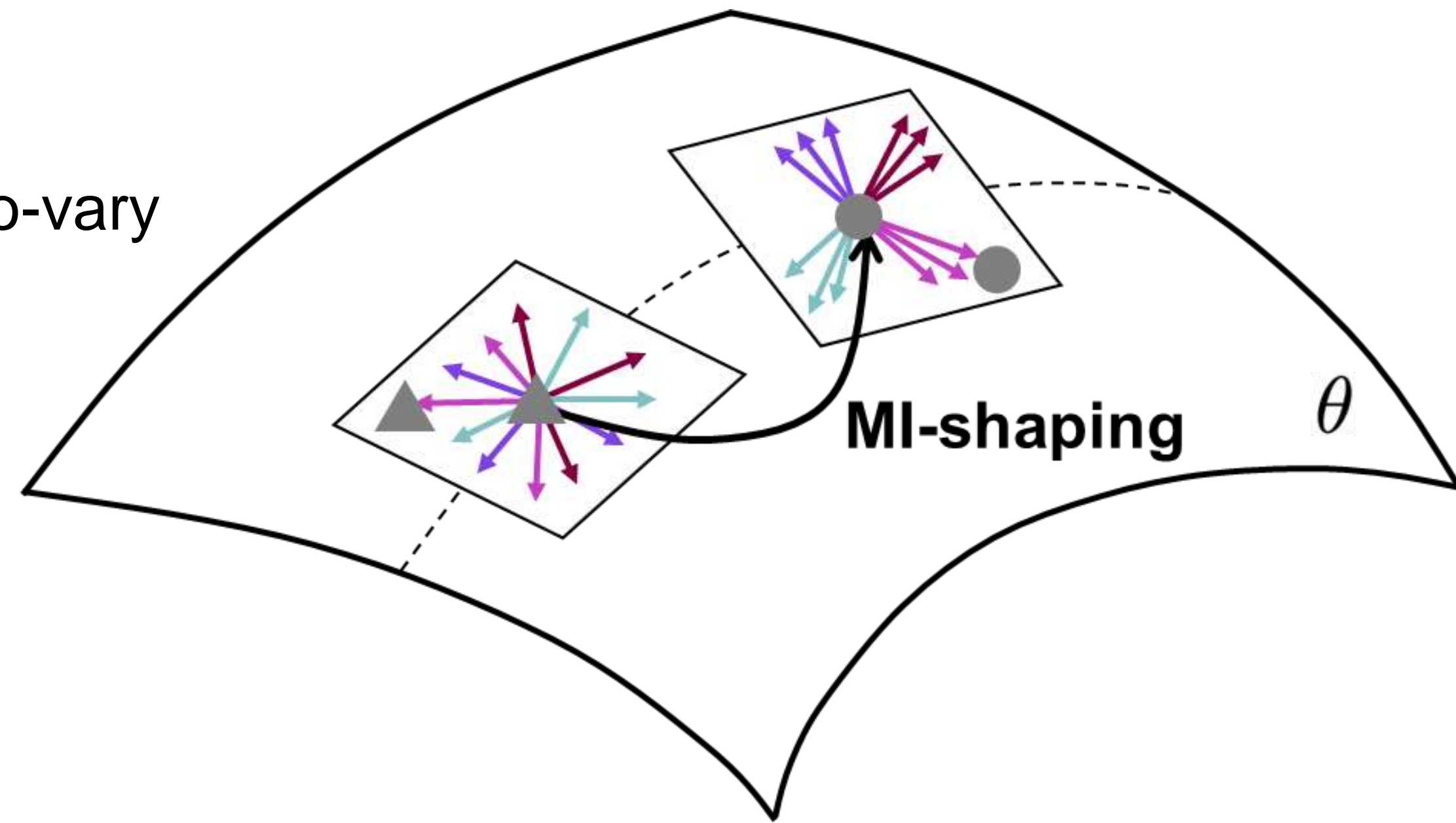
Inter-pixel correlations are captured by cosine similarity of the NeRF Jacobians

Setting up Semantic “Neuronal Resonances” via Aligning Gradients



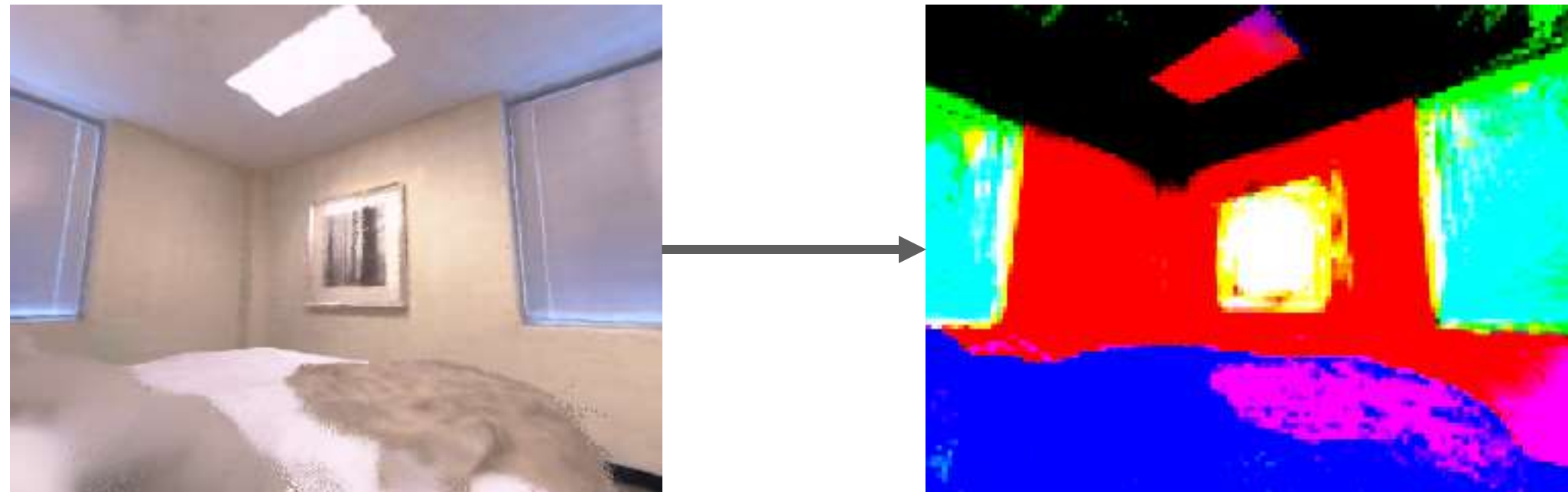
These pixels should co-vary

But these should not



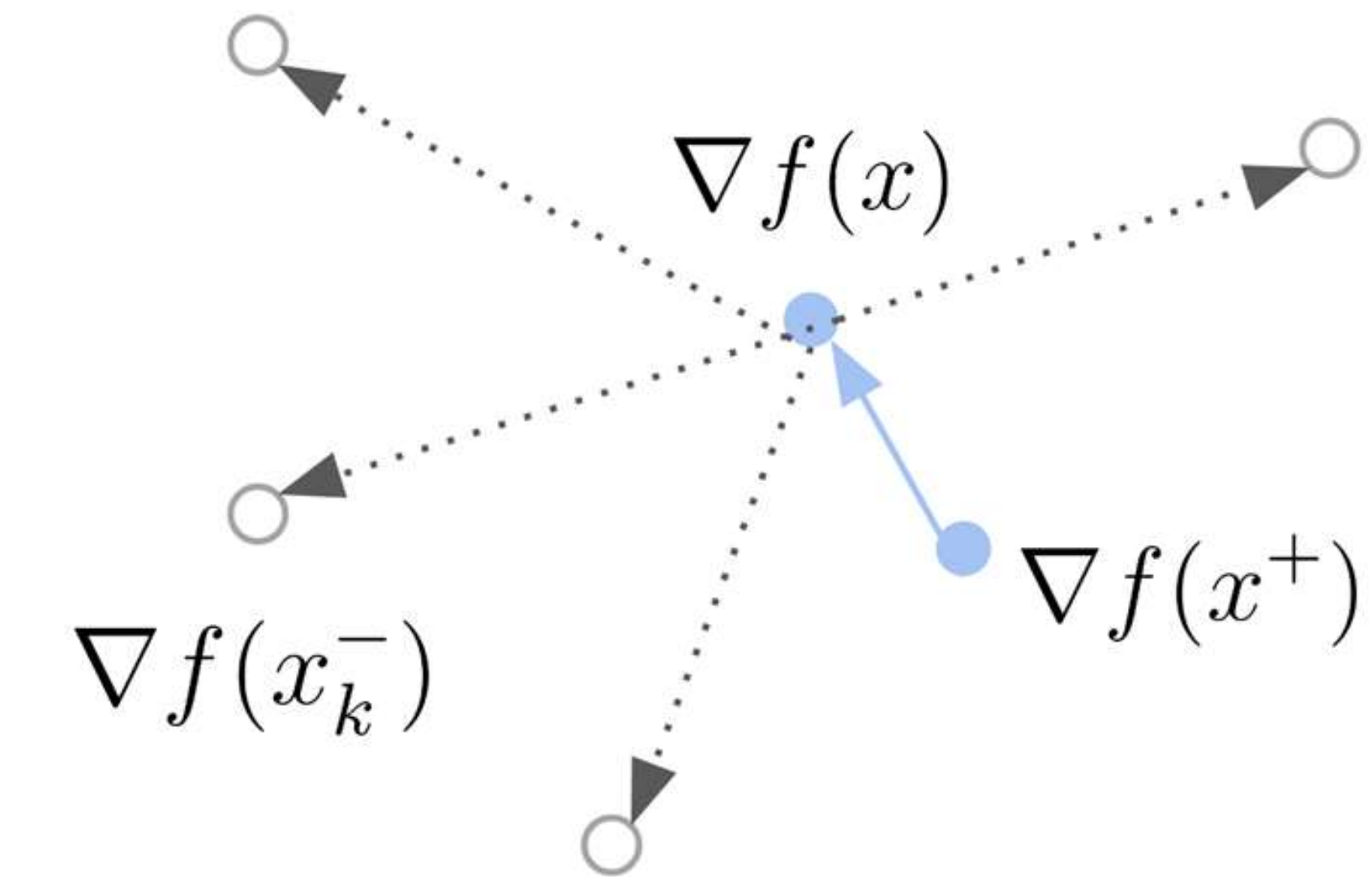
Shaping co-aligns gradients of correlated points (here points of the same semantic class)

NeRF MLP Shaping via Mutual Information Gradients



General purpose
image feature: DINO

Obtain some source of semantic affinity

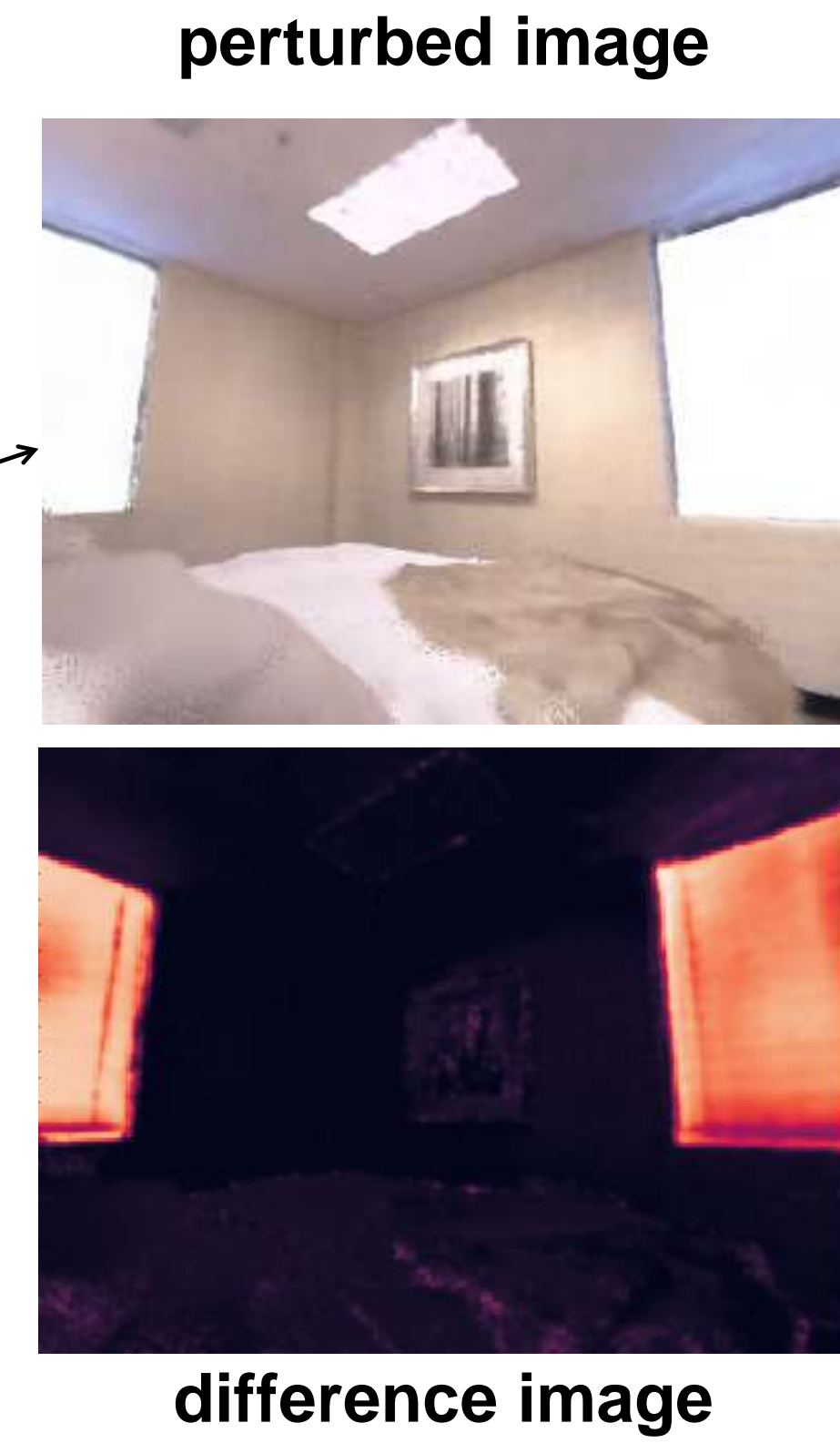


InfoNCE contrastive loss on
gradients + reconstruction loss

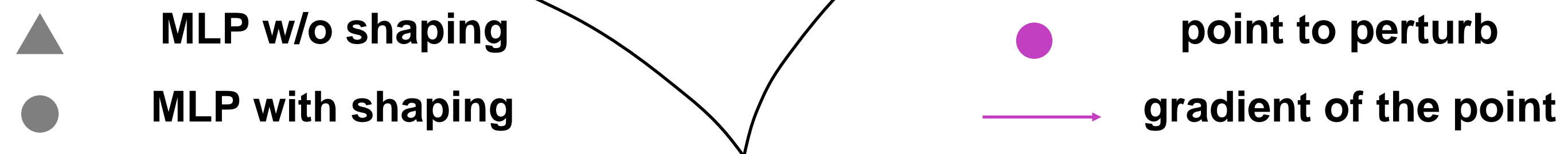
**Contrastive training
aligning gradients**

NeRF Shaping Causes Gradient Alignment

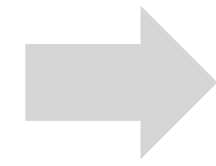
Before shaping



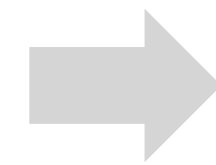
After shaping



Application: Editing Appearance

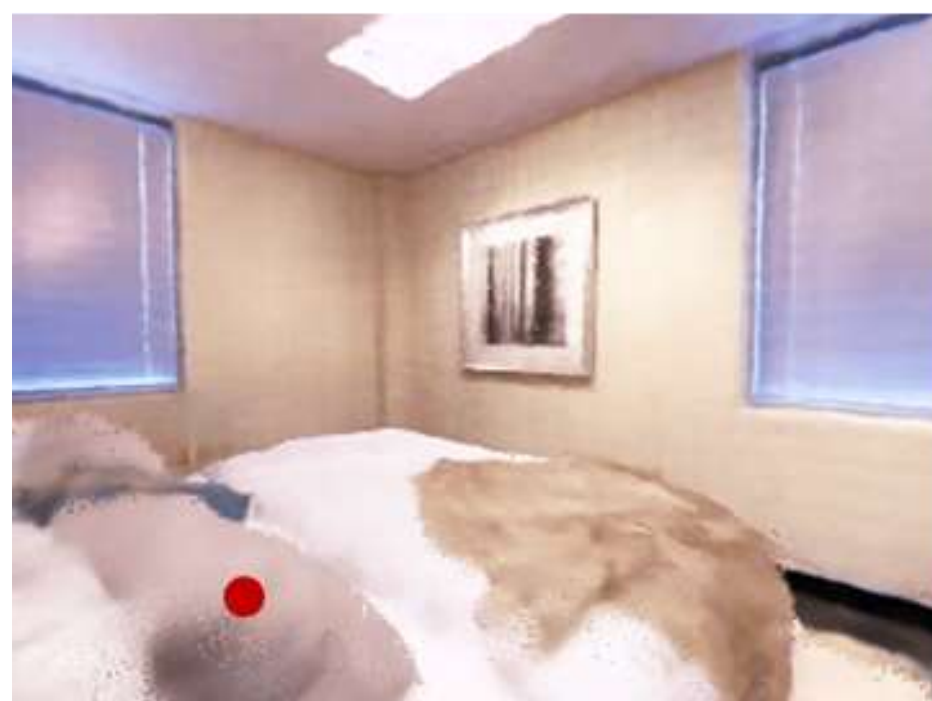


Application: Editing Appearance

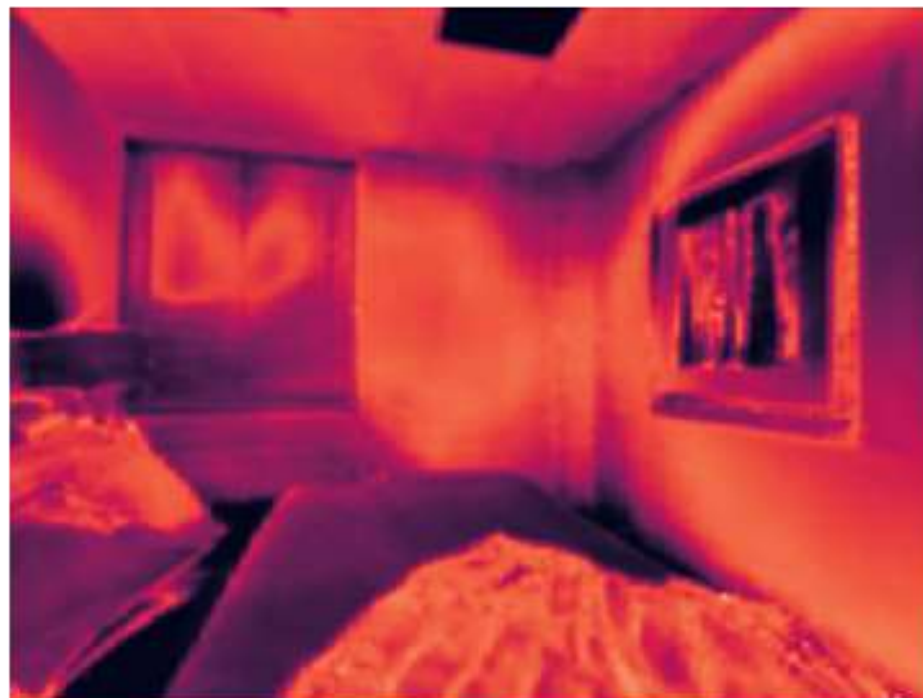


Application: Entity Selection

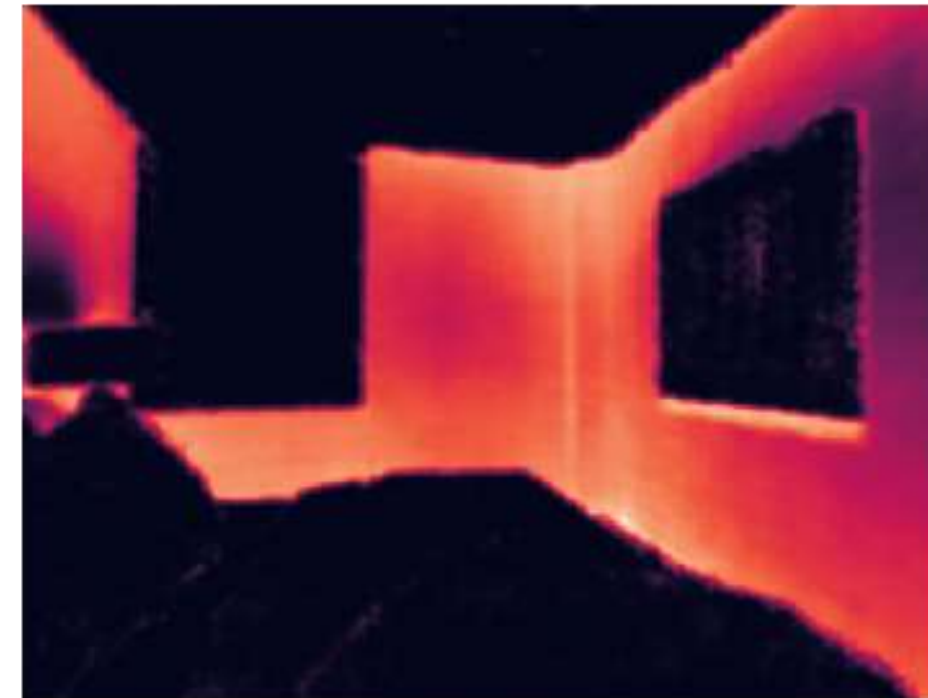
image



NeRF



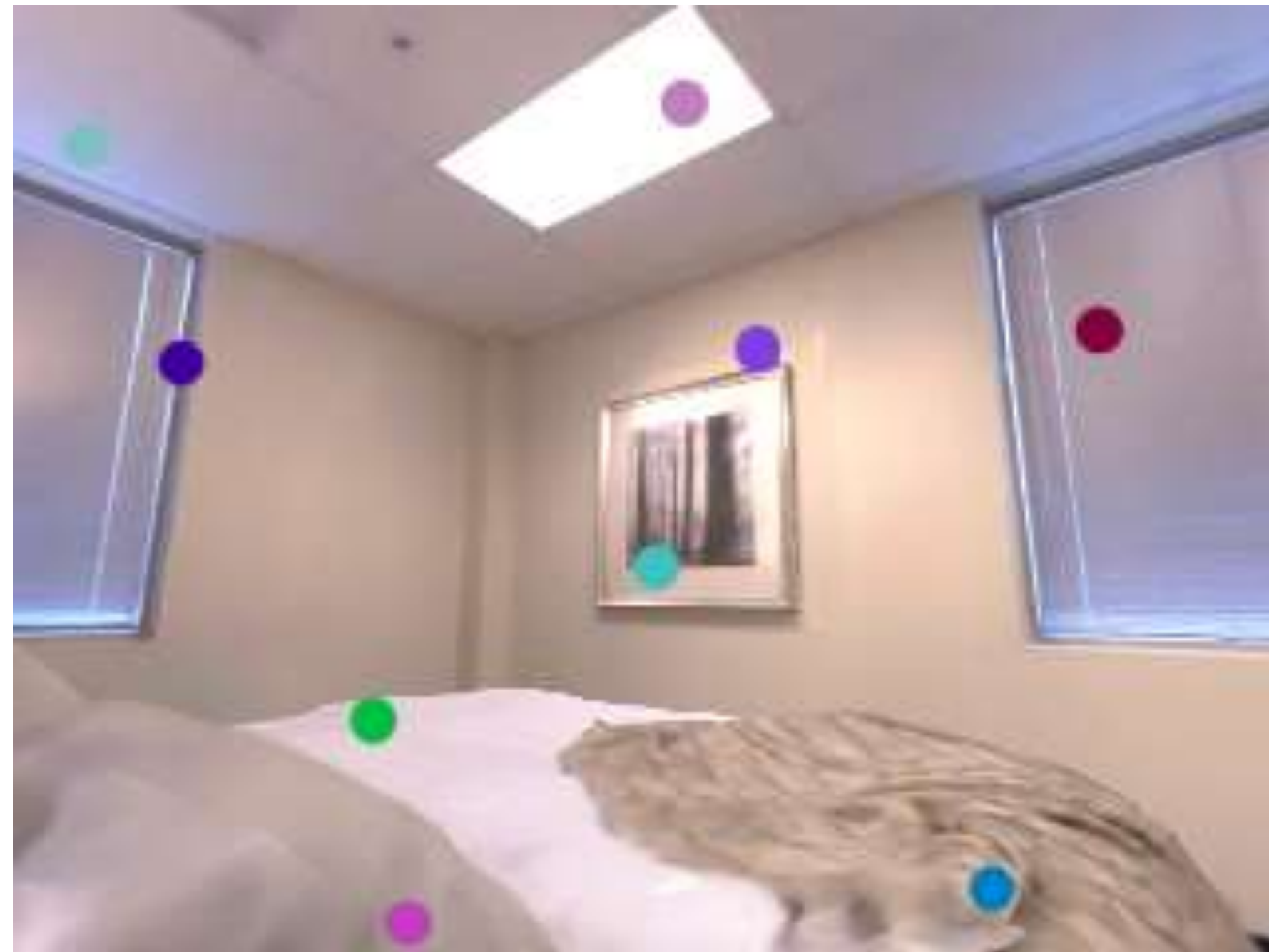
JacobiNeRF



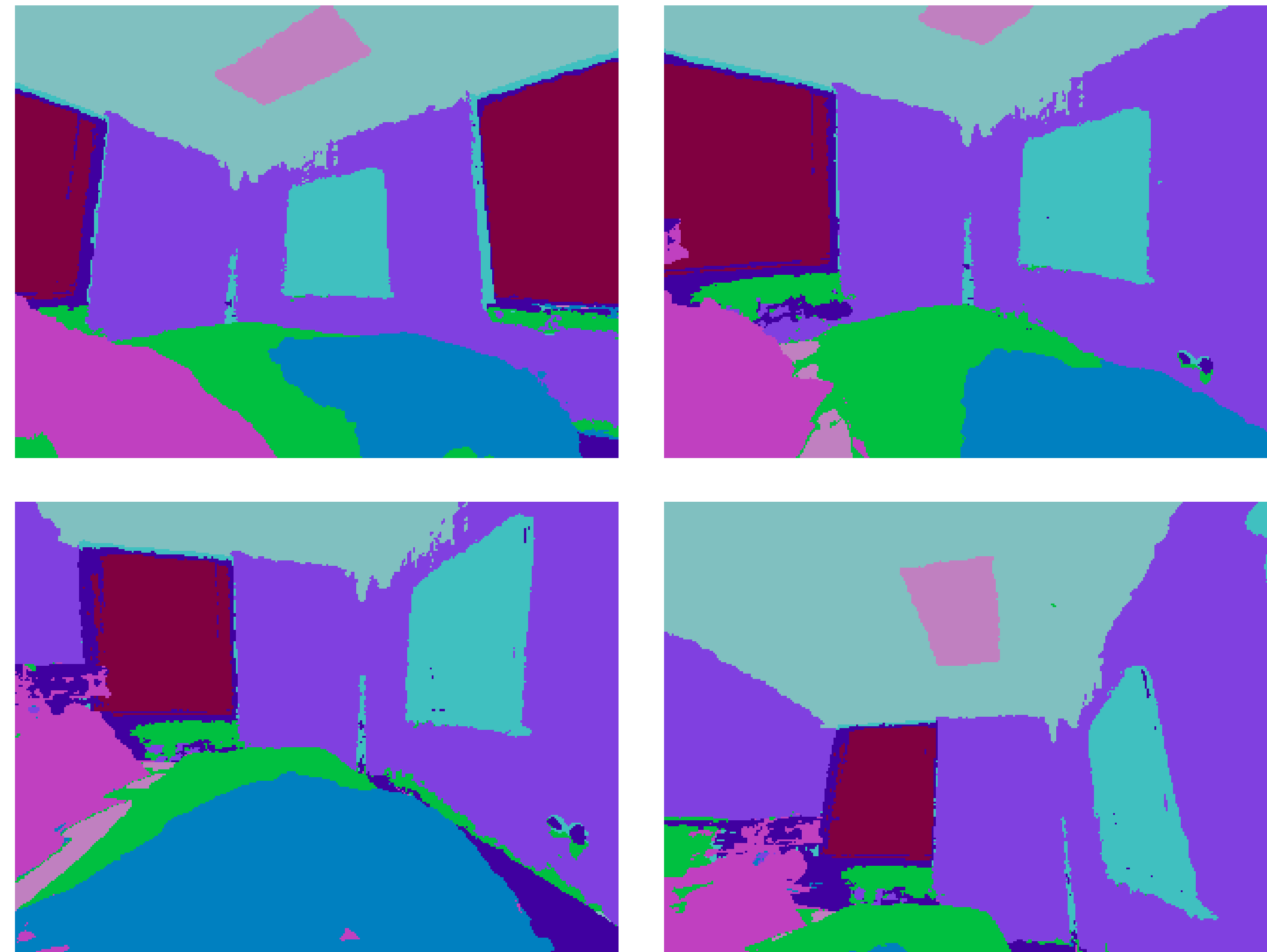
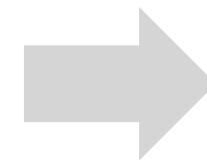
From a single point we can select an entire semantic entity.

Application: Label Propagation

Acquire dense labels of a scene given sparse annotations.



Label one pixel for each class from one view

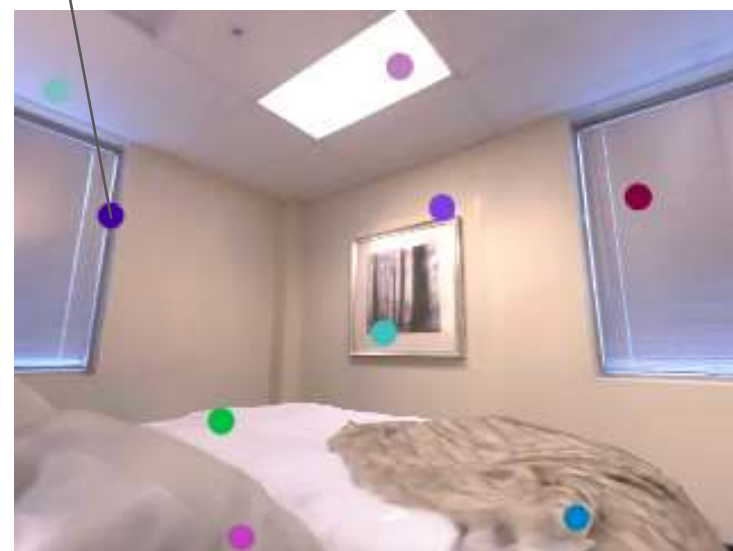


Dense label for any view

Propagation Through Resonances

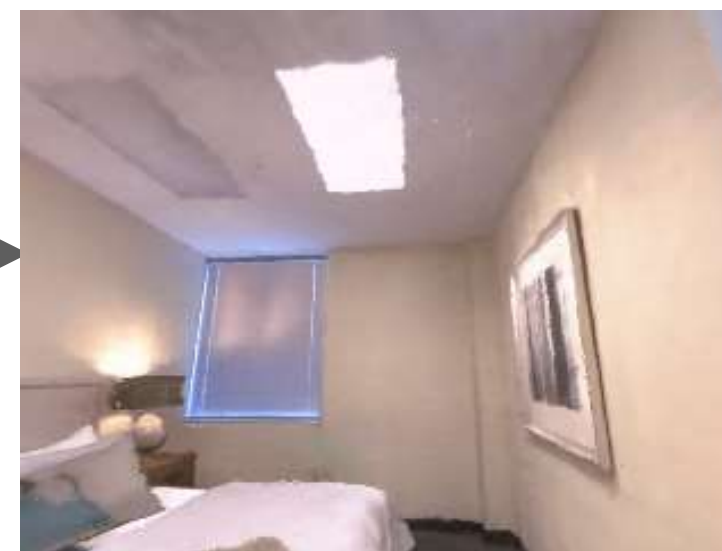
2D version (JacobiNeRF-2D)

Given m labels

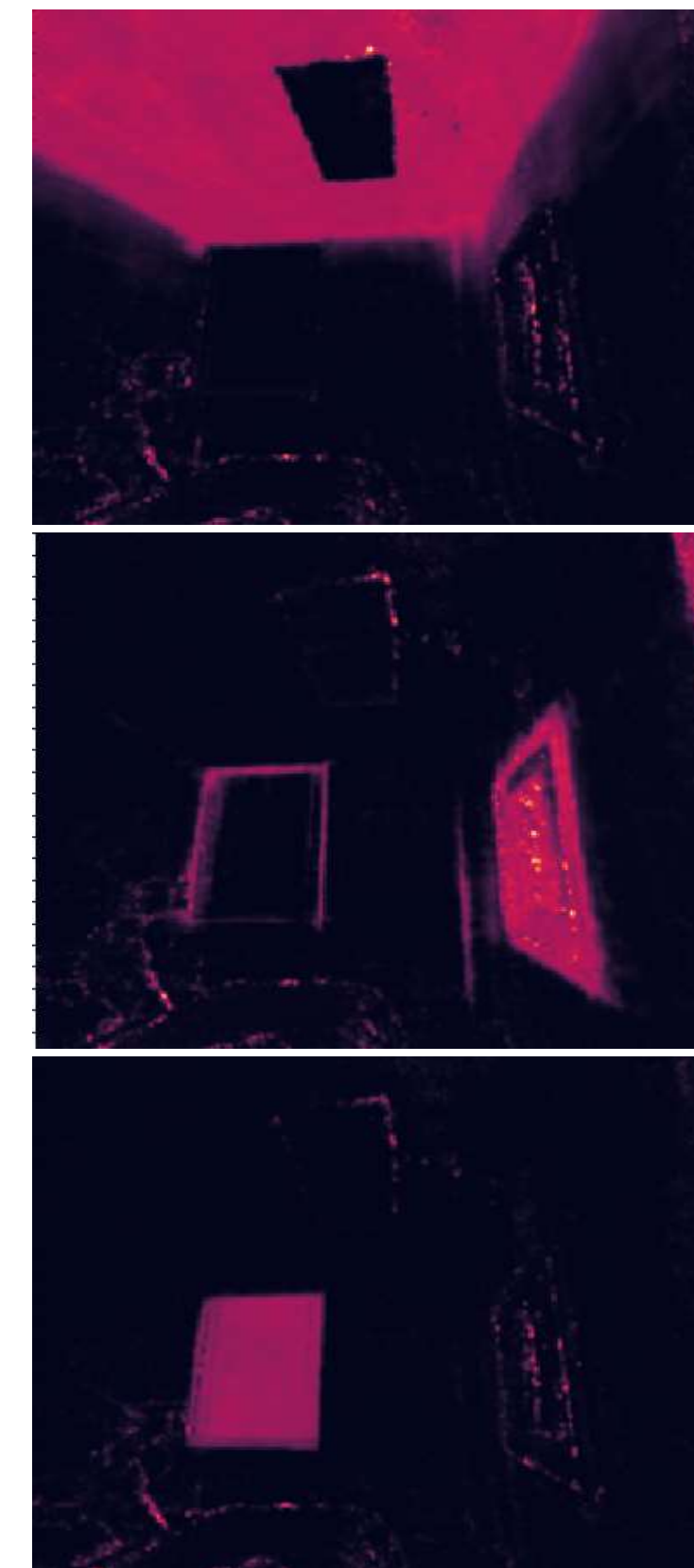


Source view

Perturb along
gradients



Target view



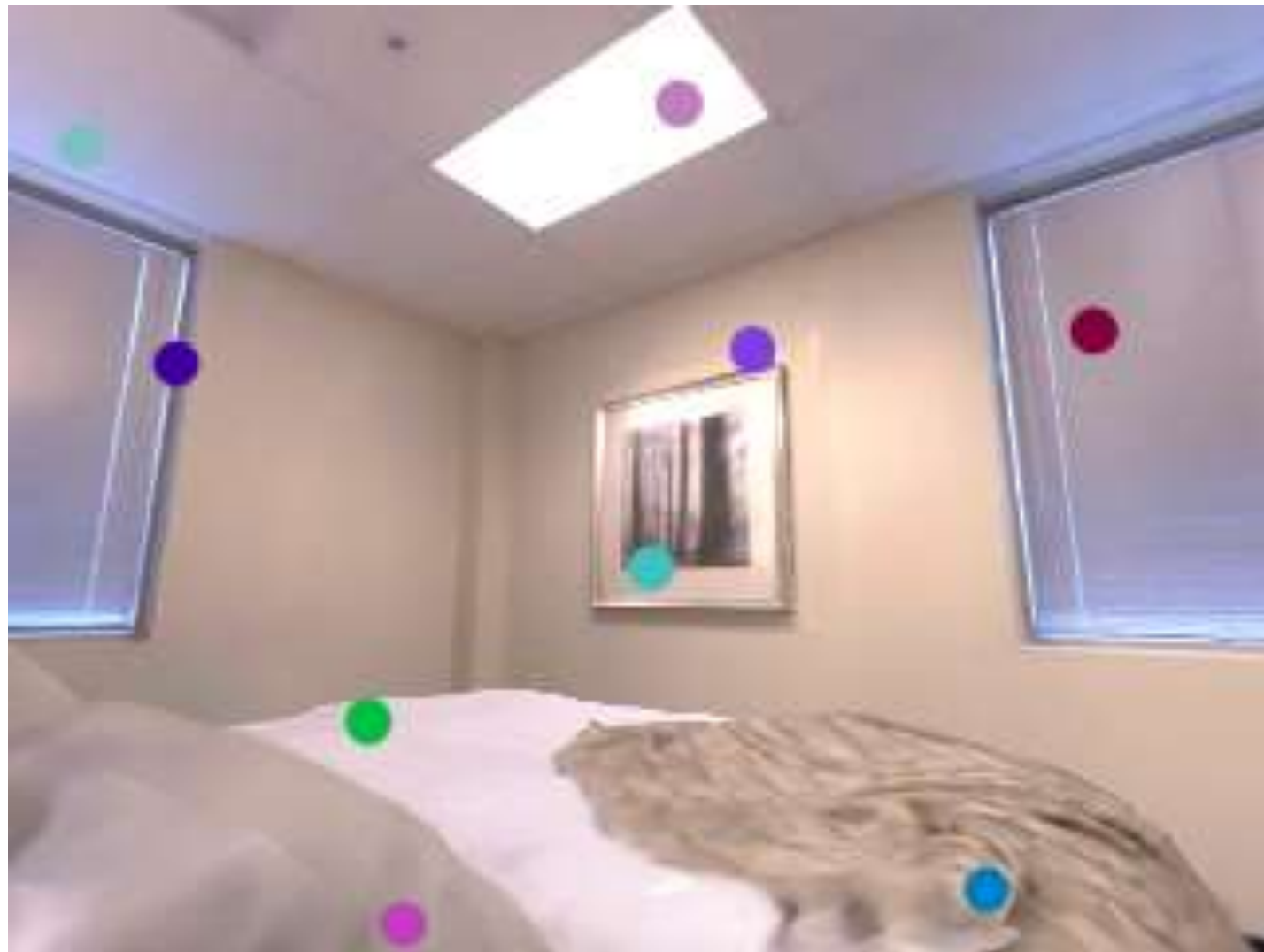
.....
m responses

argmax

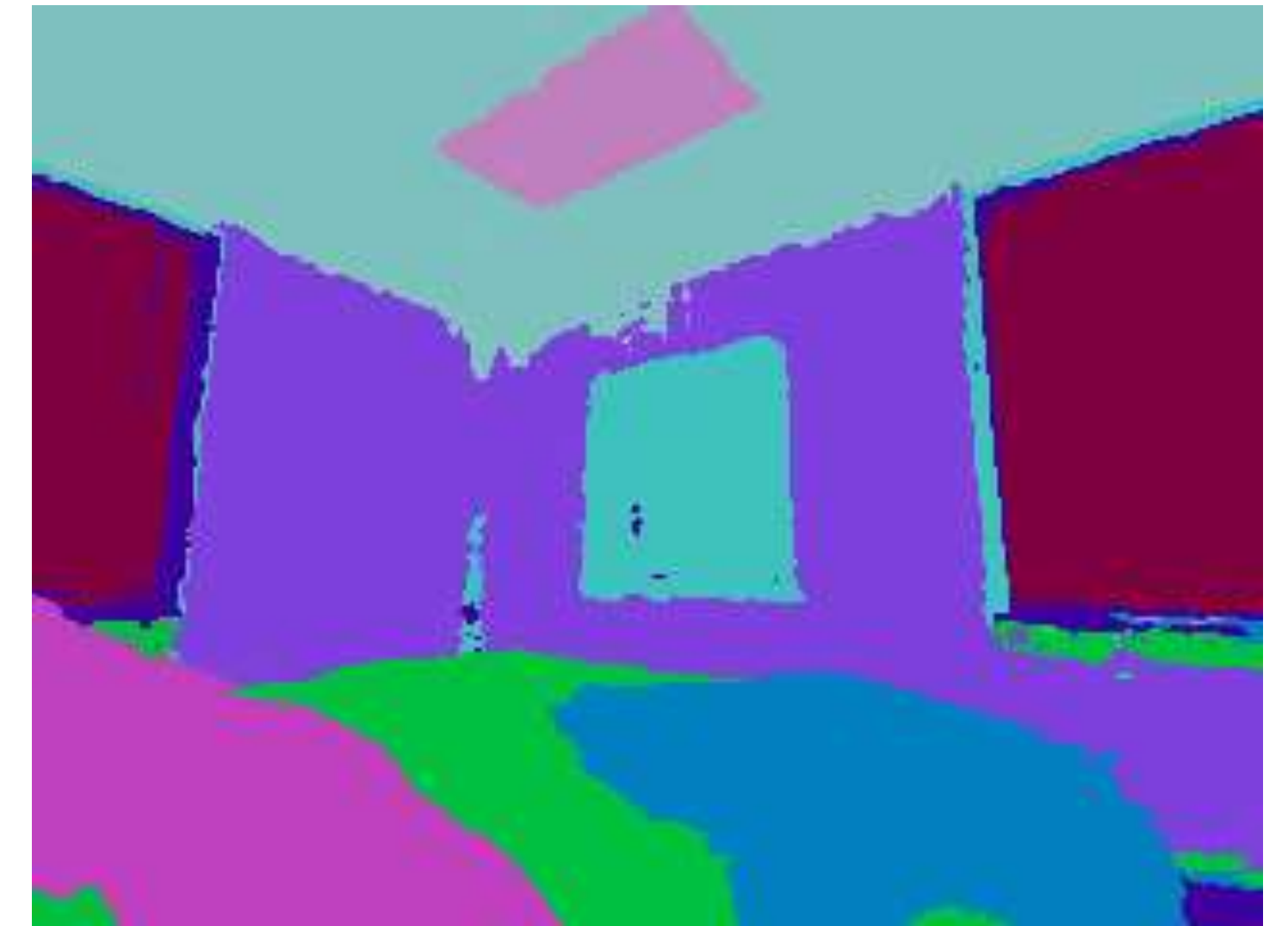


Label

Semantic Segmentation (**sparse** 1pix/class, Replica)

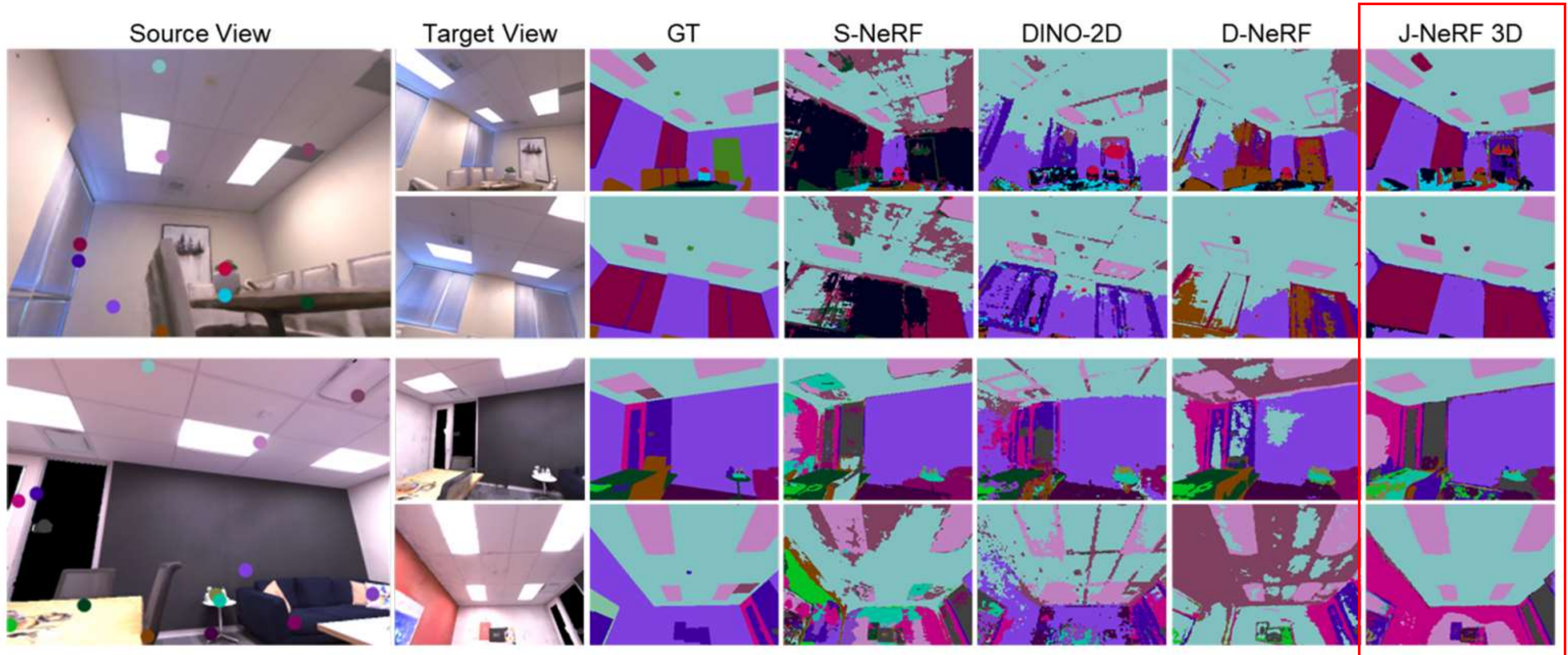


Given label



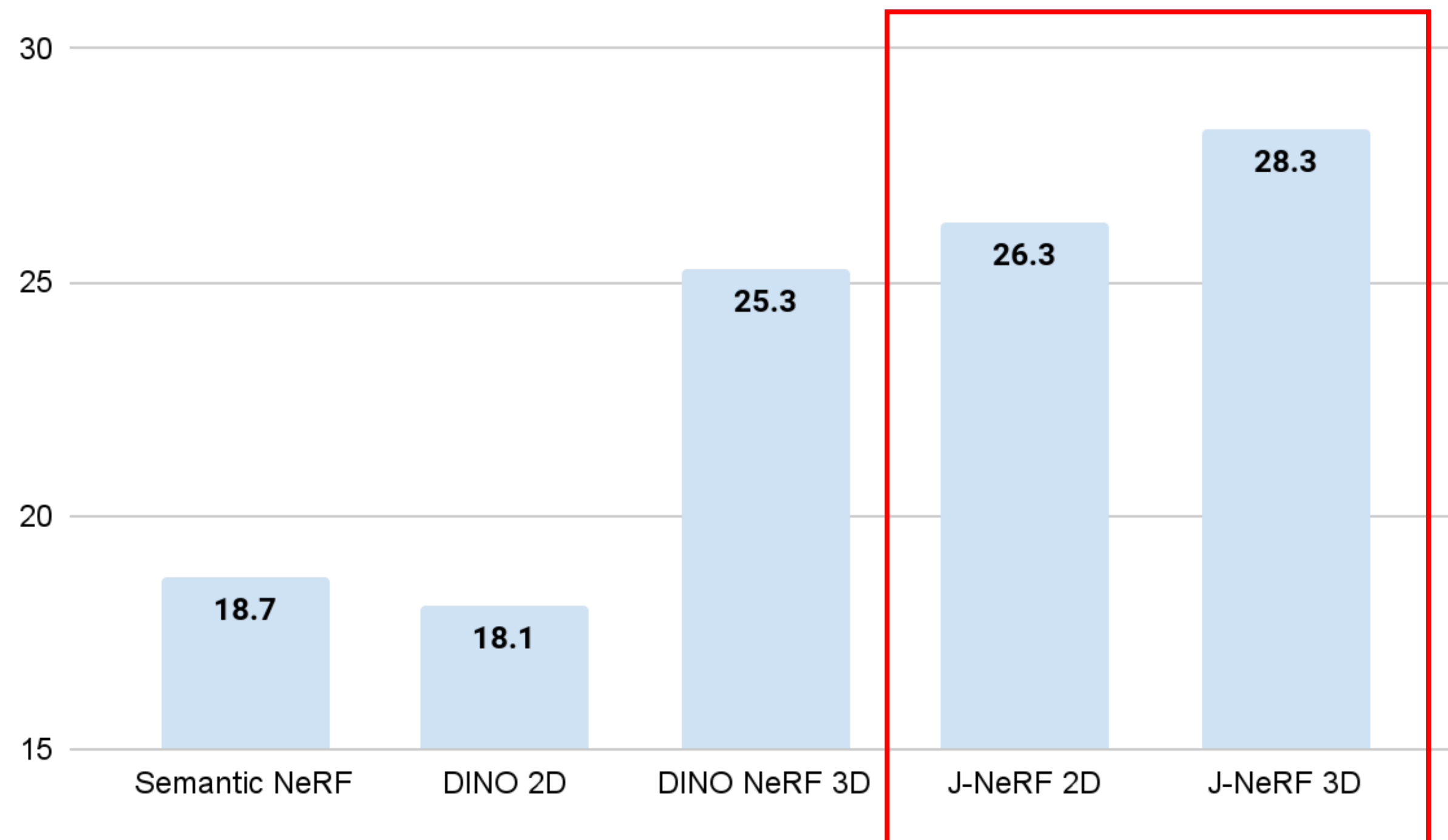
J-NeRF 3D

Semantic Segmentation (**sparse** 1pix/class, Replica)



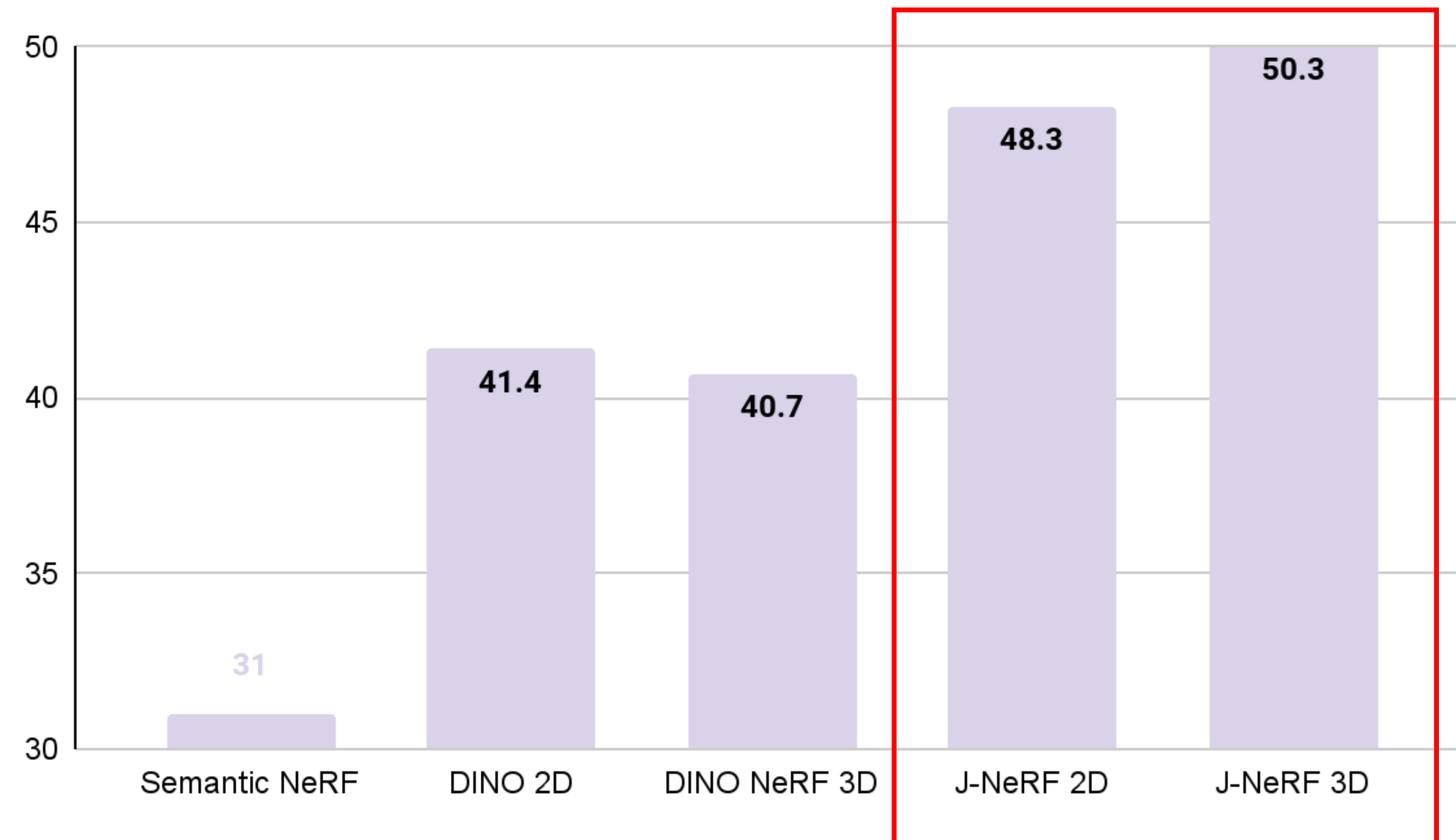
Semantic Segmentation (**sparse** 1pix/class, Replica)

1 pix/class 1 view



mIoU

1 pix/class 1 view



Acc

Average results on 7 scenes, 180 test views for each scene

Semantic Segmentation (**dense** 1view, Replica)

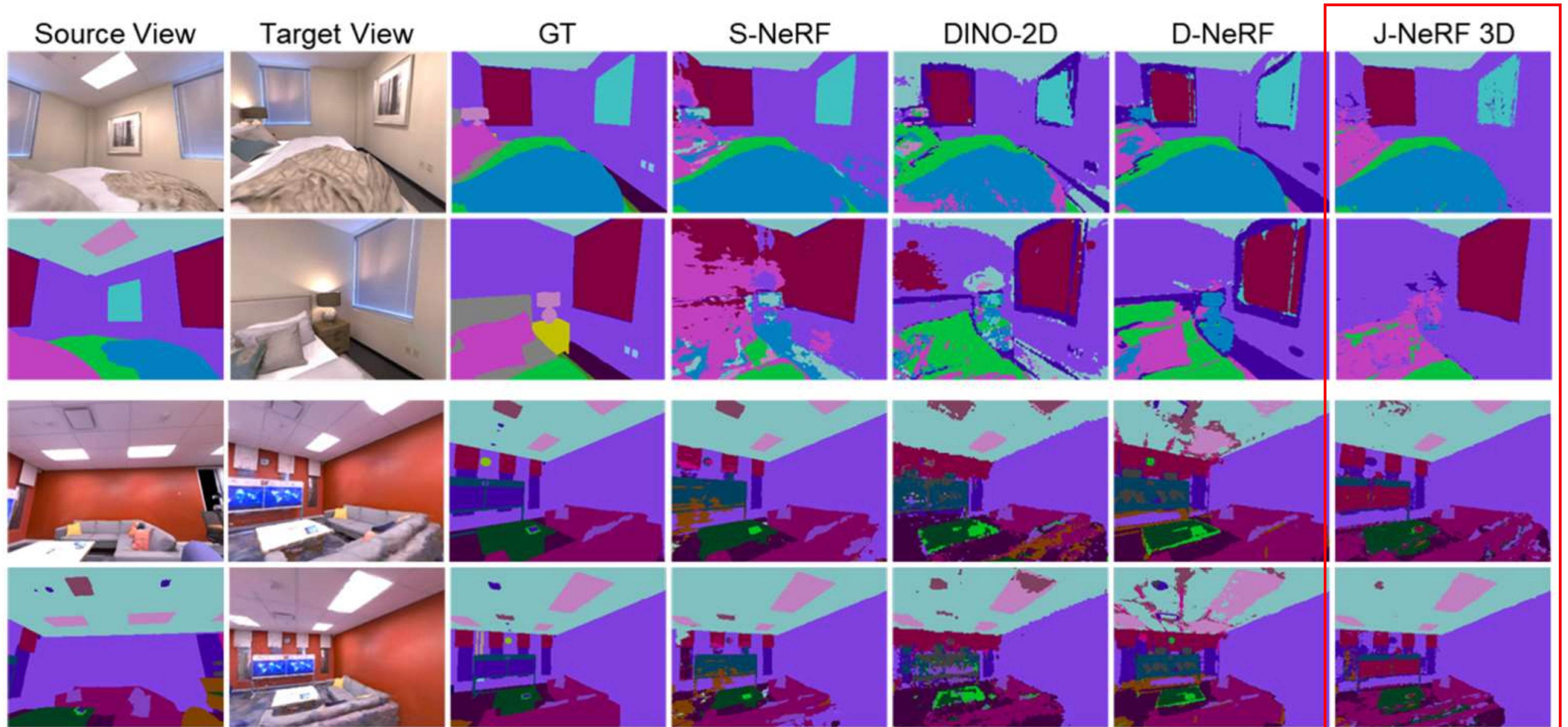


Given label



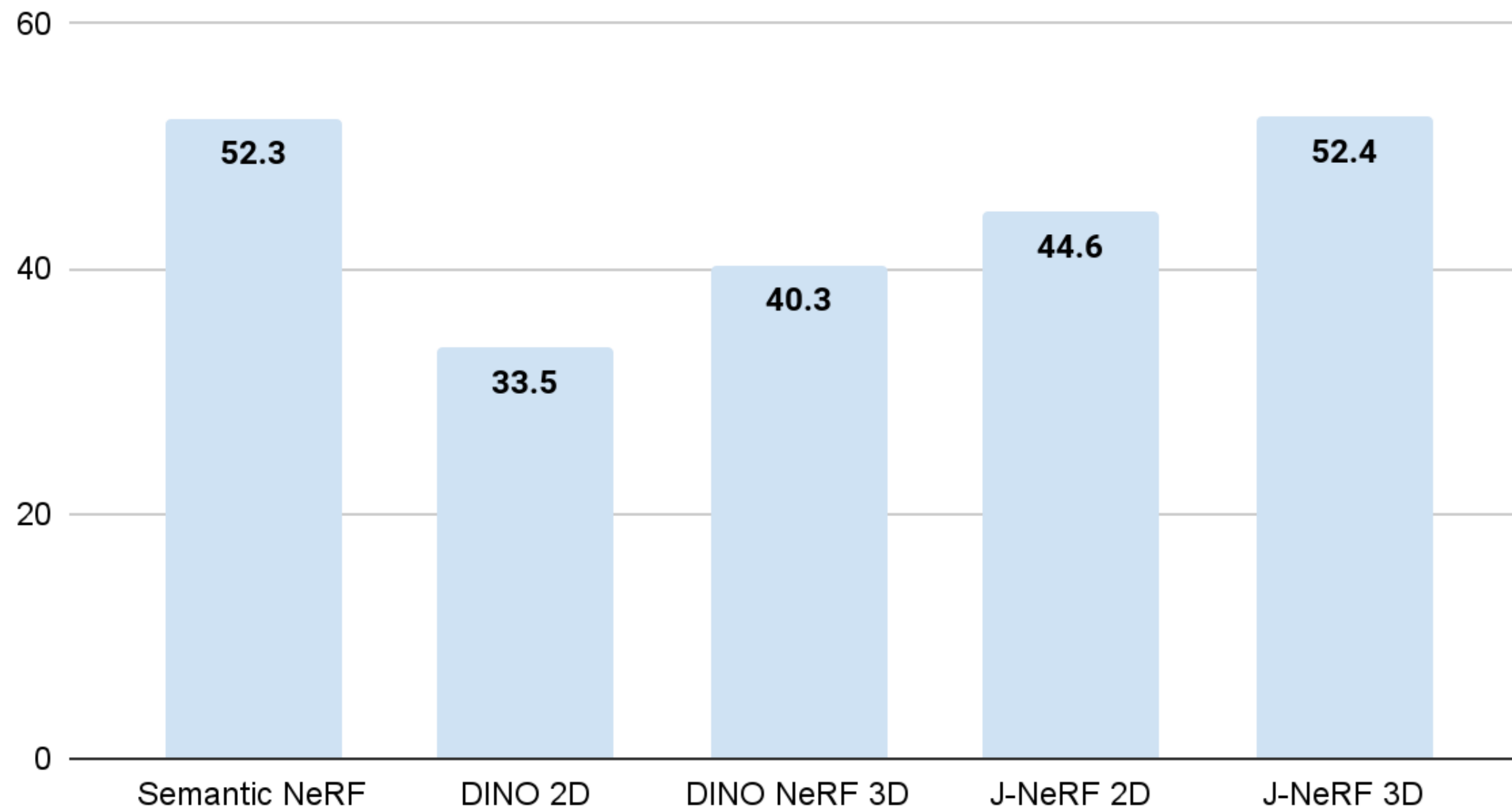
J-NeRF 3D

Semantic Segmentation (**dense** 1view, Replica)



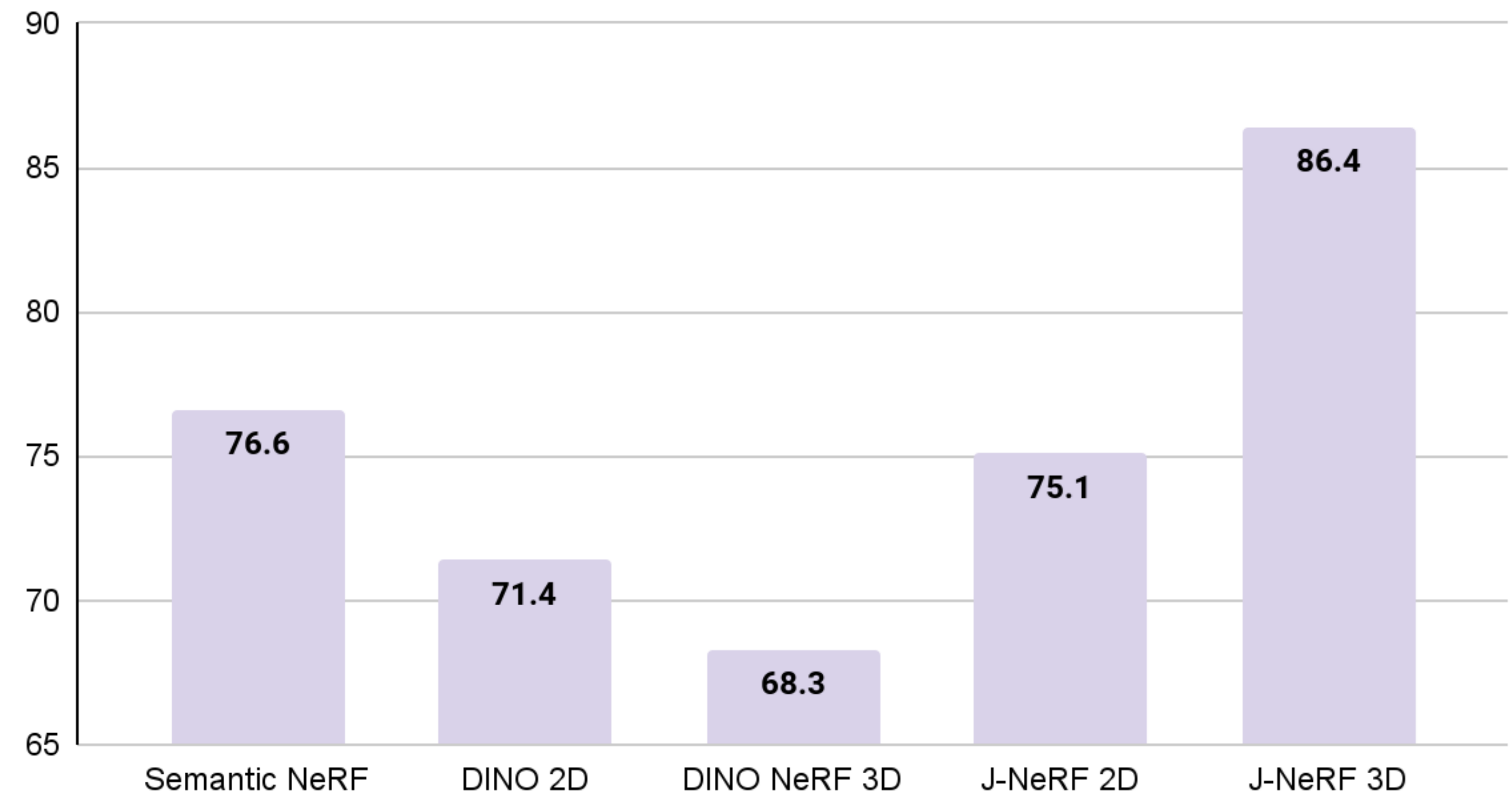
Semantic Segmentation (**dense** 1view, Replica)

Dense label 1 view



mIoU

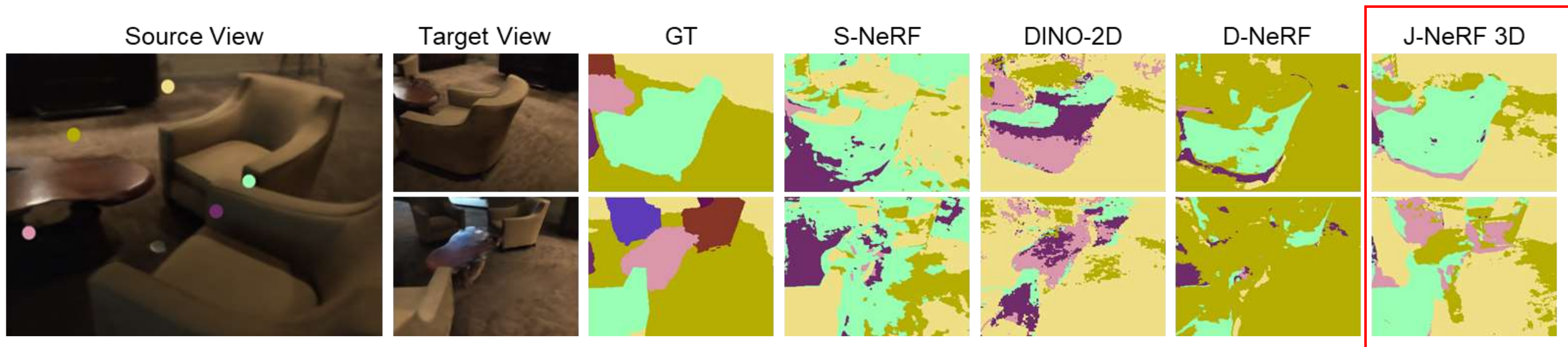
Dense label 1 view



Acc

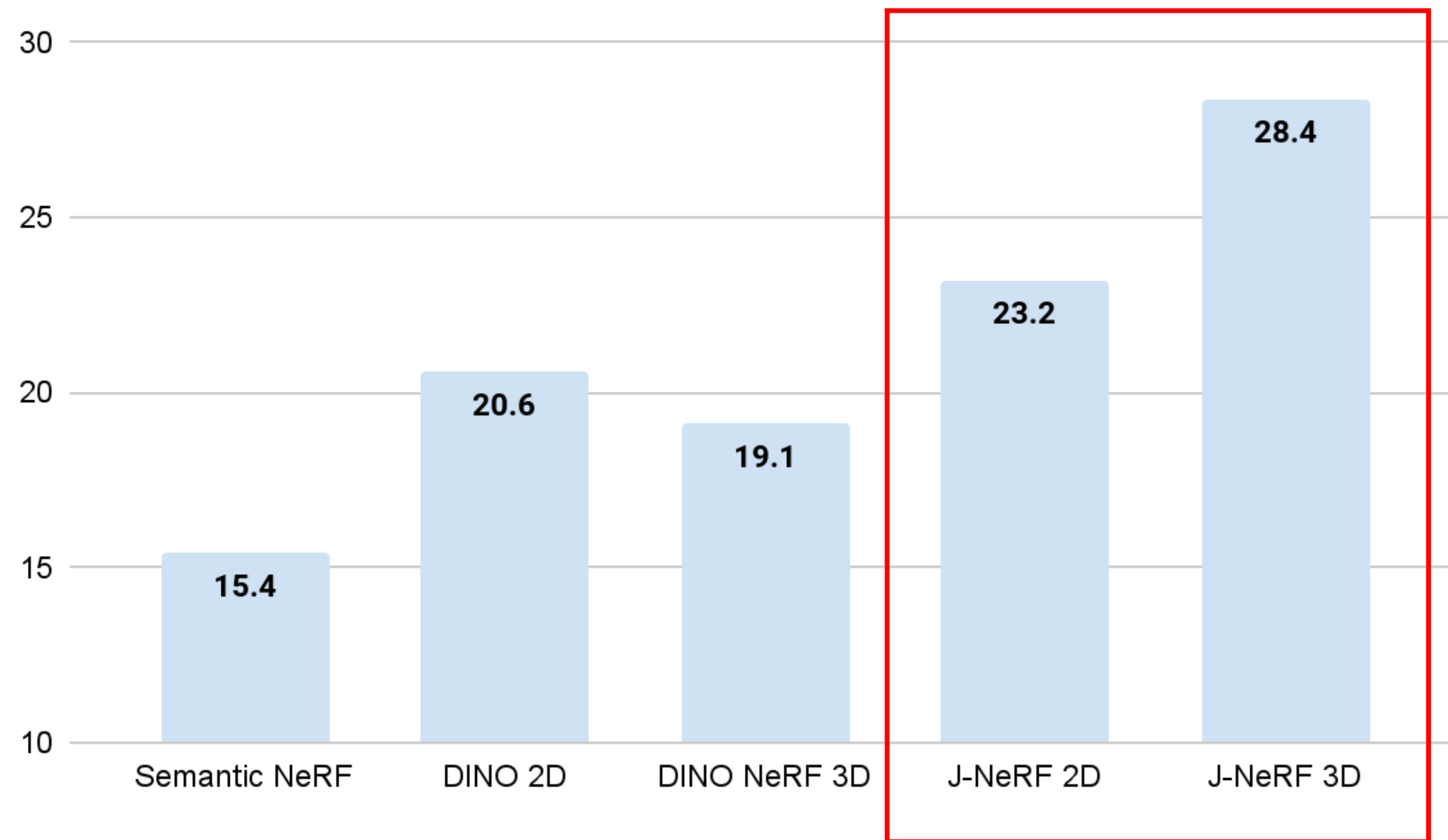
Average results on 7 scenes, 180 test views for each scene

Instance segmentation (**sparse**, 1pix/instance, ScanNet)



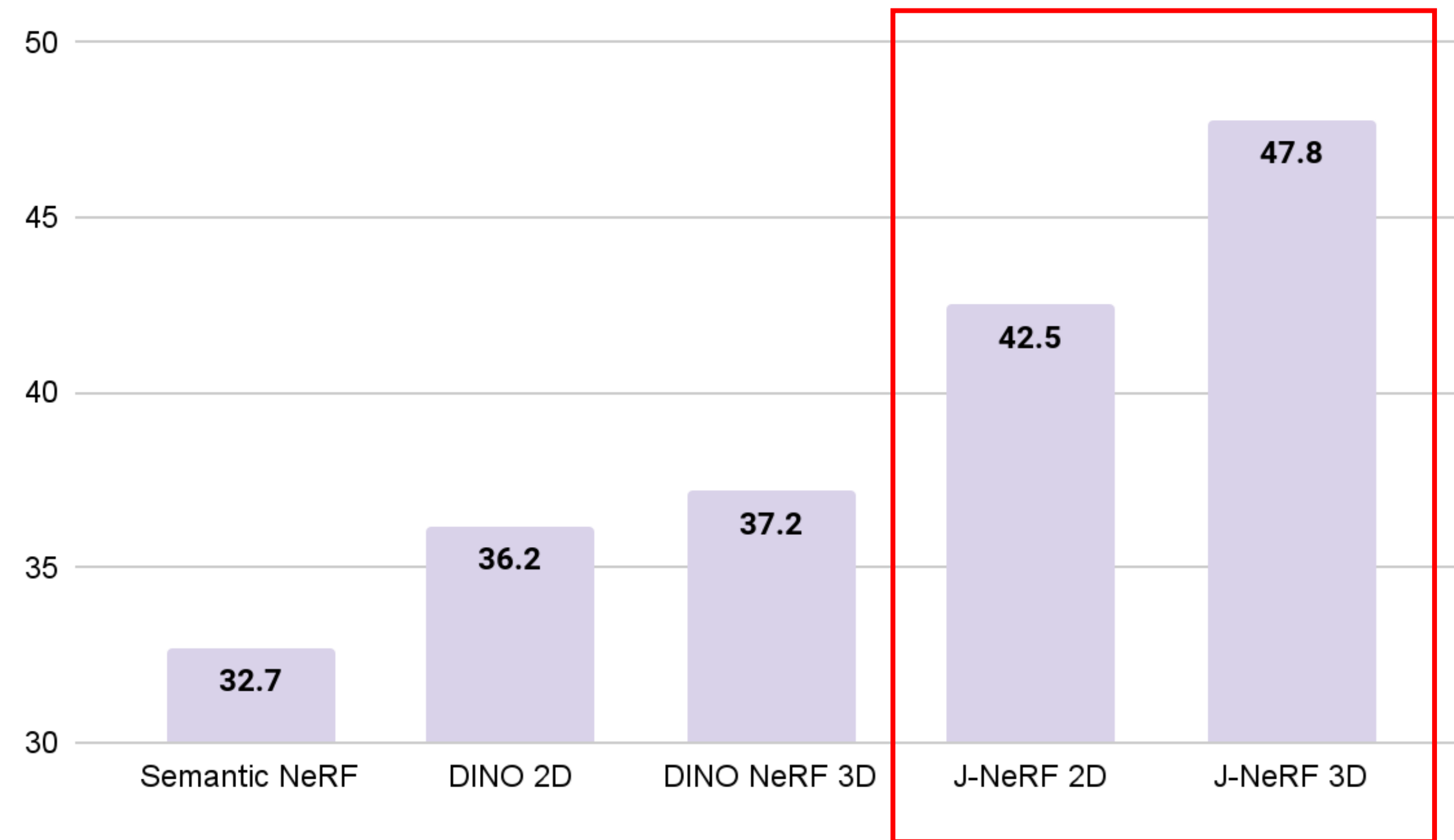
Instance segmentation (**sparse**, 1pix/instance, ScanNet)

1 pix/class 1 view



mIoU

1 pix/class 1 view

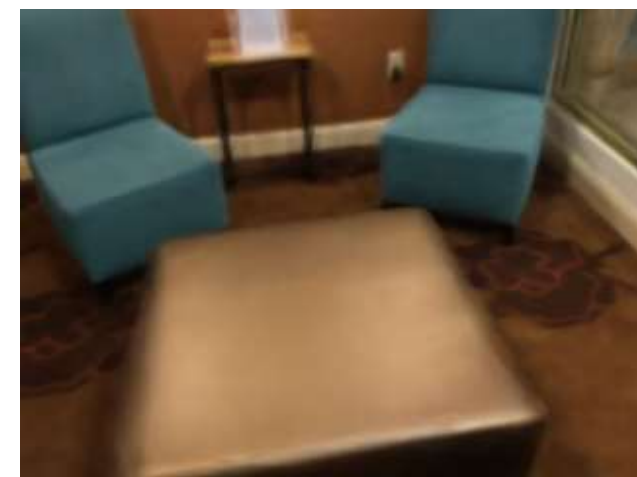


Acc

Average results on 4 scenes, ~180 test views for each scene

Instance segmentation (1 view, **dense**, ScanNet)

Source view Target view



GT



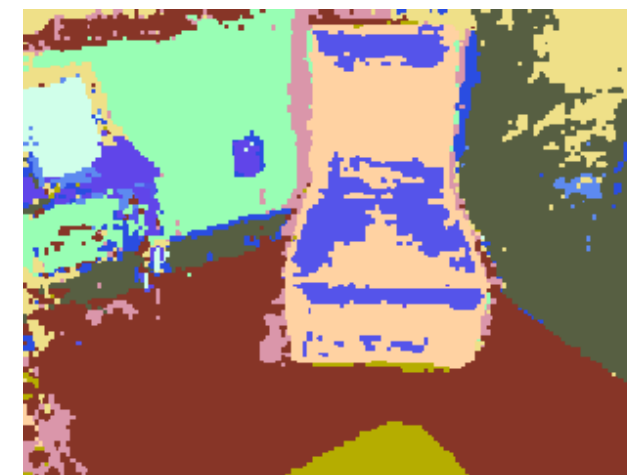
DINO-2D



D-NeRF

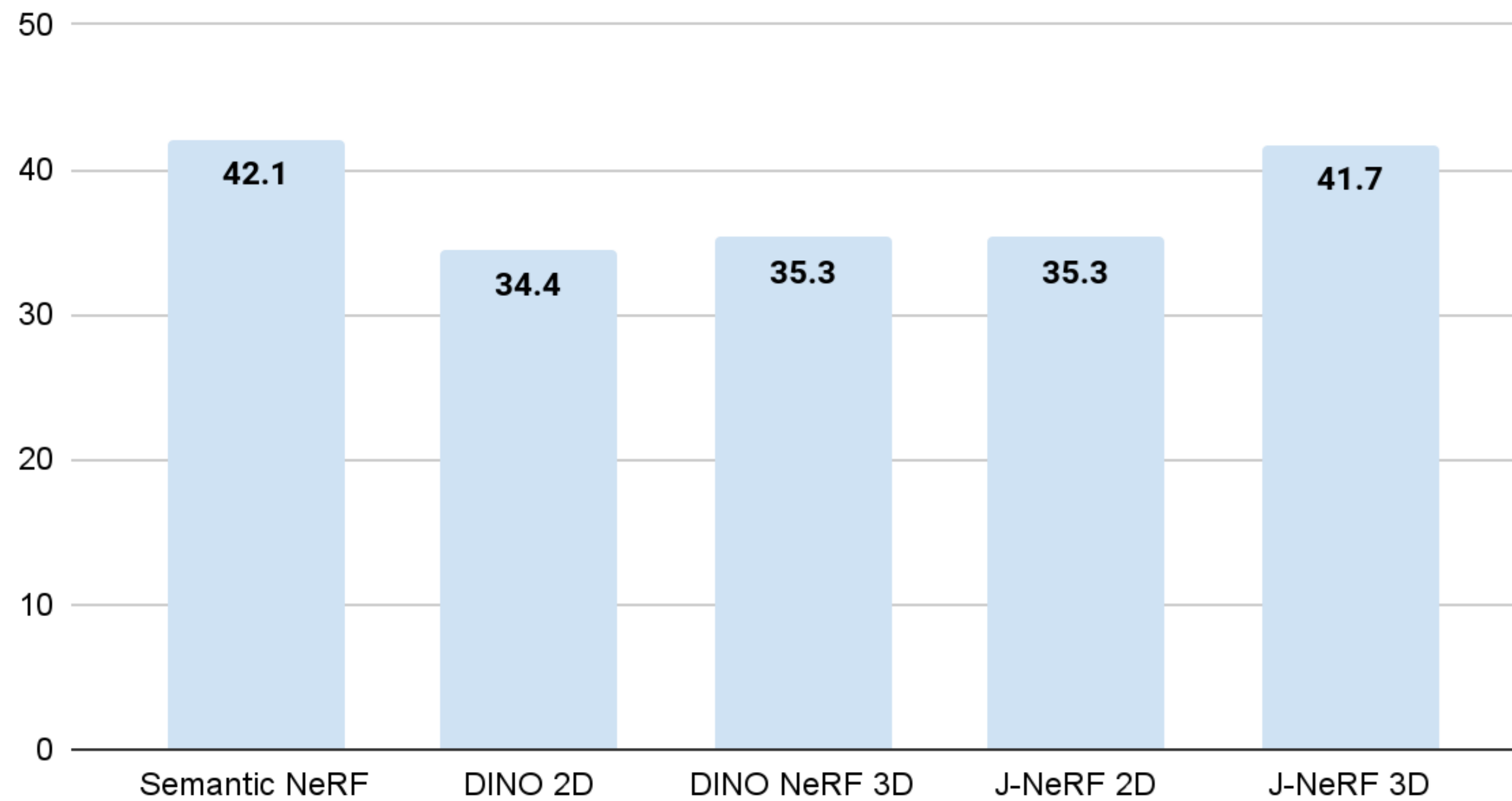


J-NeRF 3D



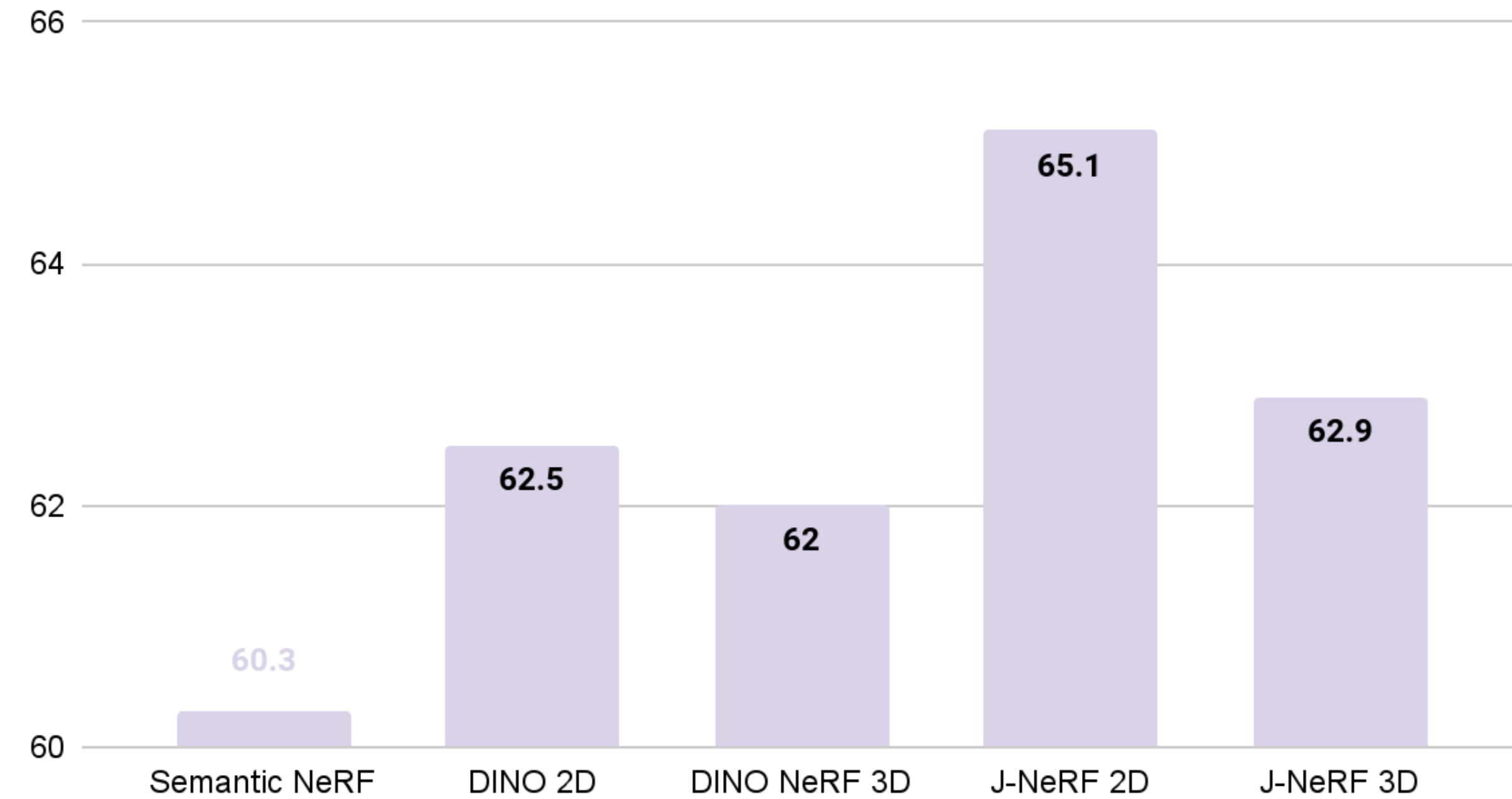
Instance segmentation (1 view, **dense**, ScanNet)

Dense label 1 view



mIoU

Dense label 1 view



Acc

Average results on 4 scenes, ~180 test views for each scene

<https://github.com/xxm19/jacobinerf>

