



## BEVSpread: Spread Voxel Pooling for Bird's-Eye-View Representation in Vision-based Roadside 3D Object Detection

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![](_page_0_Figure_5.jpeg)

![](_page_0_Picture_6.jpeg)

## Results

Modality

LiDAR

LiDAR

LiDAR & Camera

**Image Feature** 

Venue	Vehicle (IoU=0.5)			Pedestrian (IoU=0.25)			Cyclist ( <i>IoU</i> =0.25)		
	Easy	Middle	Hard	Easy	Middle	Hard	Easy	Middle	Hard
CVPR' 19	63.07	54.00	54.01	38.53	37.20	37.28	38.46	22.60	22.49
Sensors	71.47	53.99	54.00	55.16	52.49	52.52	54.68	31.05	31.19
ICRA' 19	71.04	53.71	53.76	55.83	54.45	54.40	54.05	30.79	31.06
WACV' 22	44.78	37.58	37.55	6.81	6.75	6.74	21.06	13.57	13.17
ECCV' 22	61.37	50.73	50.73	16.89	15.82	15.95	22.16	22.13	22.06
AAAI' 23	75.50	63.58	63.67	34.95	33.42	33.27	55.67	55.47	55.34
CVPR' 23	77.78	65.77	65.85	41.22	39.29	39.46	60.23	60.08	60.54
-	79.07	66.82	66.88	46.54	44.51	44.71	62.64	63.50	63.75
	+1.29	+1.05	+1.03	+5.32	+5.22	+5.25	+2.41	+3.42	+3.21
CVPR 23	81.62	75.90	75.94	40.89	38.98	39.18	60.29	60.60	61.13
-	82.84	77.10	77.19	43.96	42.03	42.13	62.31	64.44	64.89
	+1.22	+1.21	+1.25	+3.07	+3.05	+2.95	+2.02	+3.84	+3.76
AAAI 23	76.90	66.91	66.89	30.42	28.08	28.11	55.34	53.53	53.51
CVPR 23	77.93	67.50	67.49	36.26	30.35	30.30	61.49	56.98	56.90
-	80.61	70.04	70.03	38.65	34.32	34.25	63.66	59.11	59.03
	+2.69	+2.55	+2.54	+2.39	+3.97	+3.95	+2.17	+2.13	+2.13

Scene B

![](_page_0_Picture_11.jpeg)

![](_page_0_Picture_12.jpeg)

**Predicted 3D bounding box** 

**Projection of the pedestrian's image features**