

Decoupled Semantic Prototypes enable learning from diverse annotation types for semi-weakly segmentation in expert-driven domains

Poster Session WED-PM-299



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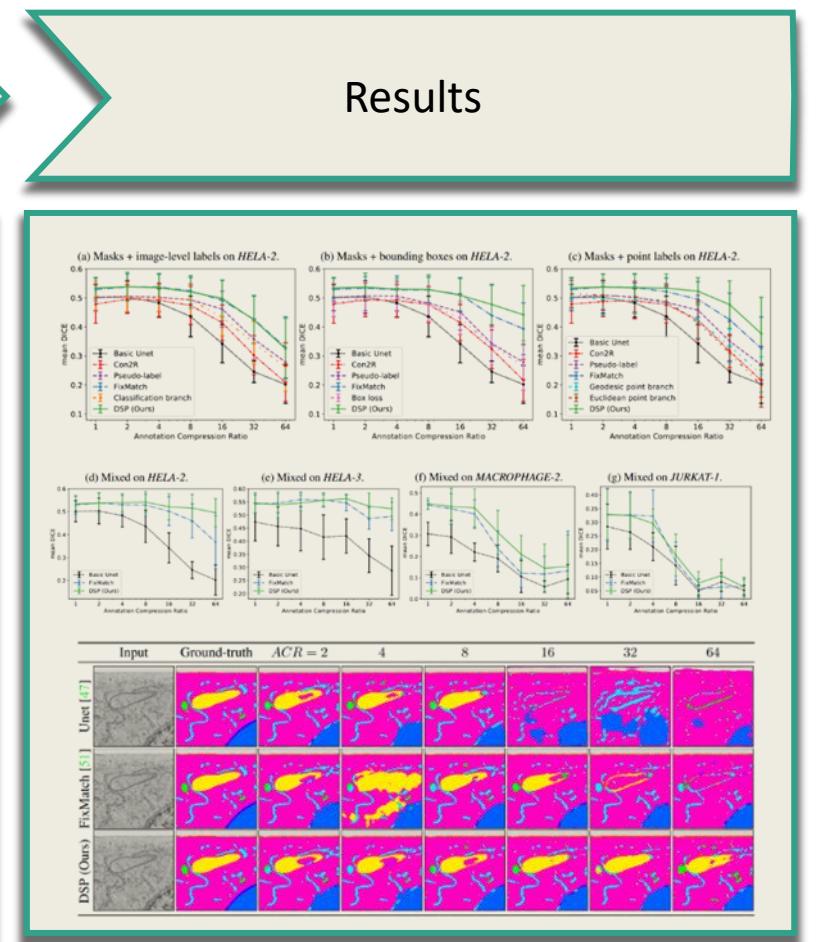
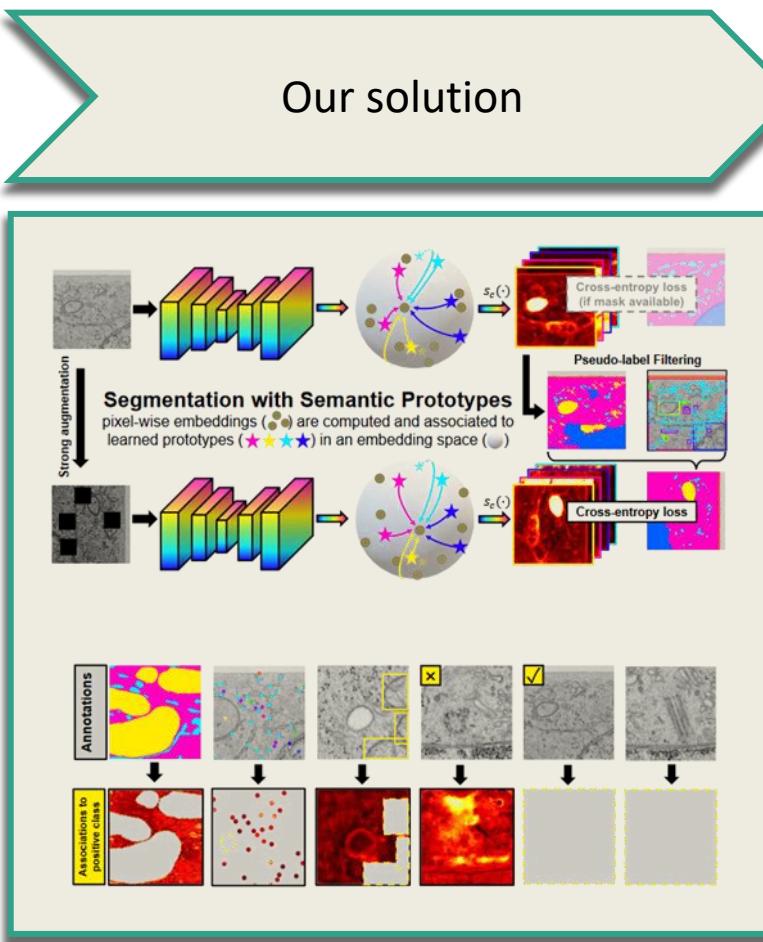
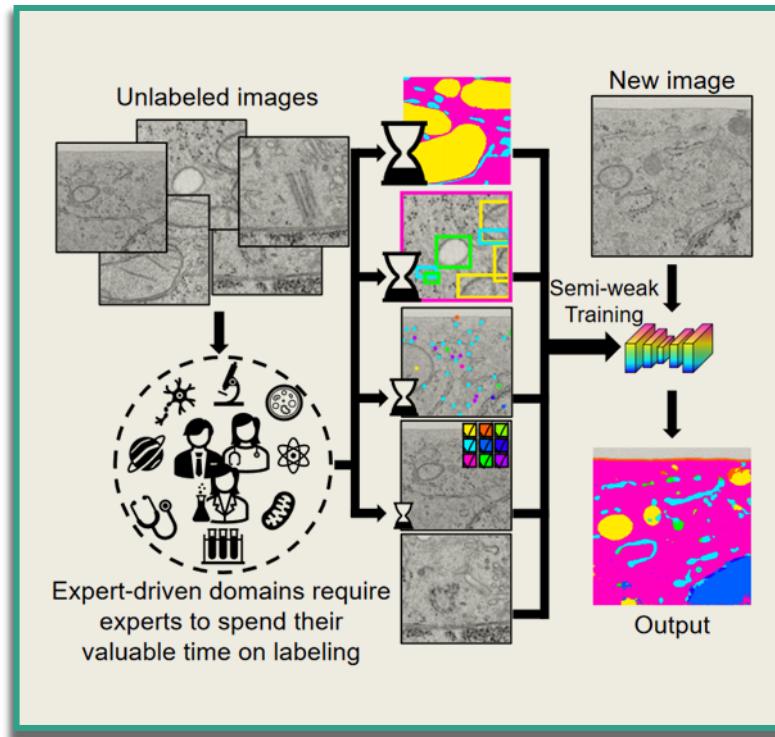
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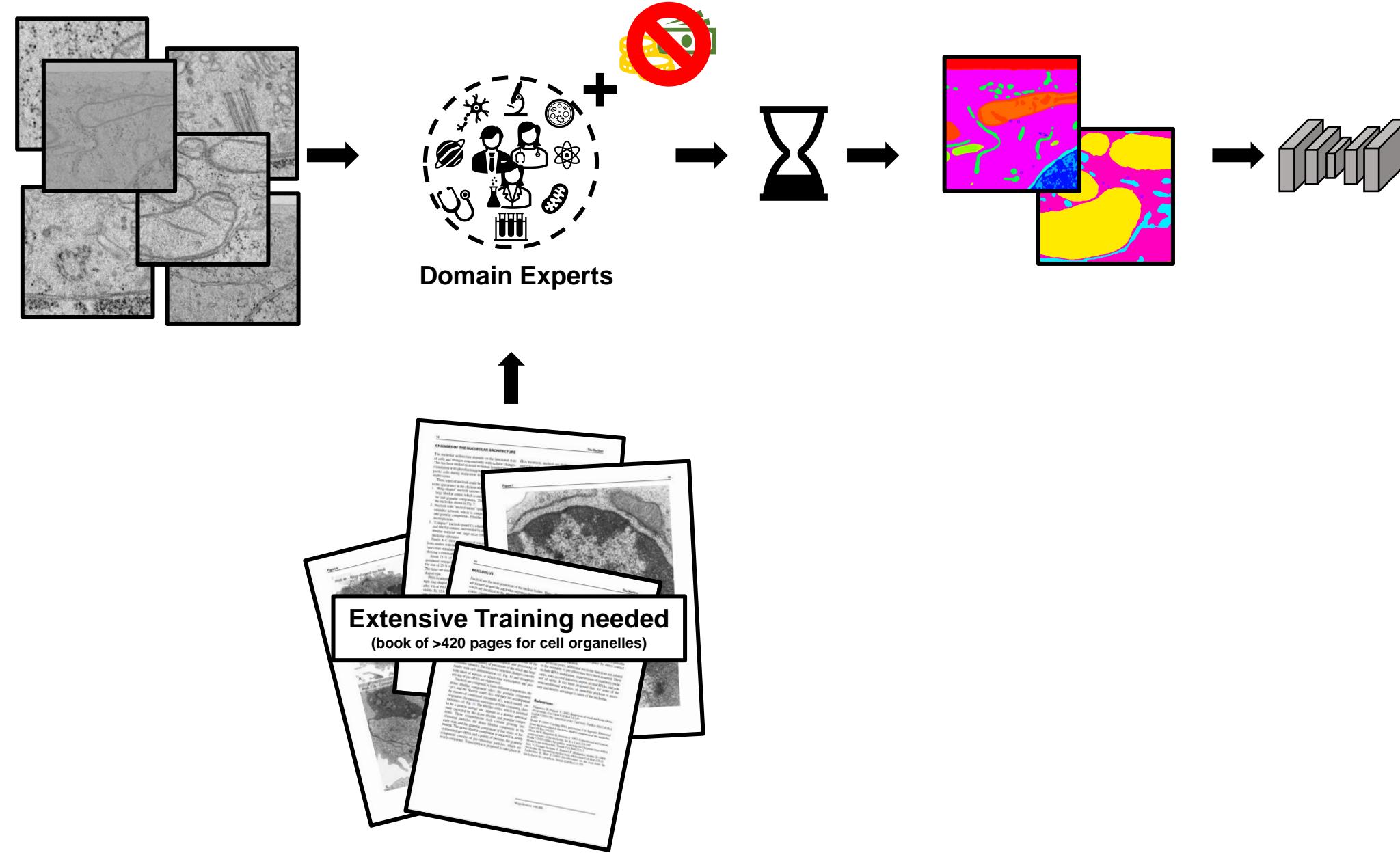
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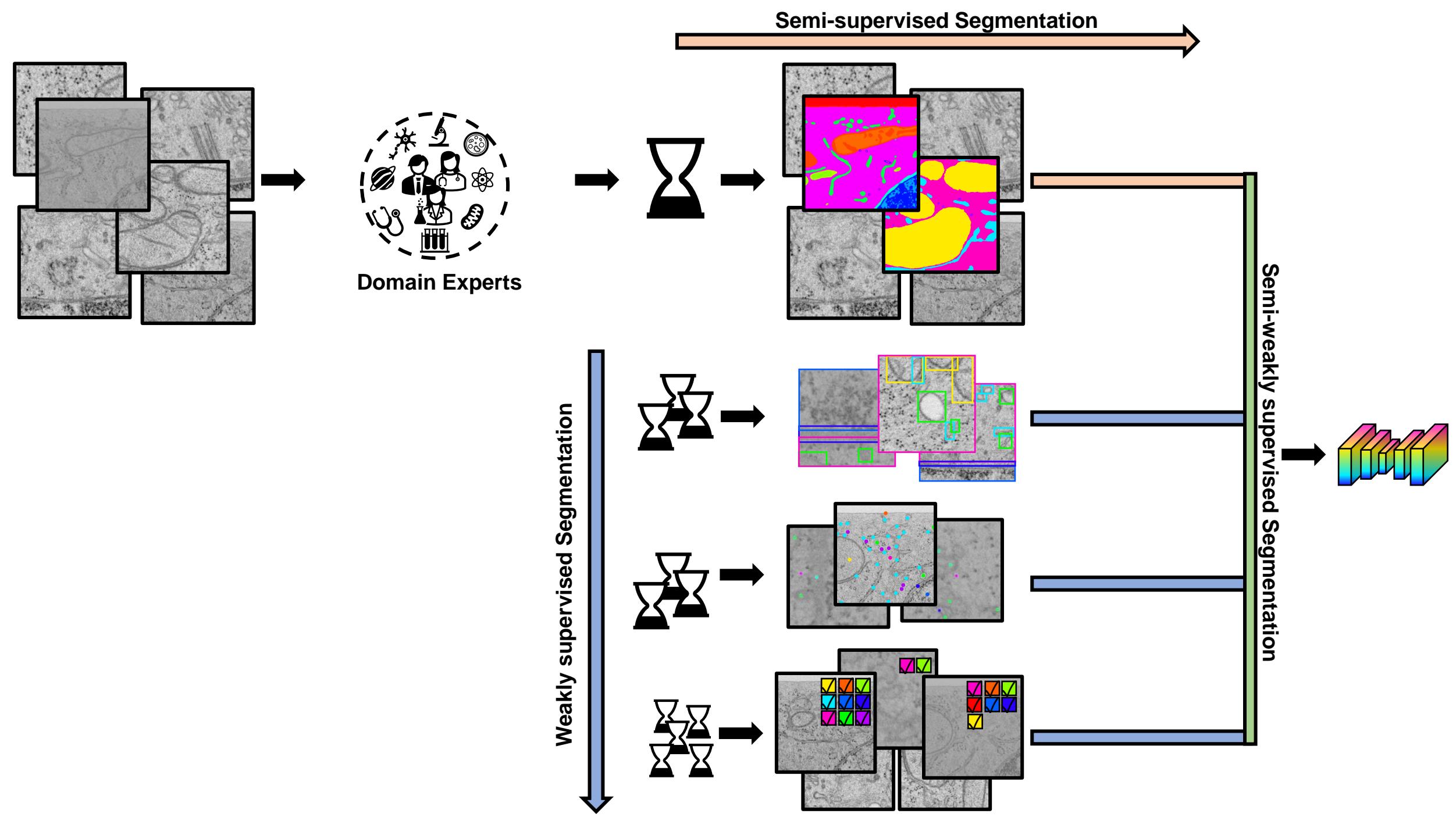
Challenge: Expert availability

Our solution

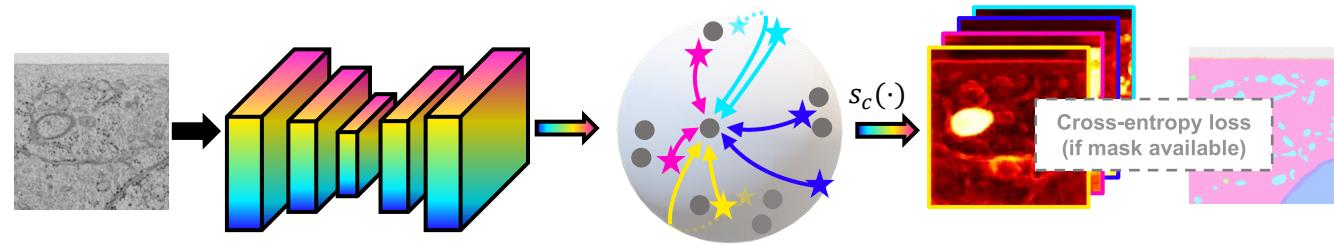
Results







Training with diverse annotation types



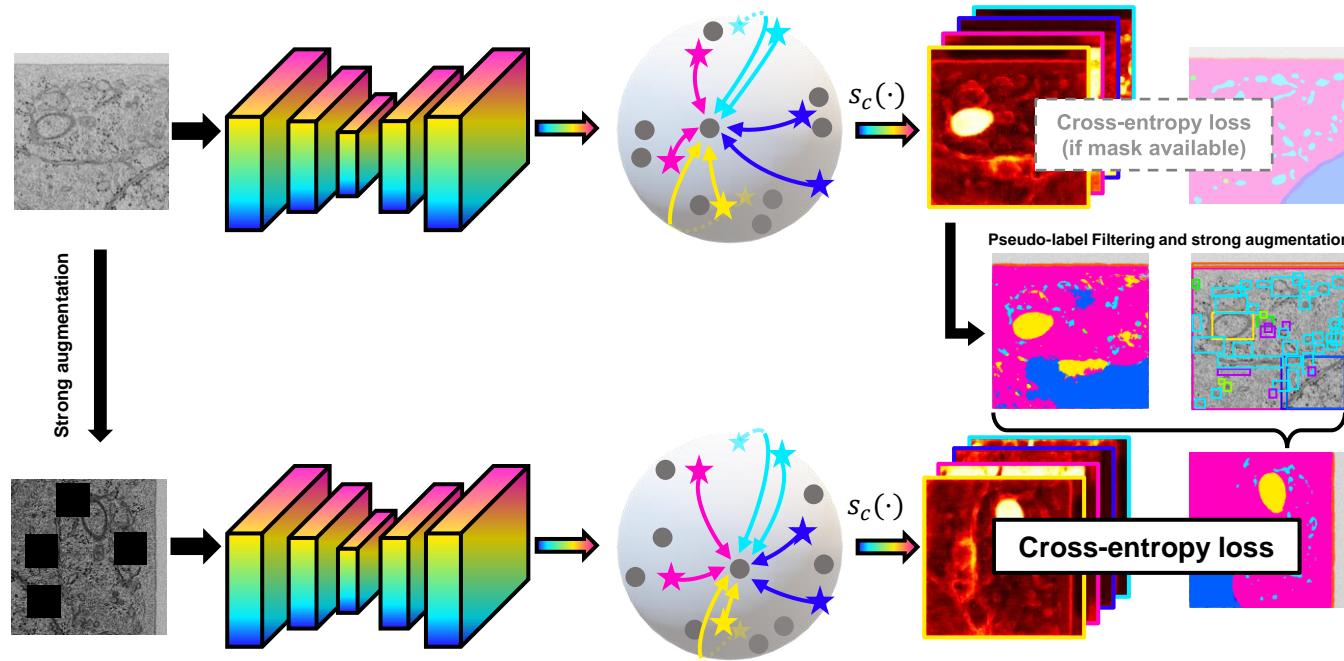
Pixel-embedding-prototype similarity

$$\sigma(f, p_c^j) = \frac{f^\top p_c^j}{\|f\| \cdot \|p_c^j\|}$$

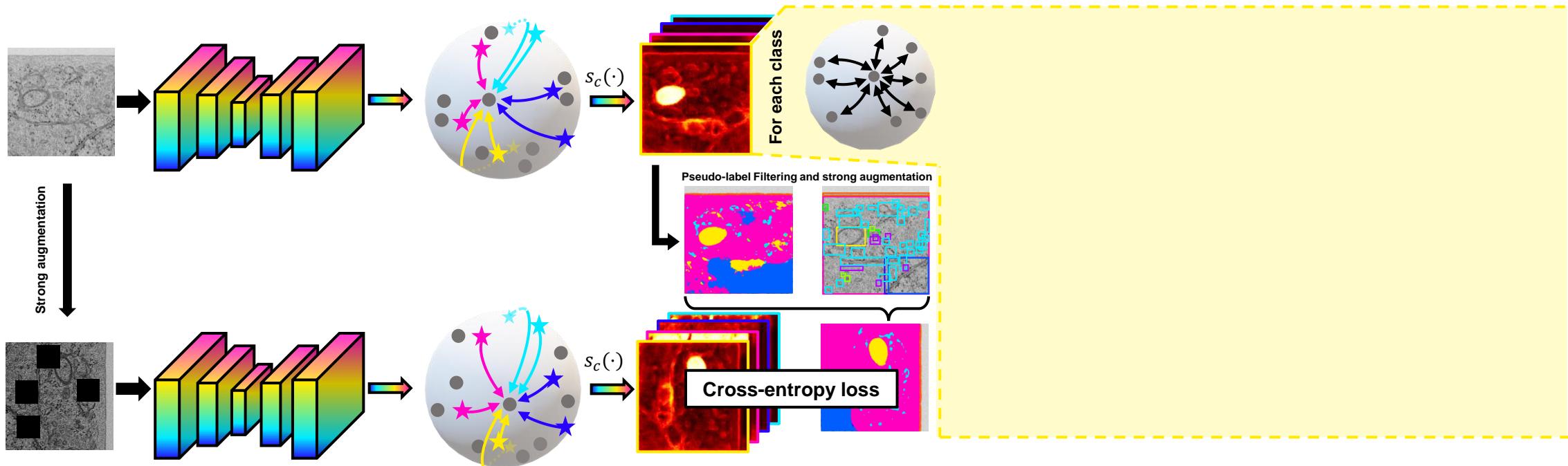
Class-wise score for pixel-embedding

$$s_c(f, P_c) = \frac{1}{|P_c|} \cdot \sum_{j \in P_c} \sigma(f, p_c^j)$$

Training with diverse annotation types

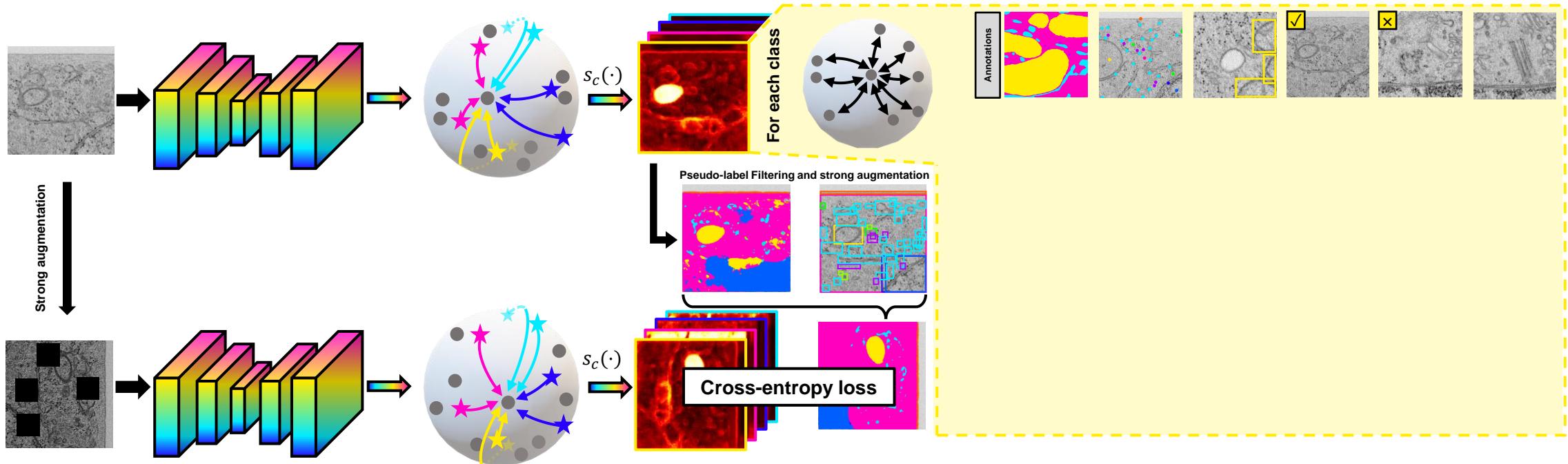


Training with diverse annotation types



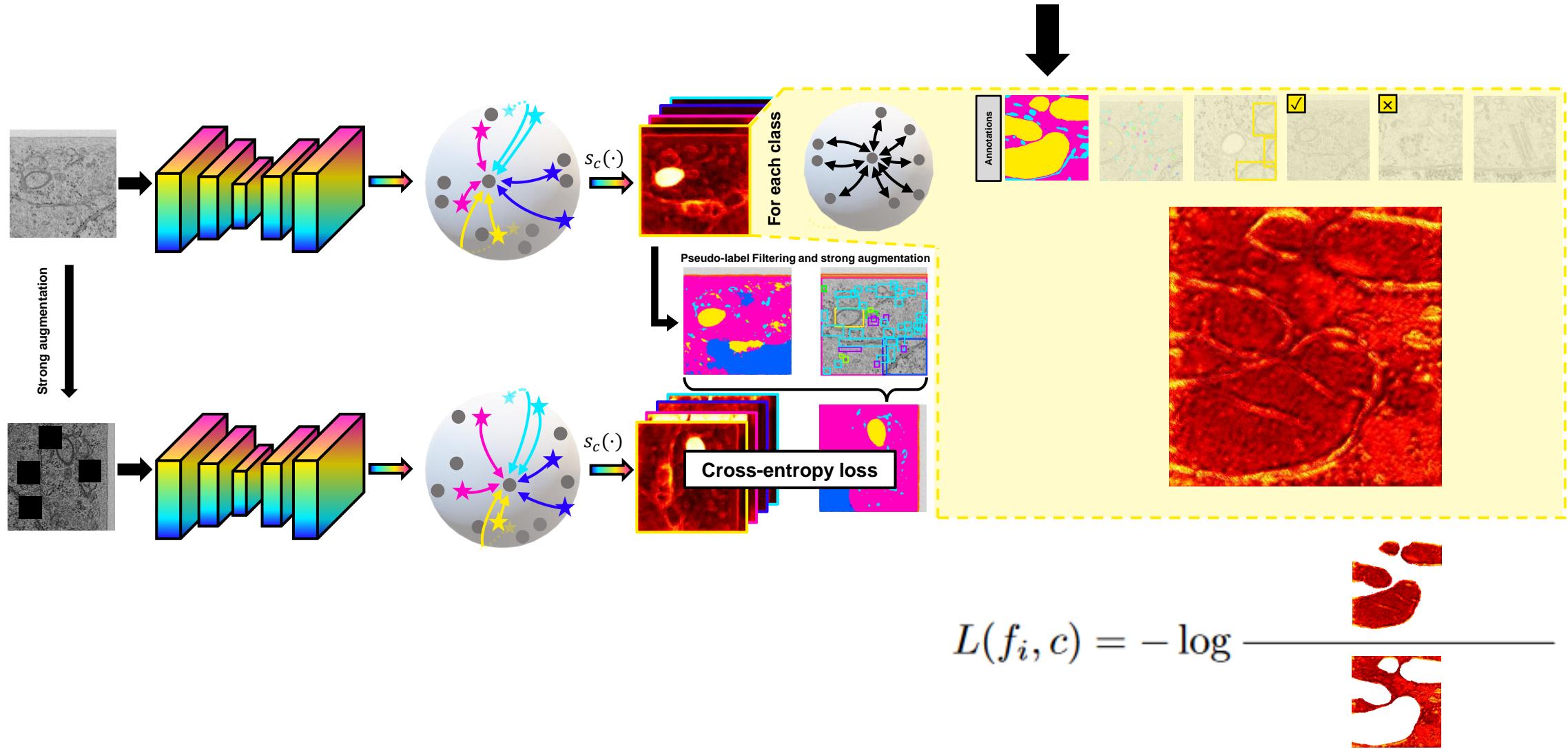
$$L(f_i, c) = -\log \text{——}$$

Training with diverse annotation types

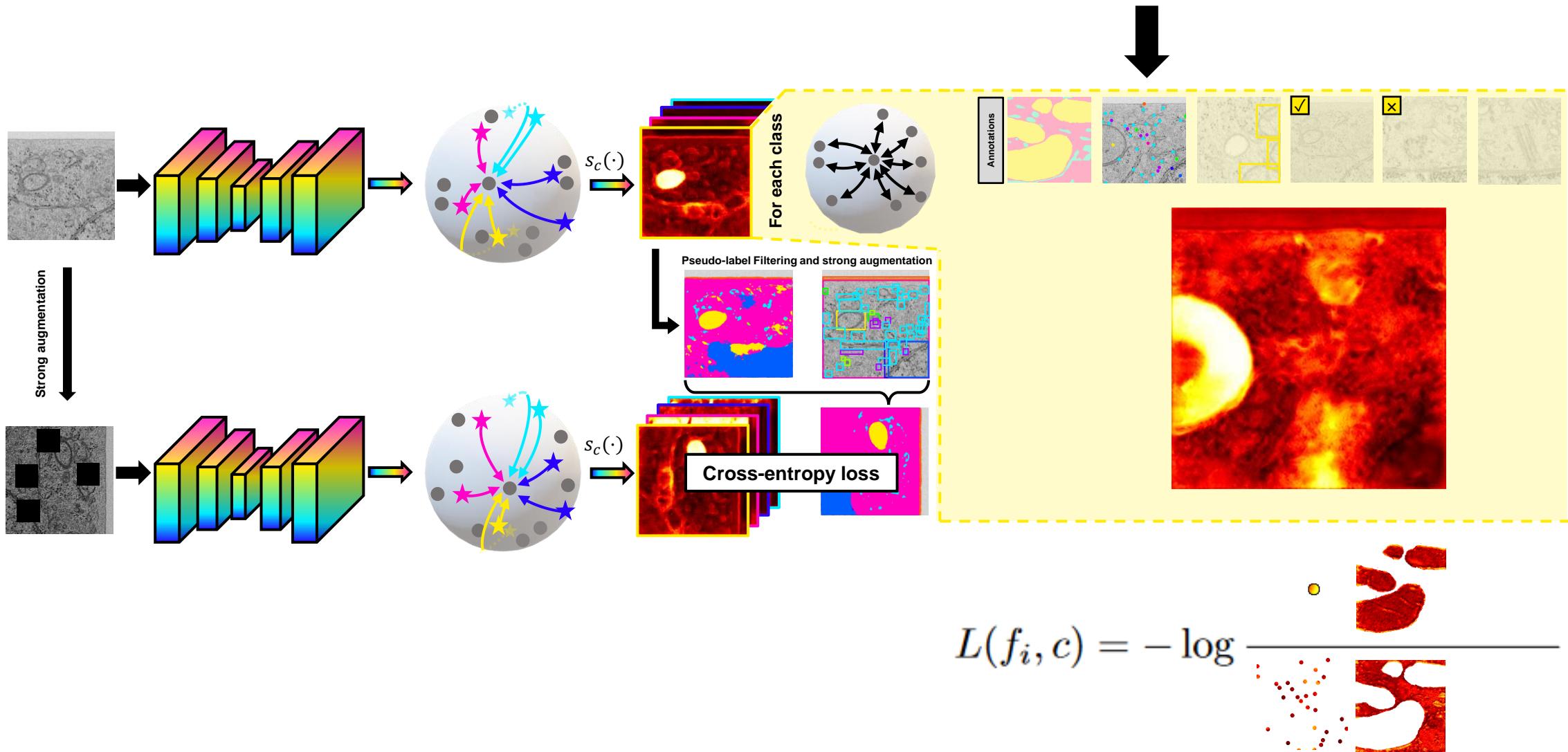


$$L(f_i, c) = -\log \text{——}$$

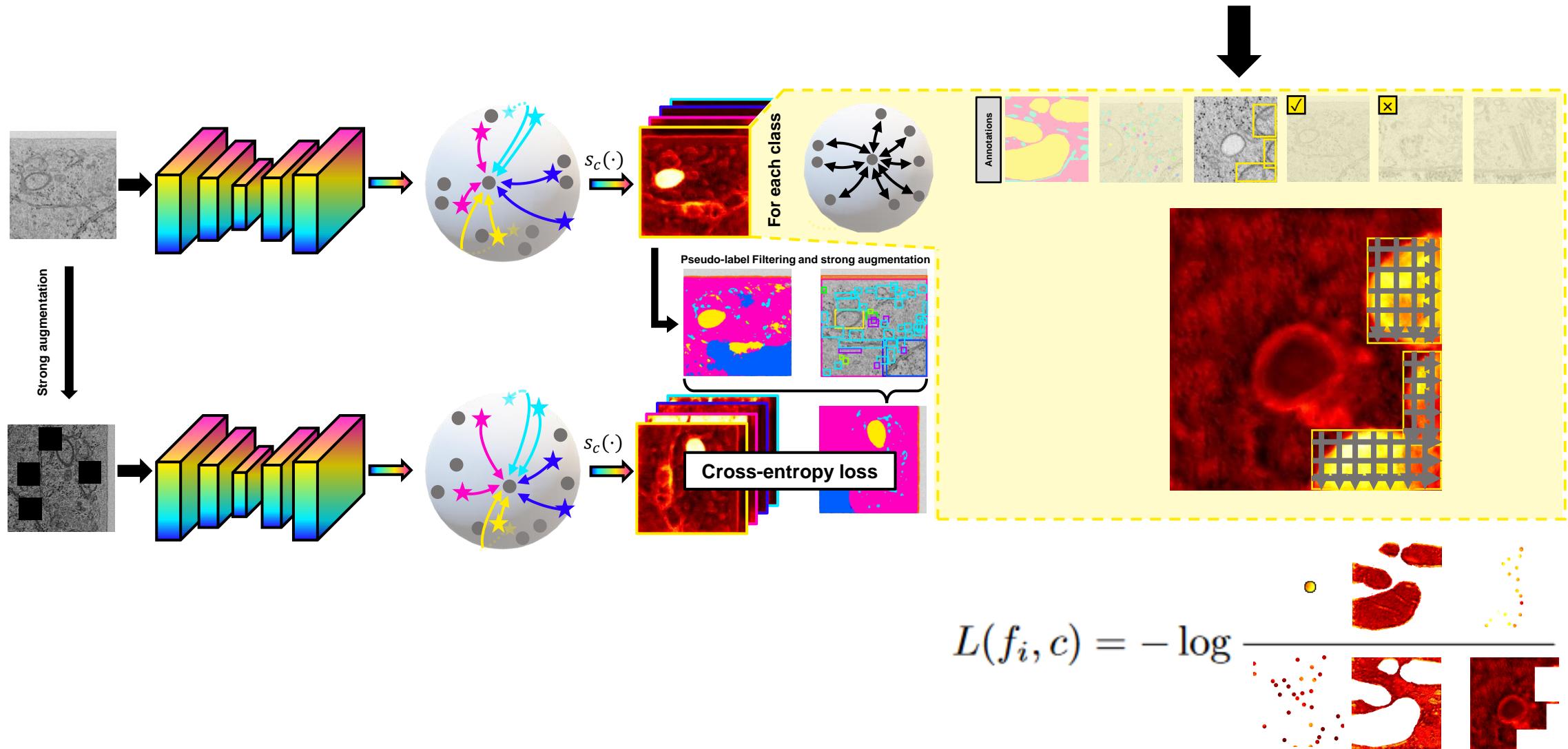
Training with diverse annotation types



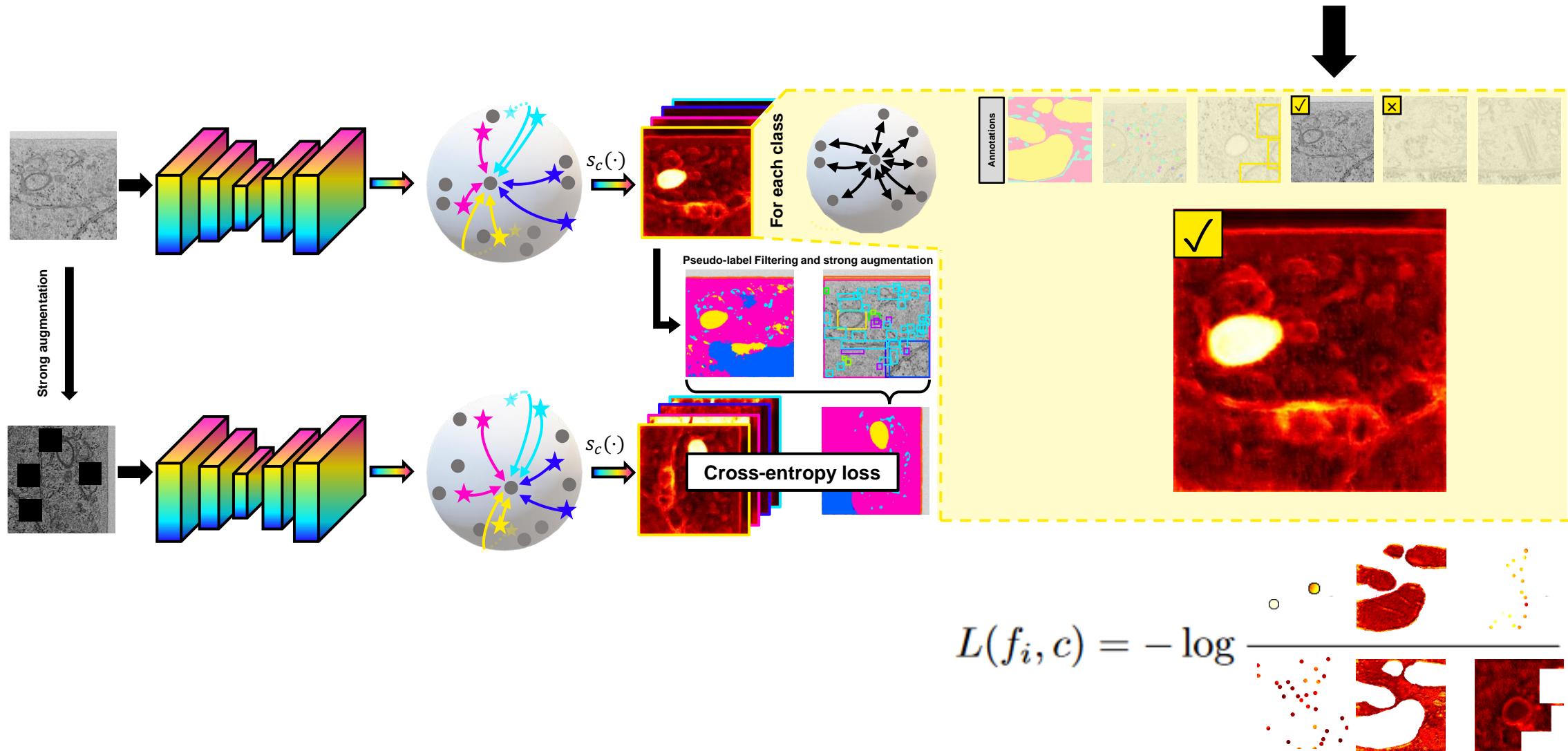
Training with diverse annotation types



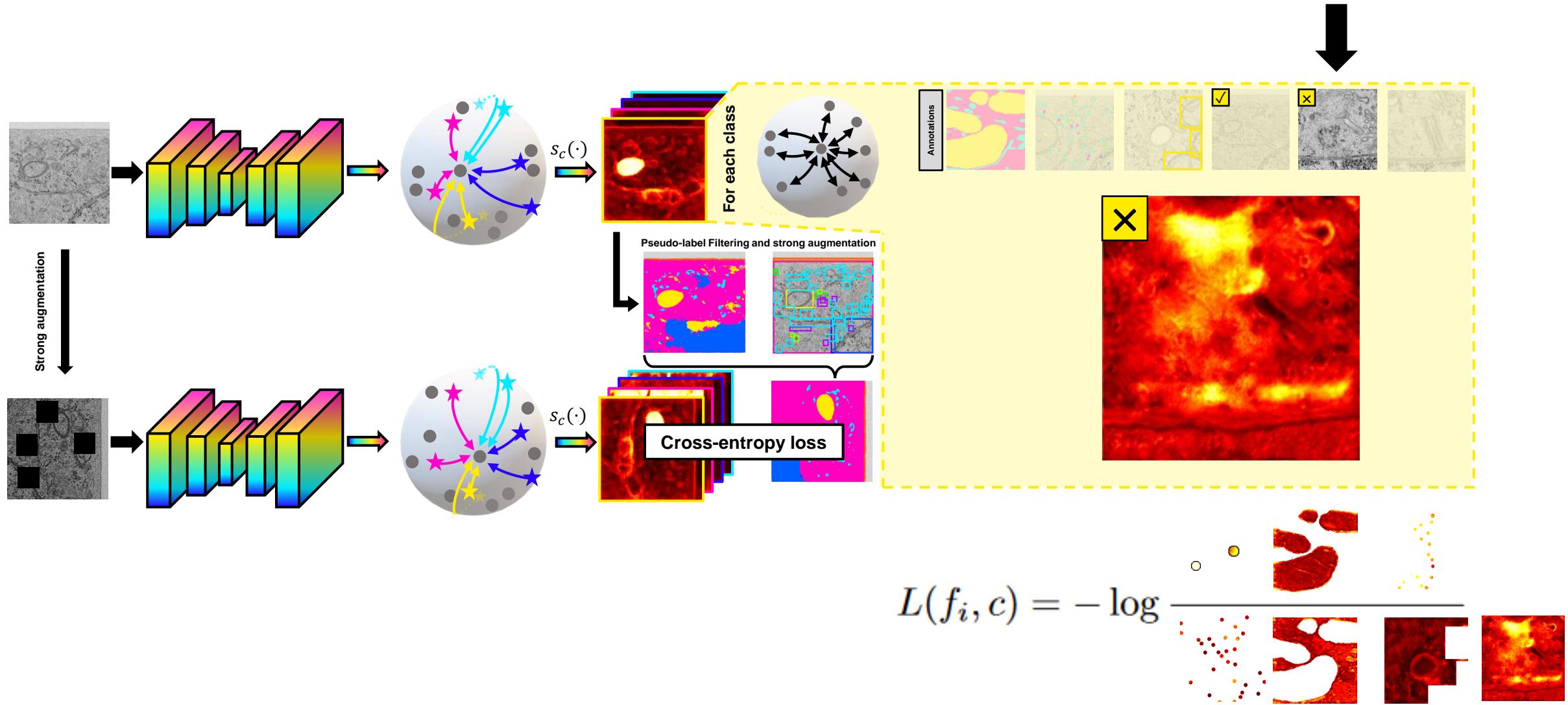
Training with diverse annotation types



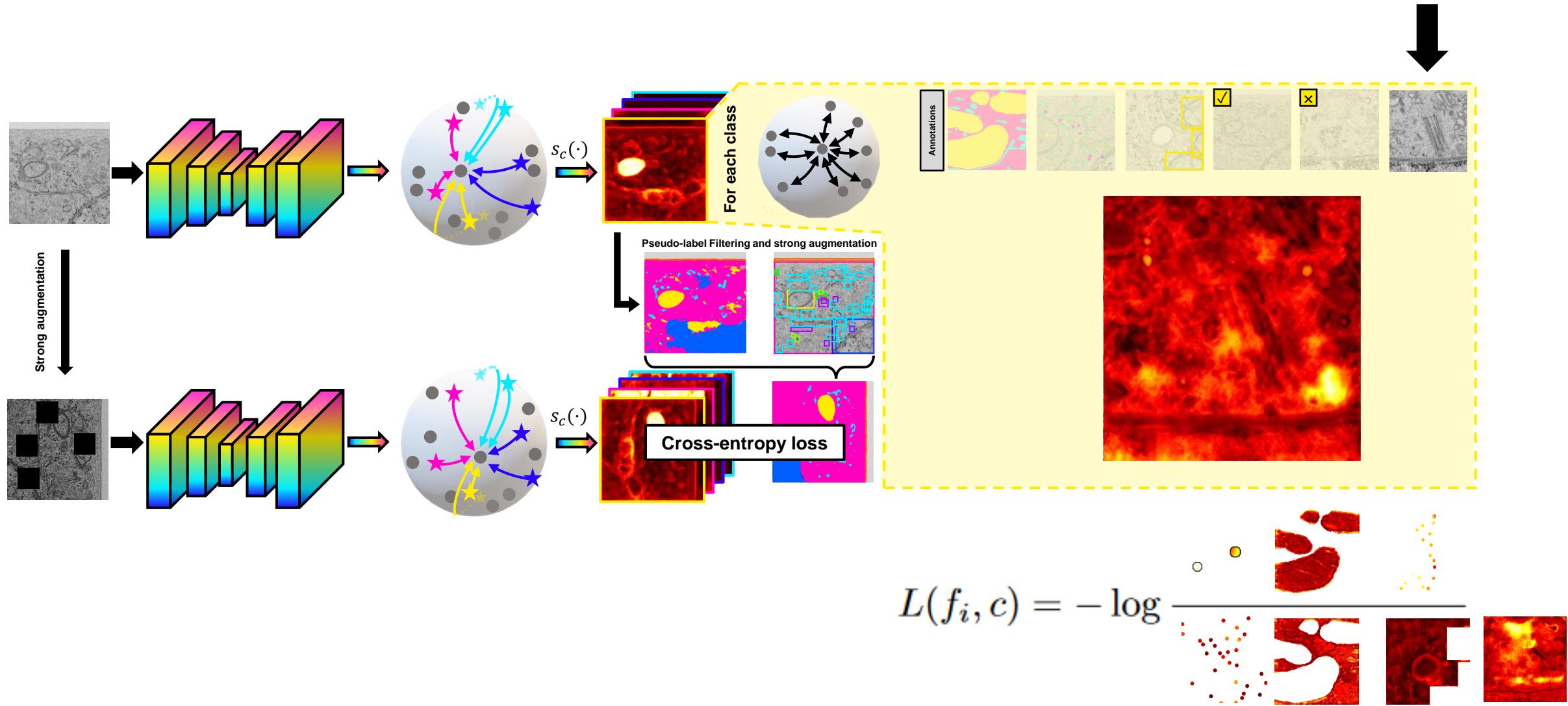
Training with diverse annotation types



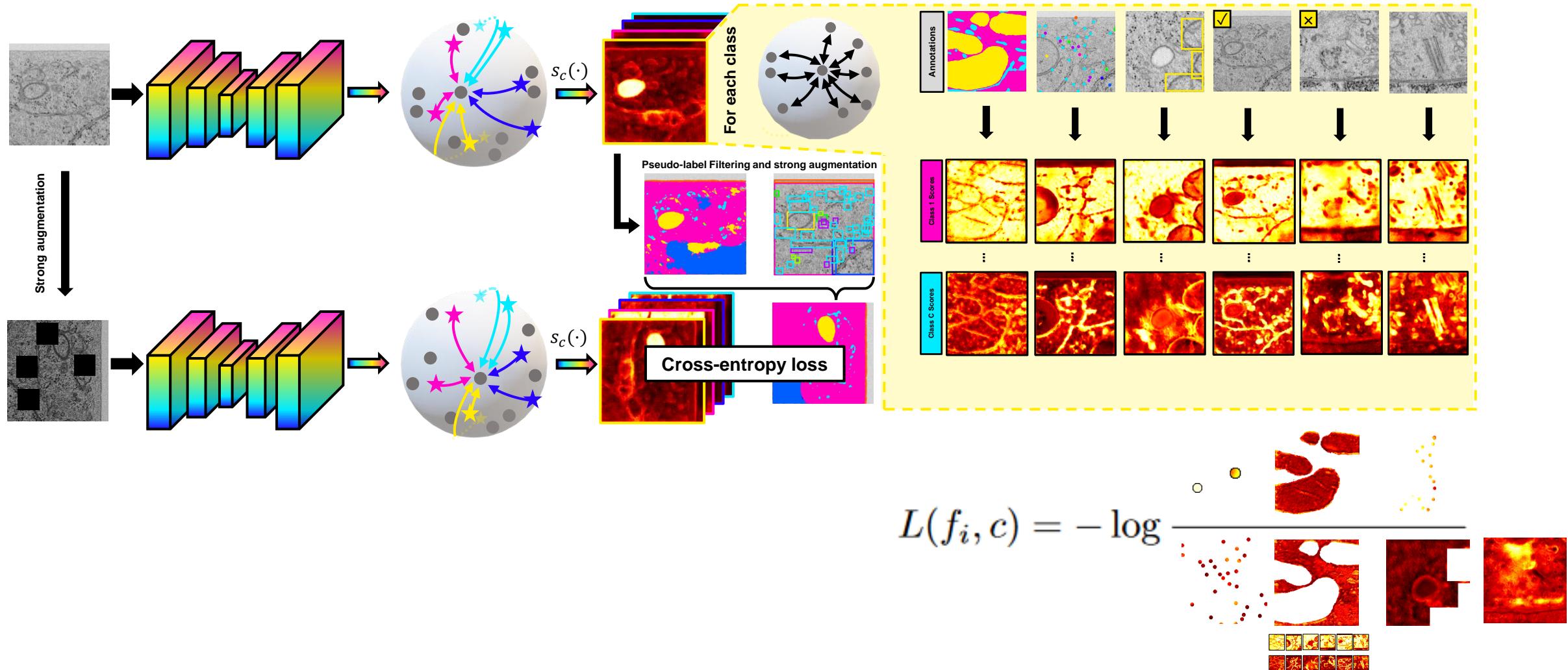
Training with diverse annotation types



Training with diverse annotation types

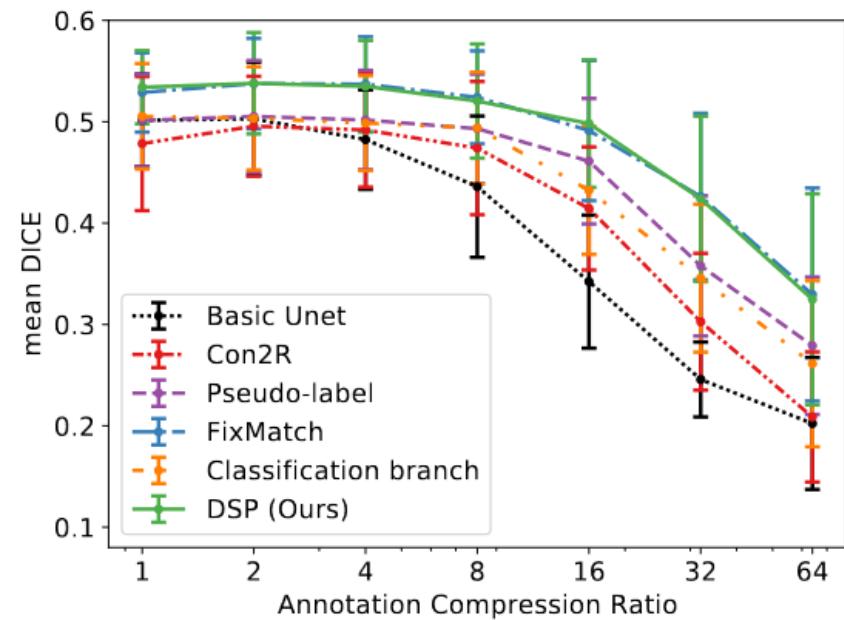


Training with diverse annotation types

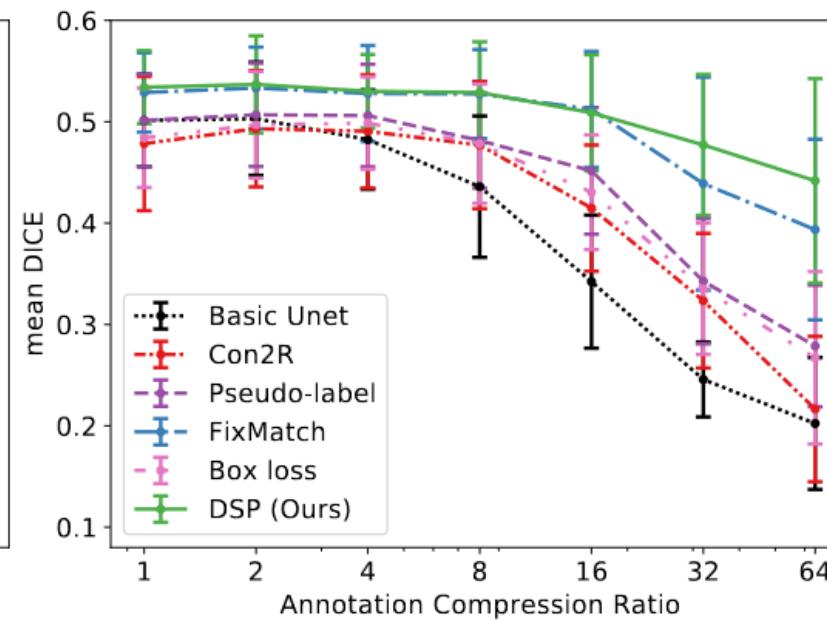


Quantitative results

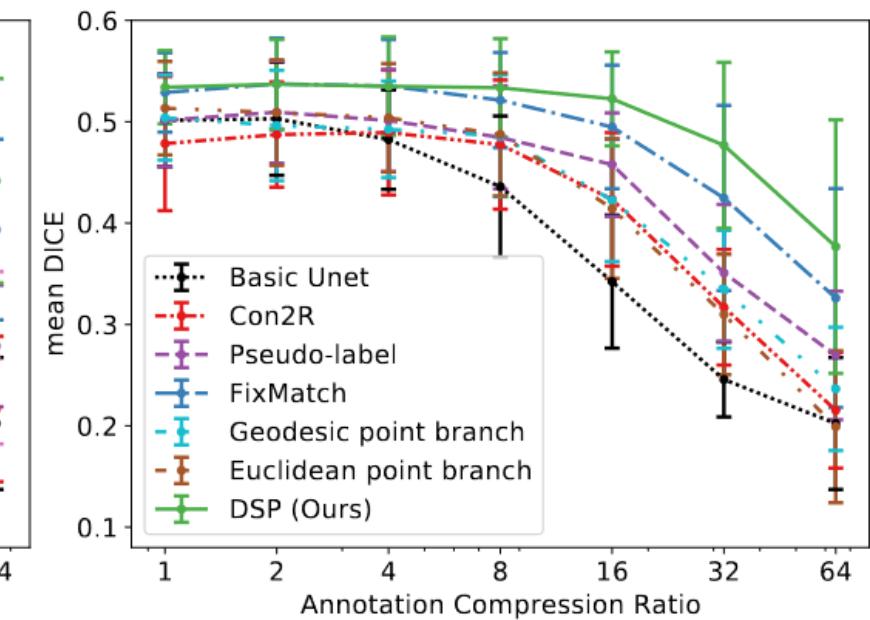
(a) Masks + image-level labels on *HELA-2*.



(b) Masks + bounding boxes on *HELA-2*.

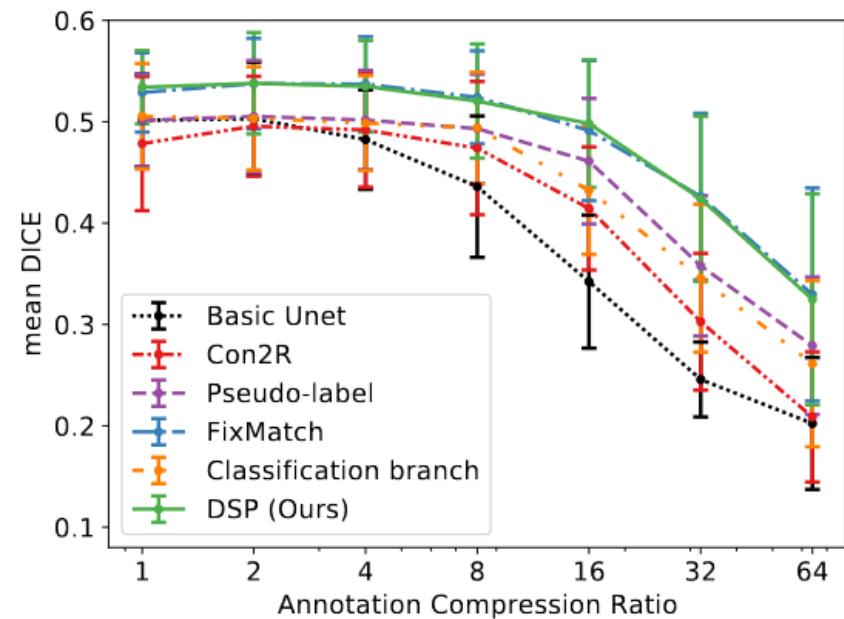


(c) Masks + point labels on *HELA-2*.

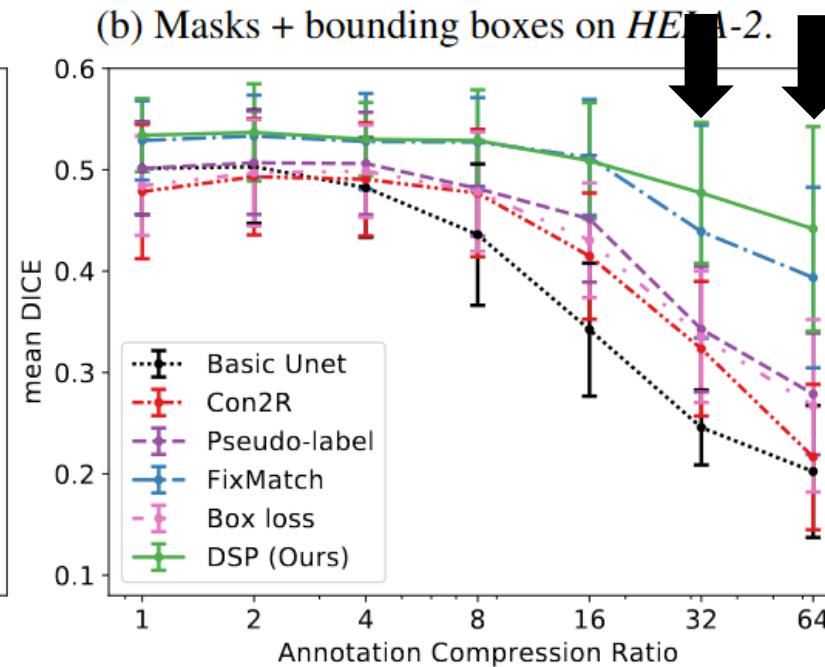


Quantitative results

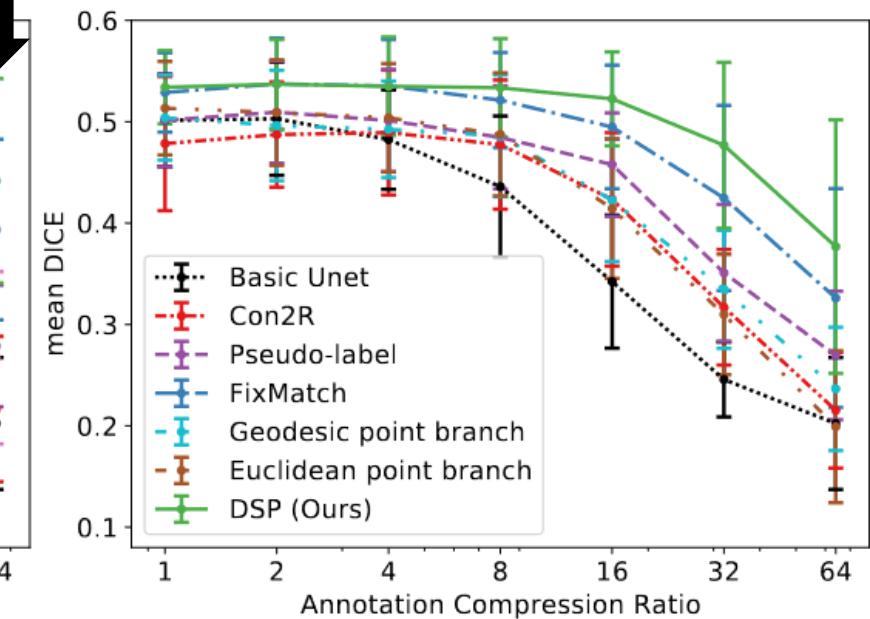
(a) Masks + image-level labels on *HELA-2*.



(b) Masks + bounding boxes on *HELA-2*.

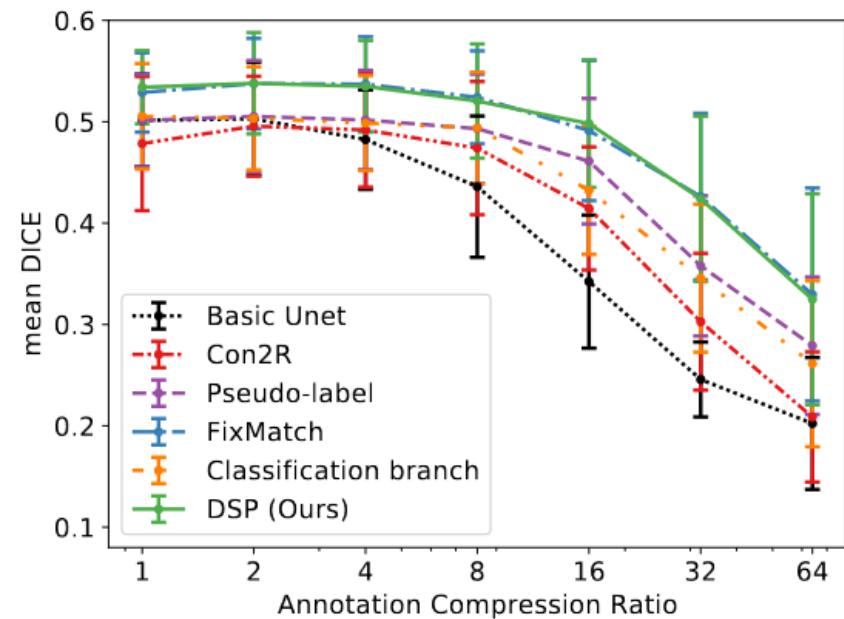


(c) Masks + point labels on *HELA-2*.

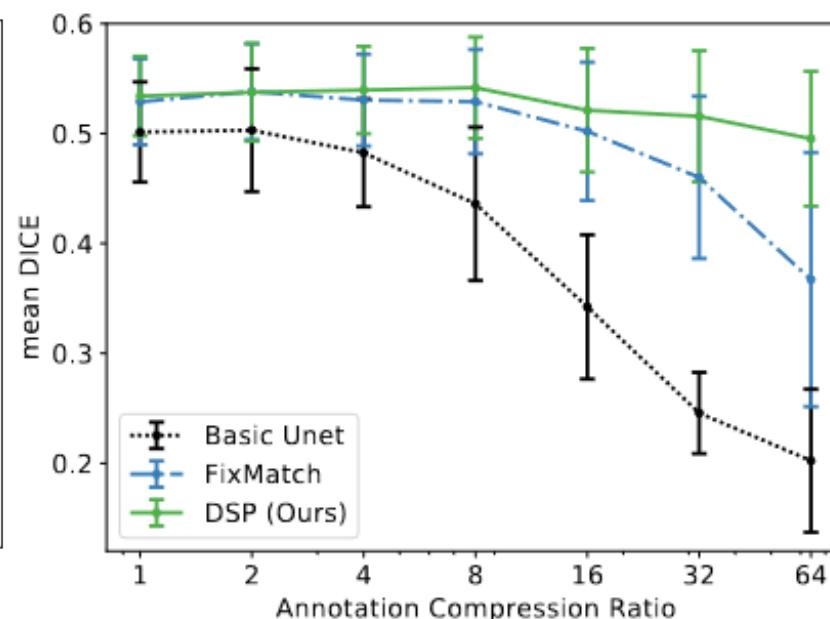


Quantitative results

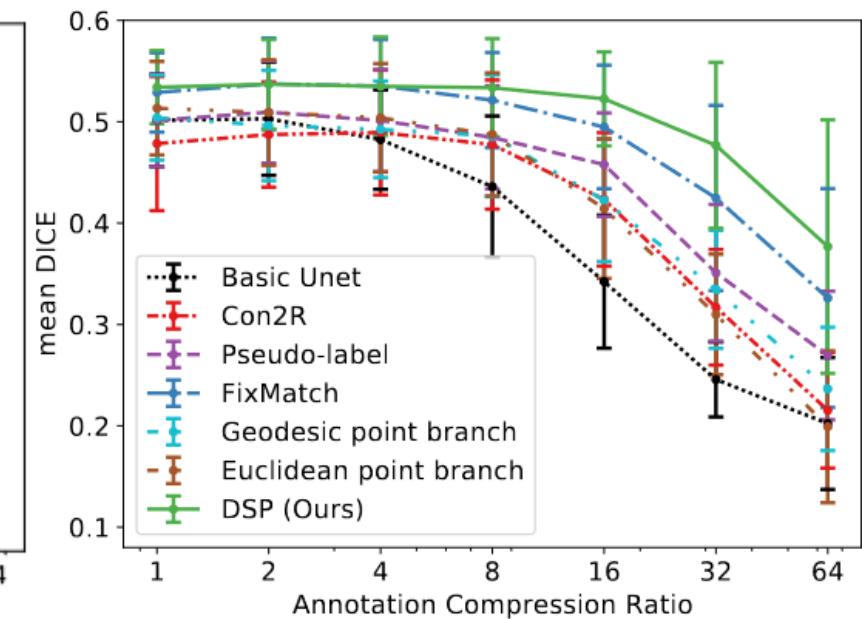
(a) Masks + image-level labels on *HELA-2*.



(d) Mixed on *HELA-2*.

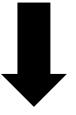


(c) Masks + point labels on *HELA-2*.



Qualitative results

Input	Ground-truth	$ACR = 2$	4	8	16	32	64
Unet [47]							
FixMatch [51]							
DSP (Ours)							



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CODE ON GITHUB!