

PIN:

Positional Insert Unlocks Object Localisation Abilities in VLMs

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CVPR'24

VLMs are great with many things, but not localisation

Prompt 1: Provide a bounding box around the cat

Prompt 2: Localise the cat in the image



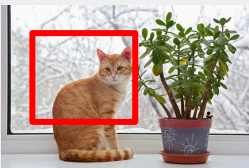
VLMs are great with many things, but not localisation

Prompt 1: Provide a bounding box around the cat

Prompt 2: Localise the cat in the image



P1:



P2: *The cat in the image is sitting on the right side [...]*

 **GPT-4V**

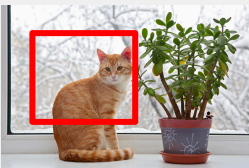
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Prompt 1: Provide a bounding box around the cat

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P1:



P2: The cat in the image is sitting on the right side [...]

 **GPT-4V**

P1: To determine the size of the room.

P2: The cat in the image is localised in the image.

 **OpenFlamingo**

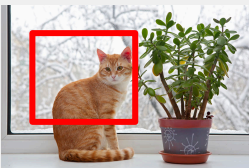
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P1: To determine the size of the room.

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 **OpenFlamingo**

P1: Cats are not fond of being confined in a small space.

P2: Yes, you can do that

 **FROMAGE**

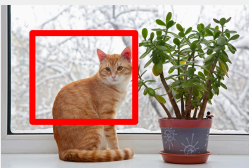
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 **OpenFlamingo**

P1: Cats are not fond of being confined in a small space.

P2: Yes, you can do that

 **FROMAGE**

P1: Provide a bounding box around the cat's plant

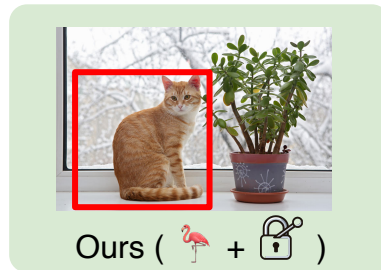
P2: <empty string>

 **BLIP-2**

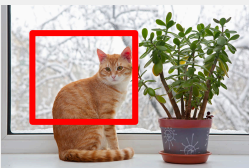
VLMs are great with many things, but not localisation

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 **BLIP-2**

Our approach



frozen VLM, e.g. Flamingo

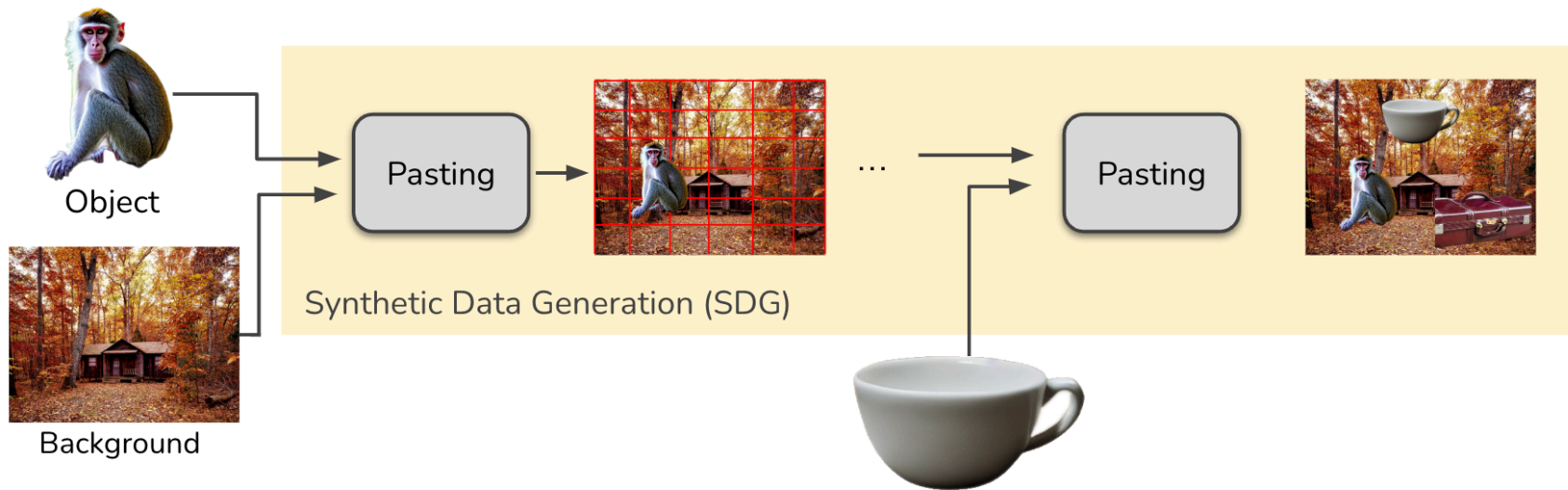


Positional Insert (PIN) module



Synthetic, unlabelled data

Synthetic data generation



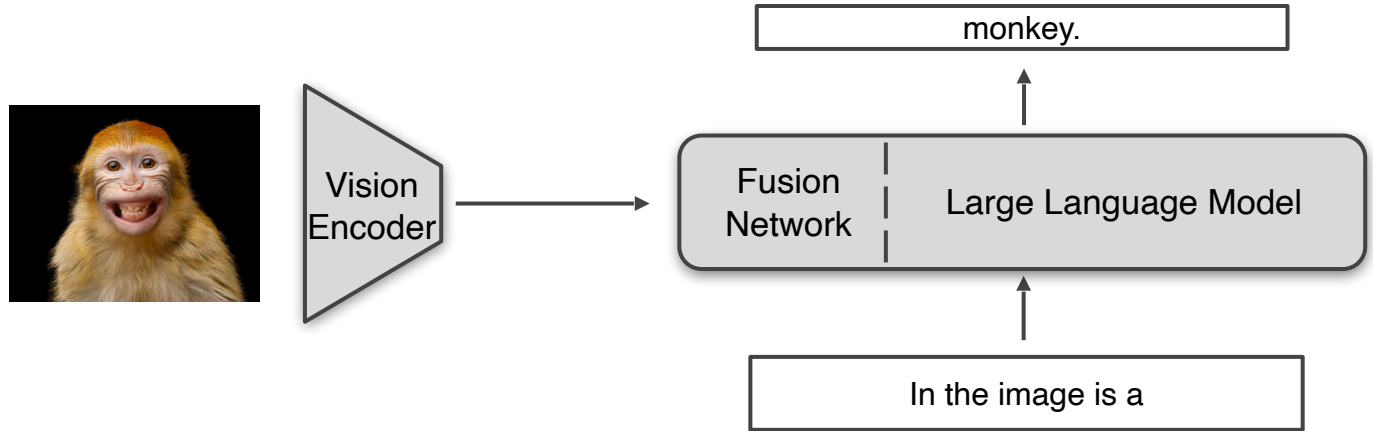
- **Self-Supervision Signal:** Location is known via pasting
- **Avoid collapse:** Pasting multiple objects

Example generated data

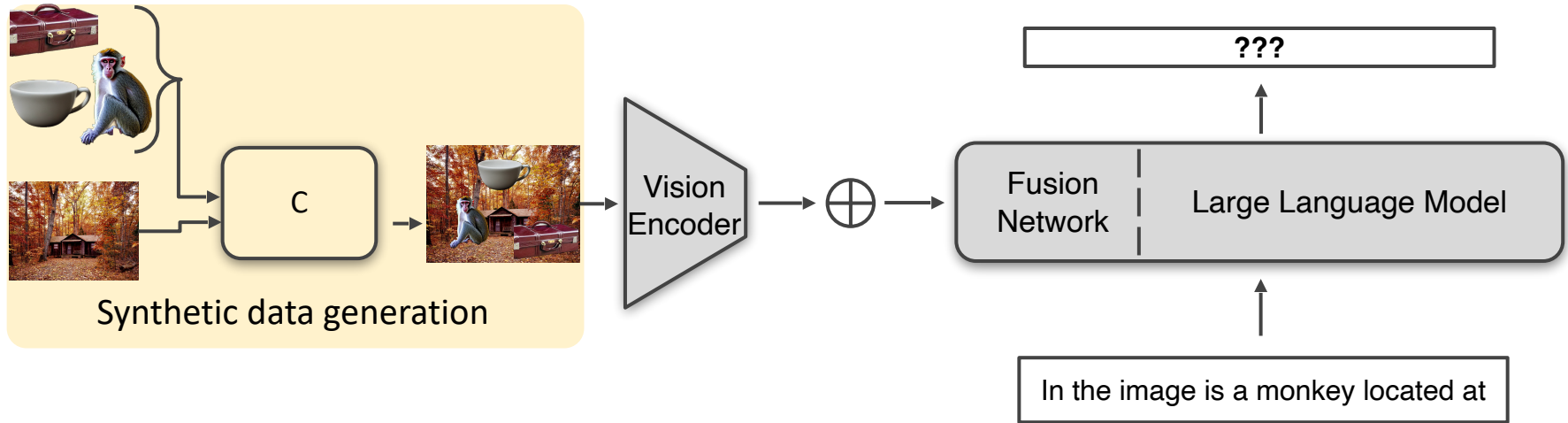


- Non-realism is **not** an issue, as vision encoder is kept completely frozen
- Pasting objects from categories that do not overlap with test data
 - Zero-shot evaluation

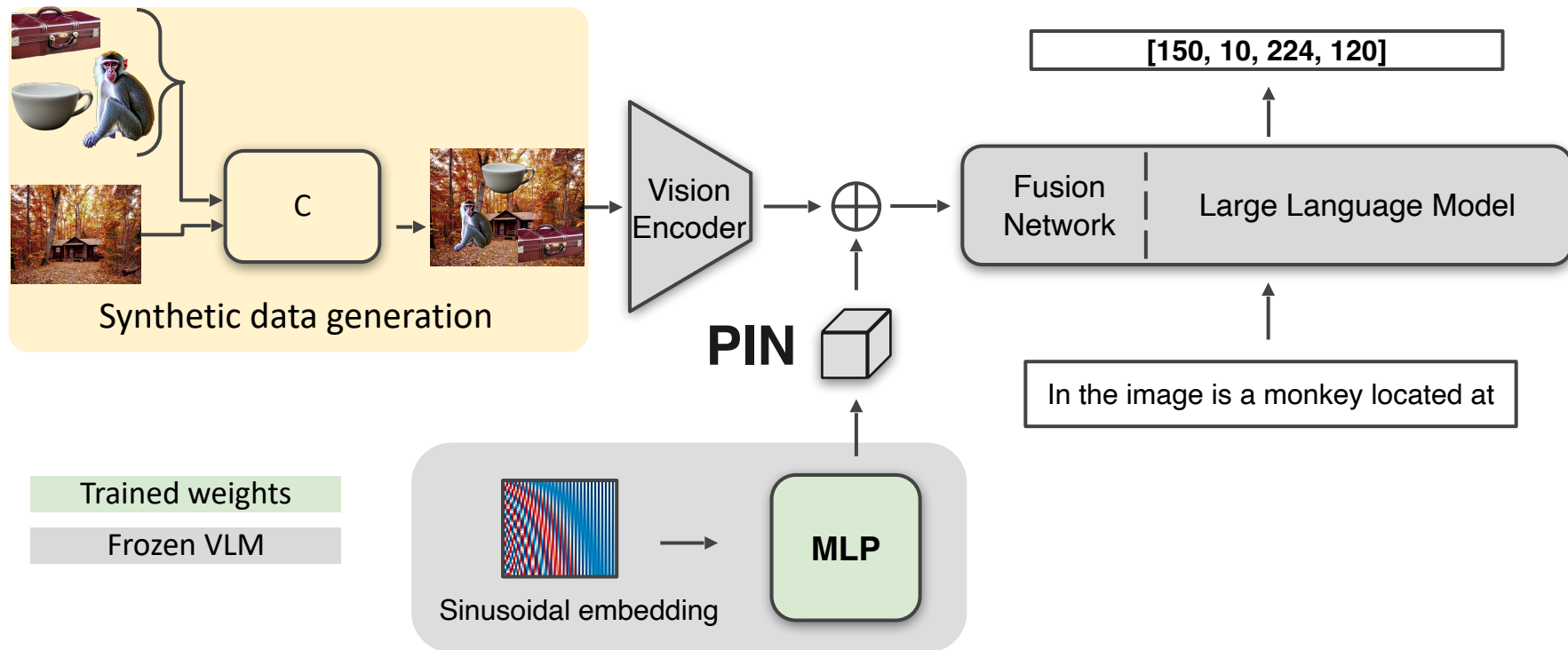
Overview of VLMs



Feed the frozen VLM synthetic data



Provide spatial learning capacity via PIN



What is PIN? It's a PEFT method for VLMs

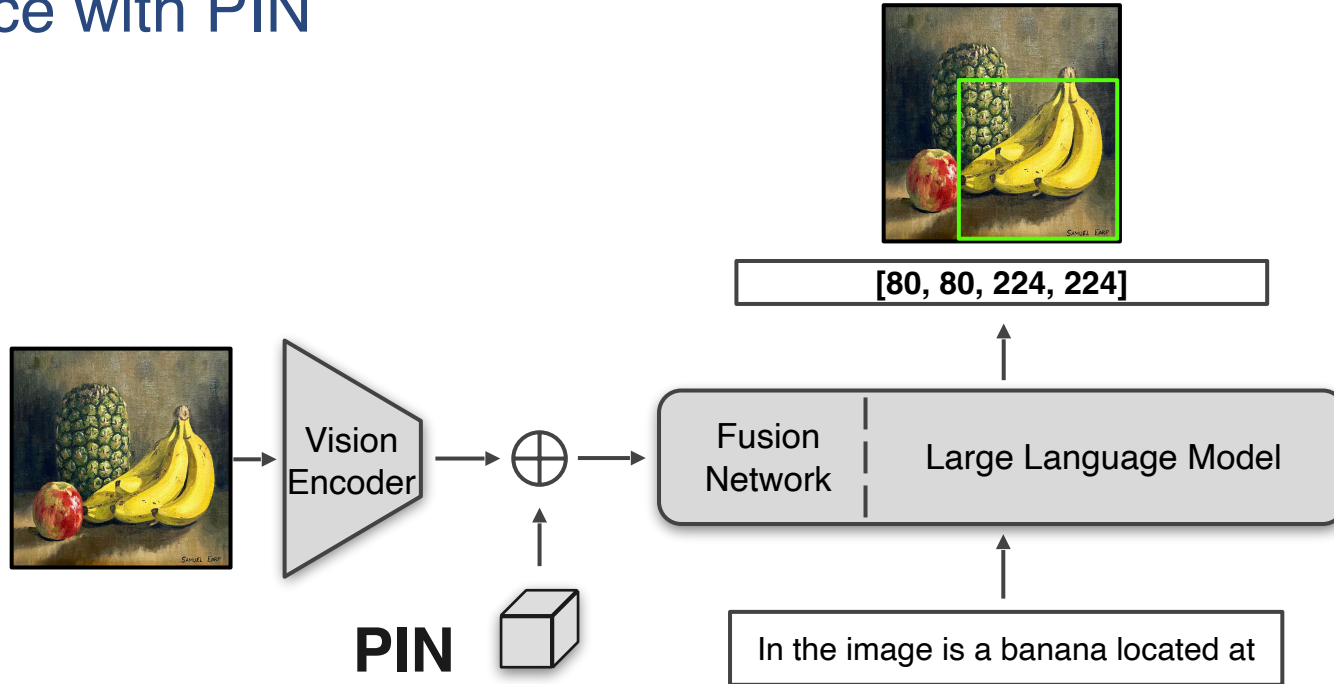
```
pos_encoding = get_sinusoid_encoding_table(n_patches=196, d_hid=64)

MLP = nn.Sequential(
    nn.Linear(64, 512),
    nn.SiLU(),
    nn.LayerNorm(512),
    nn.Linear(512, 768),
    nn.SiLU(),
    nn.LayerNorm(768),
    nn.Linear(768, 1024),
)

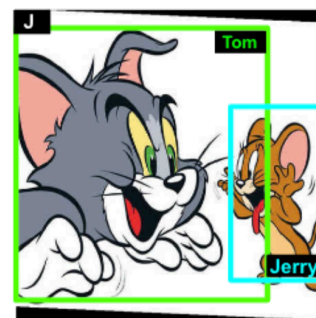
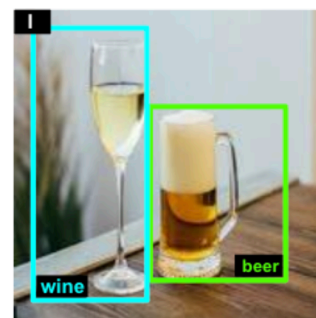
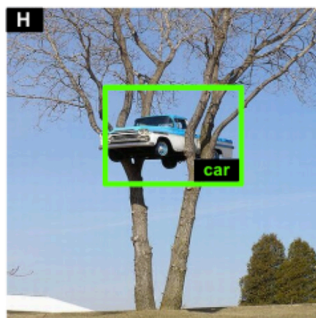
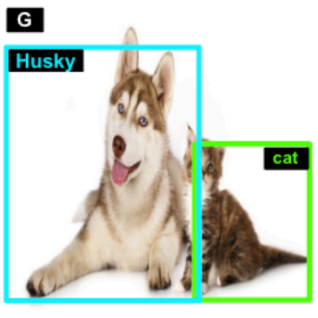
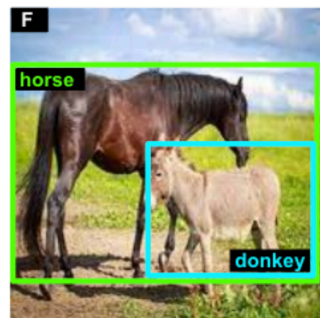
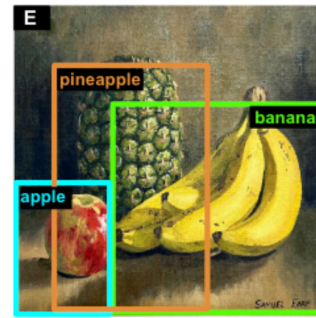
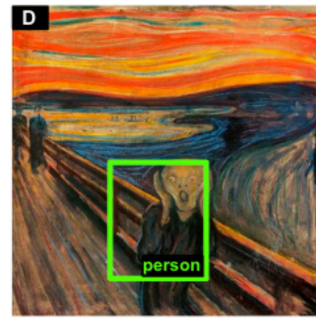
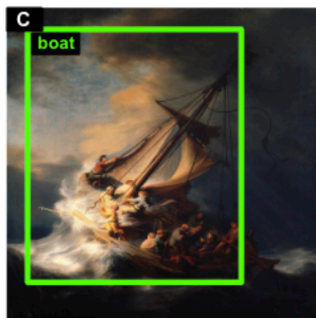
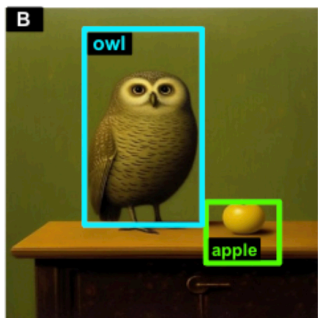
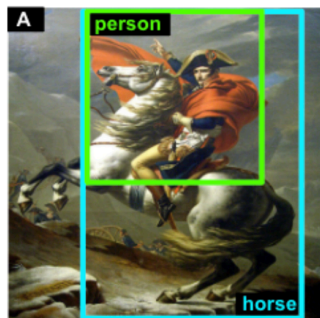
PIN = MLP(pos_encoding)
```

Just 10 LoC!

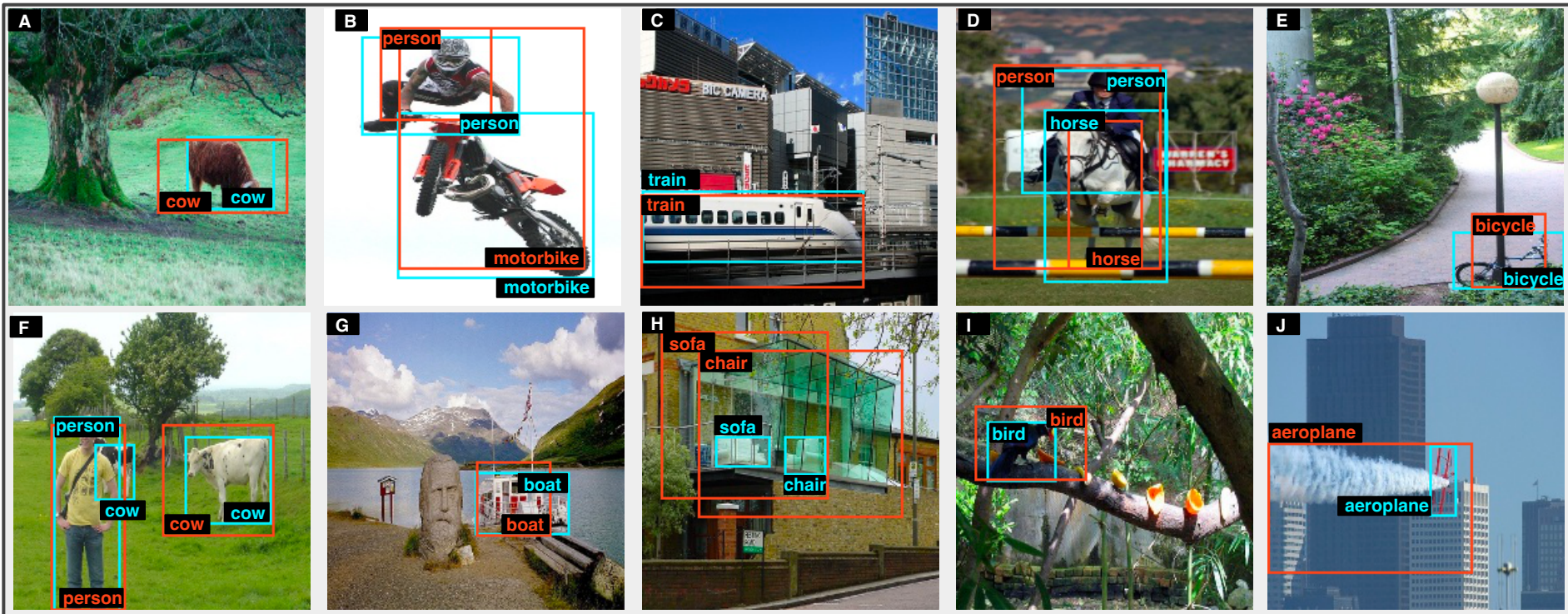
Inference with PIN



Results (zero-shot)





Results PVOC (zero-shot)



Few-shot learning doesn't work

Method	PVOC _{≤3 Objects}			COCO _{≤3 Objects}			
	mIoU	mIoU _M	mIoU _L	mIoU	mIoU _M	mIoU _L	
<i>Baselines</i>							
raw	0	0	0	0	0	0	
random	0.22±0.04	0.10±0.02	0.33±0.06	0.12±0.04	0.07±0.02	0.22±0.08	
2 context	0.19±0.11	0.08±0.05	0.30±0.18	0.10±0.08	0.06±0.04	0.18±0.16	
5 context	0.19±0.09	0.07±0.04	0.31±0.15	0.10±0.08	0.06±0.04	0.20±0.16	
10 context	0.20±0.11	0.06±0.03	0.32±0.18	0.09±0.07	0.05±0.04	0.17±0.14	
OpenFlamingo [4]	<i>Prompt-learning</i>						
	CoOp on ϕ_V	0.28	0.11	0.43	0.22	0.10	0.39
	VPT on F	0.32	0.14	0.50	0.25	0.12	0.46
	VPT on ϕ_V	0.42	0.21	0.61	0.33	0.22	0.57
	LoRA on ϕ_V	0.44	0.26	0.62	0.33	0.23	0.58
	🔒 PIN (ours)	0.45	0.27	0.62	0.35	0.26	0.59
BLIP-2 [31]	<i>Prompt-learning</i>						
	VPT on F	0.37	0.16	0.56	0.29	0.15	0.53
	VPT on ϕ_V	0.31	0.13	0.47	0.26	0.11	0.46
	🔒 PIN (ours)	0.44	0.24	0.63	0.34	0.22	0.60

PIN enables localisation

Method	PVOC _{≤3 Objects}			COCO _{≤3 Objects}				
	mIoU	mIoU _M	mIoU _L	mIoU	mIoU _M	mIoU _L		
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PIN outperforms other PEFT methods

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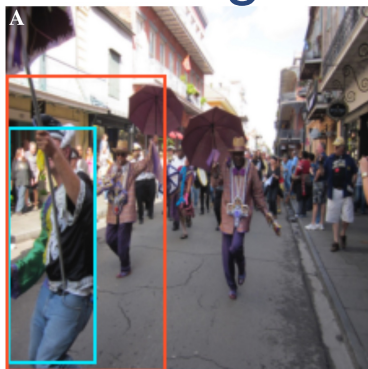
PIN works on other VLMs too

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OpenFlamingo [4]

BLIP-2 [31]

With slight modification, can work on RefCOCO.



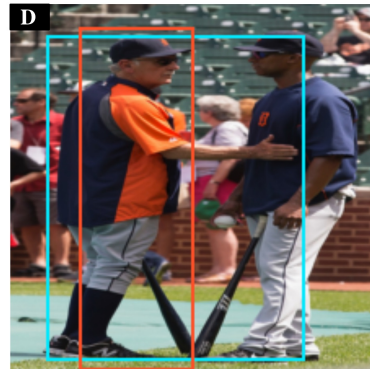
“Left black shirt”



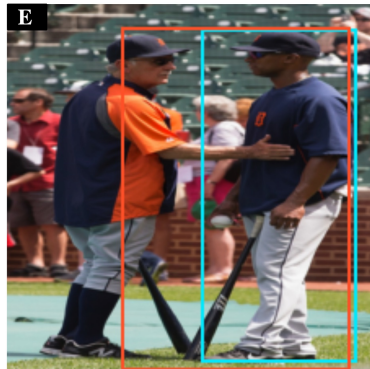
“Old lady in between the players”



“A guy in red on left”



“Guy in orange”



“Right player”



“Top left apron strings”



“Pizza squares left”



“Pizza right front piece in middle”



“A man black”



“A right person”

 Predictions

 Ground Truth

Thank you!